

Introduction to time-series commands in Stata

May 11th, 2023



Topics

Part I: Univariate time-series analysis

- Working with dates in Stata
- Declaring time-series data with **tsset**
- Plotting with **tsline**
- Testing parameter stability with **estat cusum**
- Smoothing with **tssmooth**
- Testing for unit roots with **dfuller**
- Difference and lag operators
- Visualizing autocorrelation with **ac** and **pac**
- Box-Jenkins models with **arima**
- Heteroskedasticity models with **arch**
- Forecasting with **predict**

Part II: Multivariate time-series analysis

- Business calendars with **bcal**
- Vector autoregression with **var** and **svar**
- Impulse-response functions with **irf**

Part I. Univariate time-series analysis

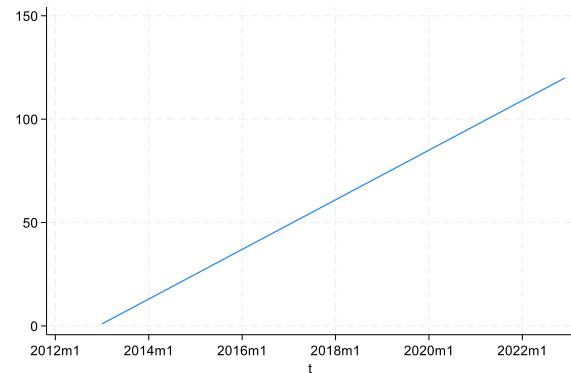
Components of a time series

$$y_t = \text{trend}_t + \text{seasonality}_t + \text{residual}_t$$

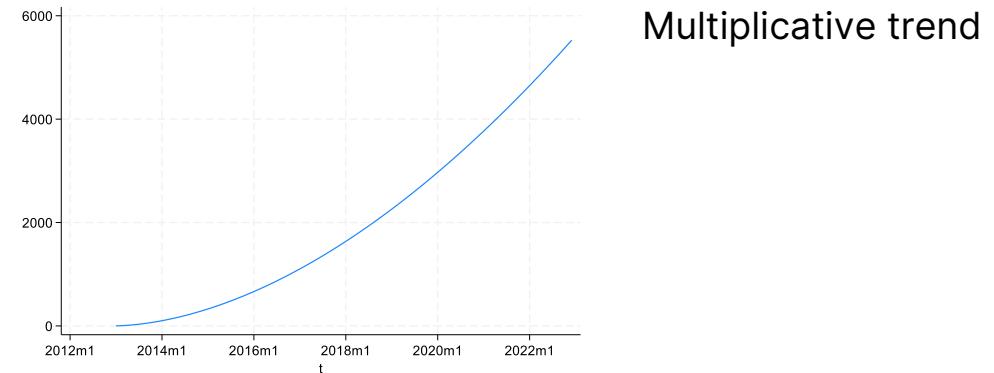
or

$$x_t = \text{trend}_t \times \text{seasonality}_t \times \text{residual}_t$$

Components of a time series

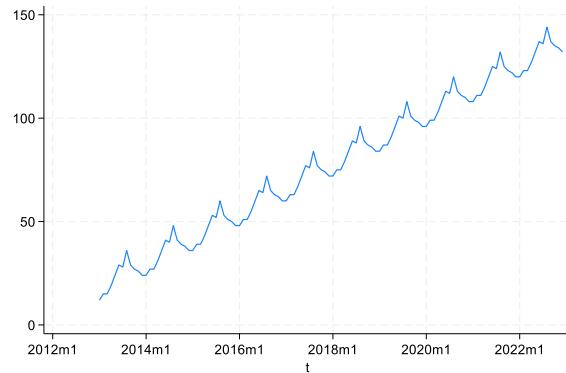


Additive trend



Multiplicative trend

Components of a time series

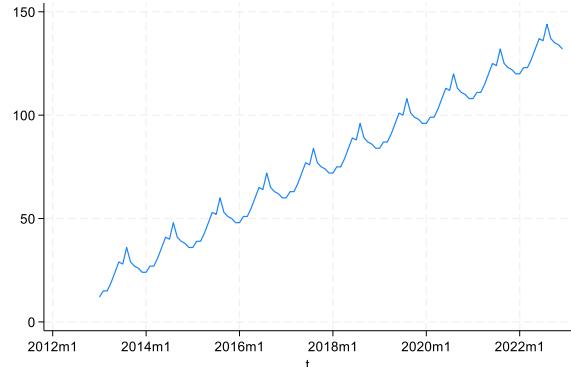


Additive trend
Additive seasonality



Multiplicative trend
Additive seasonality

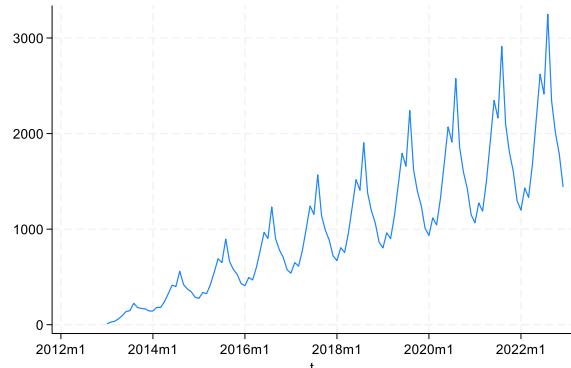
Components of a time series



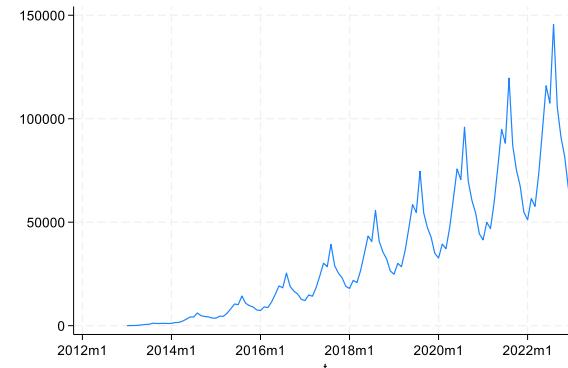
Additive trend
Additive seasonality



Multiplicative trend
Additive seasonality

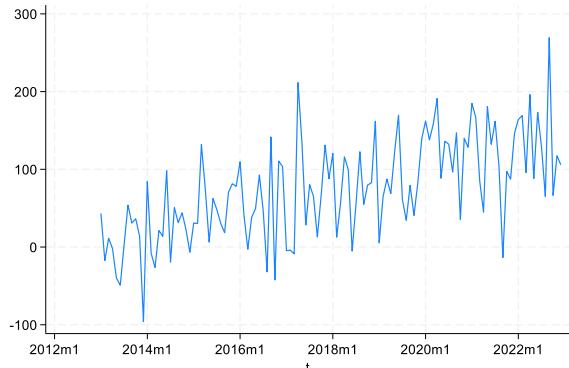


Additive trend
Multiplicative seasonality

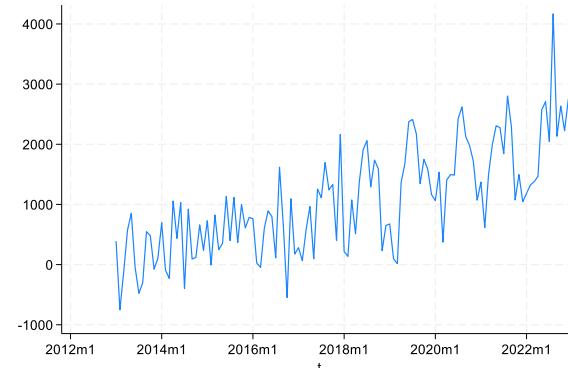


Multiplicative trend
Multiplicative seasonality

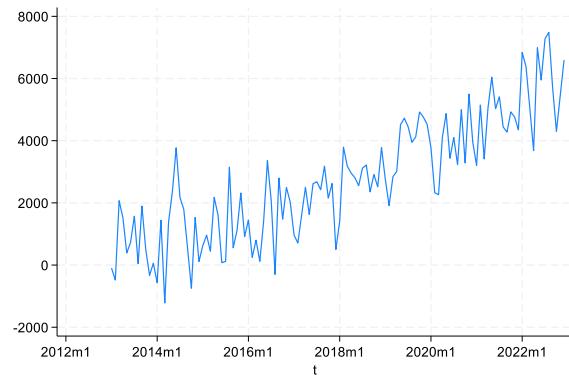
Components of a time series



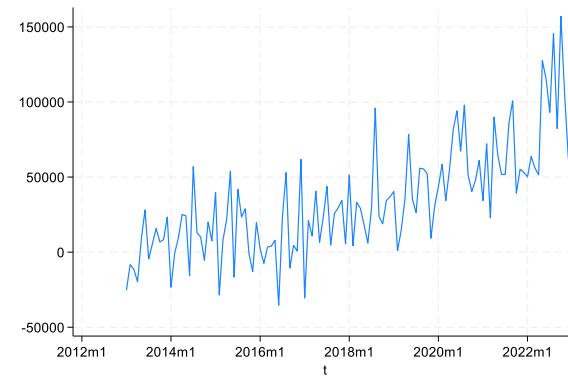
Additive trend
Additive seasonality
+ random noise



Multiplicative trend
Additive seasonality
+ random noise



Additive trend
Multiplicative seasonality
+ random noise



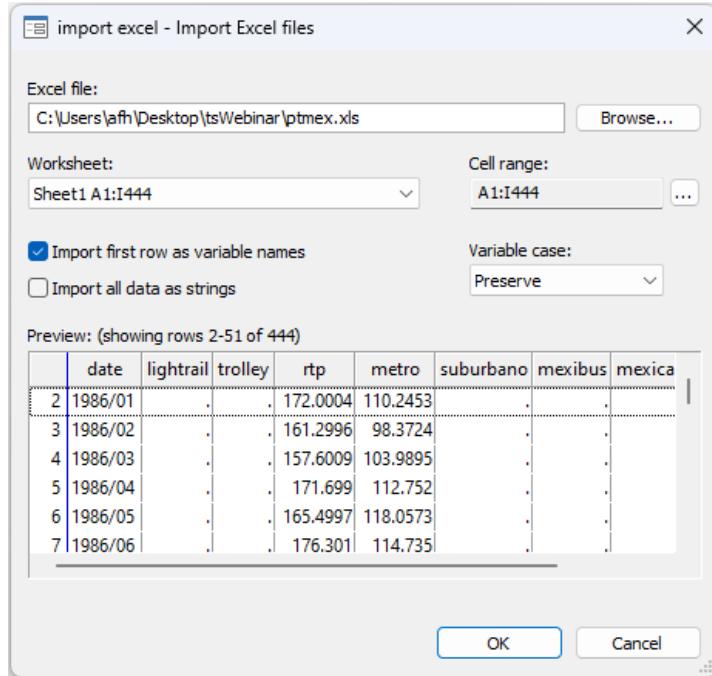
Multiplicative trend
Multiplicative seasonality
+ random noise

Public transport dataset

The screenshot shows an Excel spreadsheet with the following data:

| | date | light rail | trolley | rtp | metro | suburbano | mexibus | mexicable | metrobus | |
|-----|---------|------------|---------|-------|-------|-----------|---------|-----------|----------|--|
| 426 | 2021/05 | 1380.32 | 4173.66 | 7.73 | 62.69 | 2442785 | 5523689 | 360402 | 21008.83 | |
| 427 | 2021/06 | 1413.82 | 4456.61 | 8.24 | 63.41 | 2563421 | 5810086 | 340452 | 22154.52 | |
| 428 | 2021/07 | 1410.66 | 4841.11 | 8.53 | 69.82 | 2638193 | 6026416 | 299639 | 23177.76 | |
| 429 | 2021/08 | 1466.71 | 4551.72 | 8.65 | 67.96 | 2524601 | 5852850 | 265798 | 22484.00 | |
| 430 | 2021/09 | 1489.30 | 4632.95 | 9.45 | 70.15 | 2613918 | 5783206 | 330462 | 23432.81 | |
| 431 | 2021/10 | 1690.71 | 5200.02 | 9.62 | 78.12 | 2971497 | 6619966 | 342153 | 27111.71 | |
| 432 | 2021/11 | 1676.71 | 5189.34 | 9.00 | 78.48 | 3006178 | 6865752 | 336224 | 27032.63 | |
| 433 | 2021/12 | 1712.02 | 5117.35 | 9.54 | 84.15 | 3279013 | 7308528 | 380067 | 27514.61 | |
| 434 | 2022/01 | 1325.62 | 4308.90 | 7.65 | 70.56 | 2641487 | 6499498 | 326531 | 23643.54 | |
| 435 | 2022/02 | 1618.27 | 4491.57 | 8.24 | 72.05 | 2703405 | 6682803 | 313530 | 24694.94 | |
| 436 | 2022/03 | 2075.21 | 5311.14 | 10.34 | 88.36 | 3426554 | 8103872 | 364829 | 30270.99 | |
| 437 | 2022/04 | 1868.77 | 5071.28 | 8.48 | 82.90 | 3176214 | 7828000 | 333856 | 28239.31 | |
| 438 | 2022/05 | 2119.46 | 5731.16 | 9.98 | 91.25 | 3624145 | 8781436 | 366944 | 31750.69 | |
| 439 | 2022/06 | 2009.37 | 5595.05 | 11.14 | 88.42 | 3429680 | 8440090 | 346120 | 30637.73 | |
| 440 | 2022/07 | 1781.36 | 5848.92 | 10.34 | 80.68 | 3124001 | 7923594 | 347025 | 30743.12 | |
| 441 | 2022/08 | 2171.31 | 6560.53 | 12.69 | 90.19 | 2915970 | 9610101 | 237368 | 35001.12 | |

Importing data



- `import excel "C:\Users\afh\Desktop\tsWebinar\ptmex.xls", sheet("Sheet1") firstrow`

Date variable

The screenshot shows the Stata Data Editor (Browse) window titled "Data Editor (Browse) - [Untitled]". The main pane displays a dataset with 16 observations and 7 variables. The variables are: date, lightrail, trolley, rtp, metro, suburbano, and a unlabeled column. The "date" variable contains dates from 1986/01 to 1987/04. The "rtp" variable contains values ranging from 156.8 to 206.1996. The "metro" variable contains values ranging from 107.3016 to 110.2453. The "suburbano" variable contains values ranging from 108.9278 to 114.735. The unlabeled column contains values ranging from 109.899 to 115.9214. The "Variables" tab in the control panel lists all variables with their types and formats. The "Properties" tab shows the properties for the "date" variable, including its name, label, type, format, and value label. The "Data" tab shows the frame, filename, label, notes, variables, and observations.

| | date | lightrail | trolley | rtp | metro | suburbano |
|----|---------|-----------|---------|----------|----------|-----------|
| 1 | 1986/01 | . | . | 172.0004 | 110.2453 | . |
| 2 | 1986/02 | . | . | 161.2996 | 98.3724 | . |
| 3 | 1986/03 | . | . | 157.6009 | 103.9895 | . |
| 4 | 1986/04 | . | . | 171.699 | 112.752 | . |
| 5 | 1986/05 | . | . | 165.4997 | 118.0573 | . |
| 6 | 1986/06 | . | . | 176.301 | 114.735 | . |
| 7 | 1986/07 | . | . | 168.9004 | 124.2883 | . |
| 8 | 1986/08 | . | . | 167.0993 | 120.1064 | . |
| 9 | 1986/09 | . | . | 172.599 | 115.131 | . |
| 10 | 1986/10 | . | . | 176.3993 | 120.1281 | . |
| 11 | 1986/11 | . | . | 167.4 | 111.69 | . |
| 12 | 1986/12 | . | . | 206.1996 | 108.9278 | . |
| 13 | 1987/01 | . | . | 170.2923 | 115.9214 | . |
| 14 | 1987/02 | . | . | 156.8 | 107.3016 | . |
| 15 | 1987/03 | . | . | 177.0007 | 121.8114 | . |
| 16 | 1987/04 | . | . | 173.499 | 109.899 | . |

Variables

| Name | Label | Type | Format | Value Label |
|-----------|------------------------------|--------|--------|-------------|
| date | date | str7 | %9s | |
| lightrail | Light Rail passengers (t...) | double | %10.0g | |
| trolley | Trolleybus passengers (t...) | double | %10.0g | |
| rtp | RTP passengers (millions) | double | %10.0g | |
| metro | Metro passengers (milli...) | double | %10.0g | |
| suburbano | Suburbano passengers | long | %10.0g | |
| mexibus | Mexibus passengers | long | %10.0g | |
| mexicable | Mexicable passengers | long | %10.0g | |
| metrobus | Metrobus passengers (t...) | double | %10.0g | |

Properties

Variables

| Name | Label | Type | Format | Value Label |
|-------------|-------|------|--------|-------------|
| Name | date | | | |
| Label | date | | | |
| Type | str7 | | | |
| Format | %9s | | | |
| Value label | | | | |
| Notes | | | | |

Data

| Frame | default |
|--------------|---------|
| Filename | |
| Label | |
| Notes | |
| Variables | 9 |
| Observations | 443 |

Ready Length: 7 Vars: 9 Order: Dataset Obs: 443 Filter: Off Mode: Browse CAP NUM

Date variable format

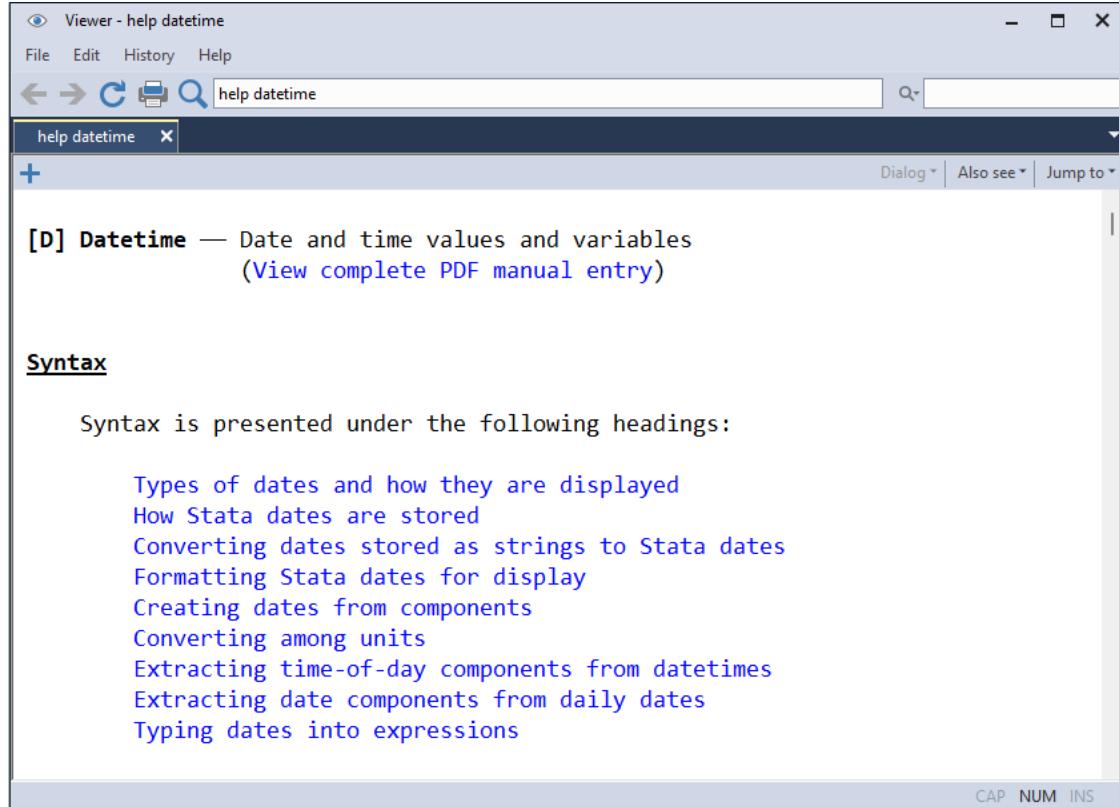
| | date | t |
|----|---------|-----|
| 1 | 1986/01 | 312 |
| 2 | 1986/02 | 313 |
| 3 | 1986/03 | 314 |
| 4 | 1986/04 | 315 |
| 5 | 1986/05 | 316 |
| 6 | 1986/06 | 317 |
| 7 | 1986/07 | 318 |
| 8 | 1986/08 | 319 |
| 9 | 1986/09 | 320 |
| 10 | 1986/10 | 321 |



| | date | t |
|----|---------|---------|
| 1 | 1986/01 | 1986m1 |
| 2 | 1986/02 | 1986m2 |
| 3 | 1986/03 | 1986m3 |
| 4 | 1986/04 | 1986m4 |
| 5 | 1986/05 | 1986m5 |
| 6 | 1986/06 | 1986m6 |
| 7 | 1986/07 | 1986m7 |
| 8 | 1986/08 | 1986m8 |
| 9 | 1986/09 | 1986m9 |
| 10 | 1986/10 | 1986m10 |

- generate t = monthly(date, "YM")
- format t %tm

Date variables help



. help datetime

Declaring time-series data

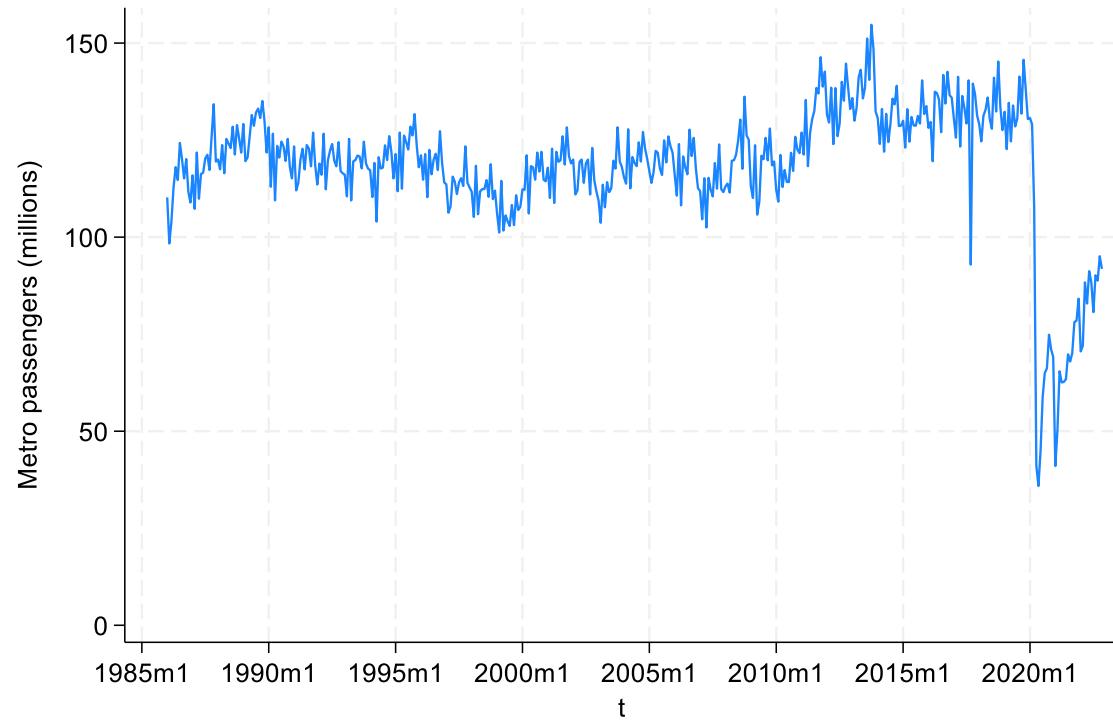
```
. tsset t
```

```
Time variable: t, 1986m1 to 2022m11  
Delta: 1 month
```

Metro

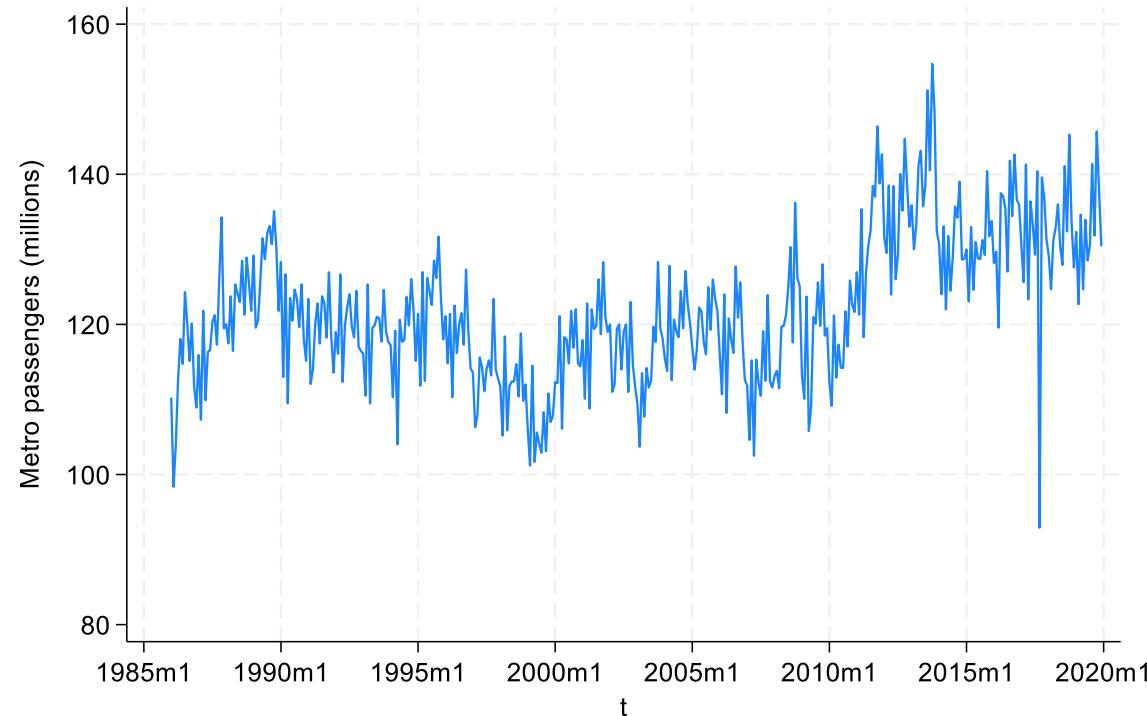


Metro: Time-series line plot



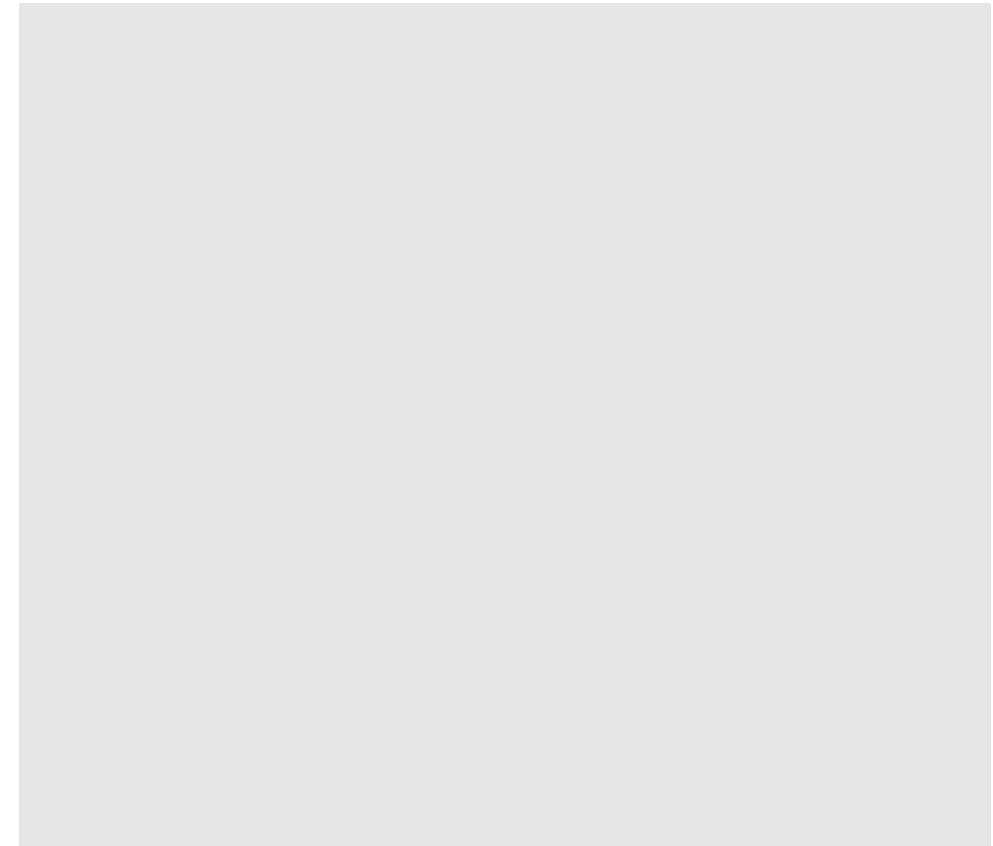
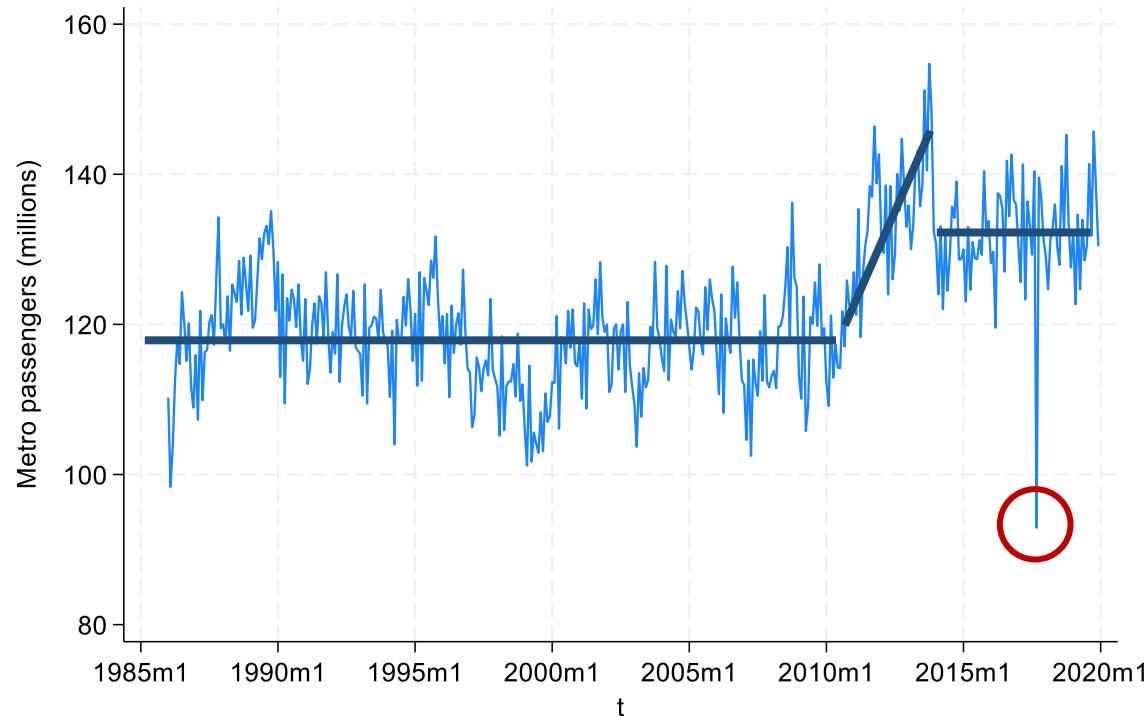
```
. tsline metro
```

Metro: Removing the pandemic



```
. keep if tin(1986m1, 2019m12)  
. tsline metro
```

Metro: First impression

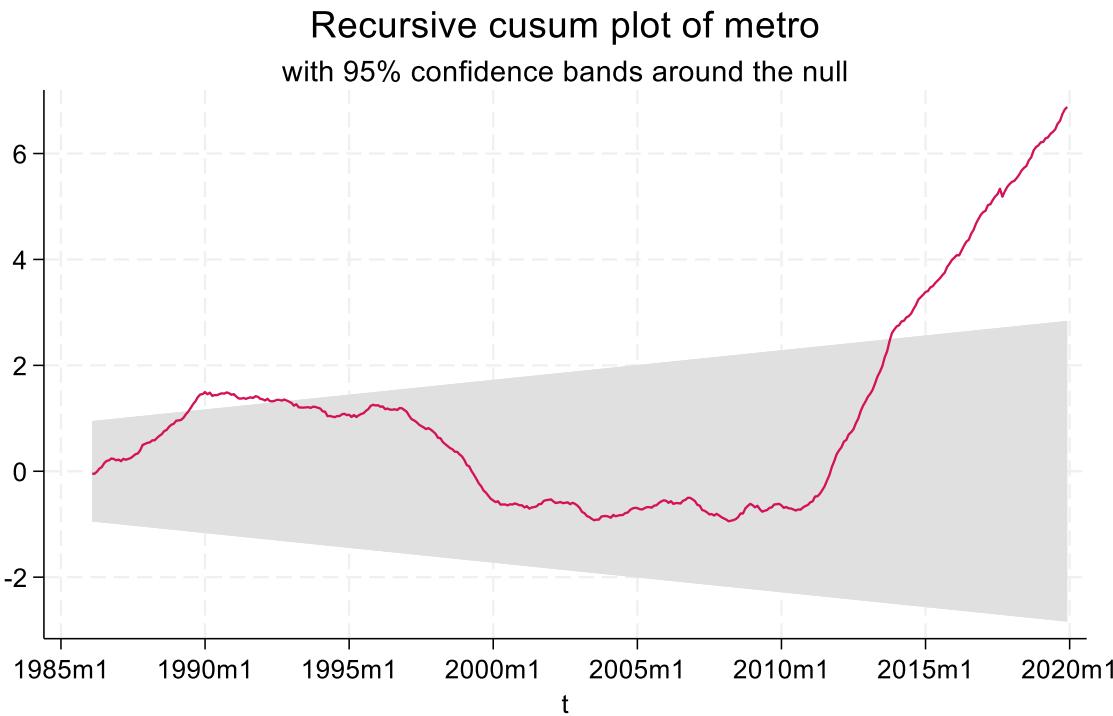


Metro: Parameter stability

| Source | SS | df | MS | Number of obs | = | 408 |
|----------|-------------|-----------|------------|---------------|----------------------|----------|
| Model | 0 | 0 | . | F(0, 407) | = | 0.00 |
| Residual | 38300.6572 | 407 | 94.1048088 | Prob > F | = | . |
| Total | 38300.6572 | 407 | 94.1048088 | R-squared | = | 0.0000 |
| | | | | Adj R-squared | = | 0.0000 |
| | | | | Root MSE | = | 9.7008 |
| metro | Coefficient | Std. err. | t | P> t | [95% conf. interval] | |
| _cons | 121.8943 | .4802593 | 253.81 | 0.000 | 120.9502 | 122.8384 |

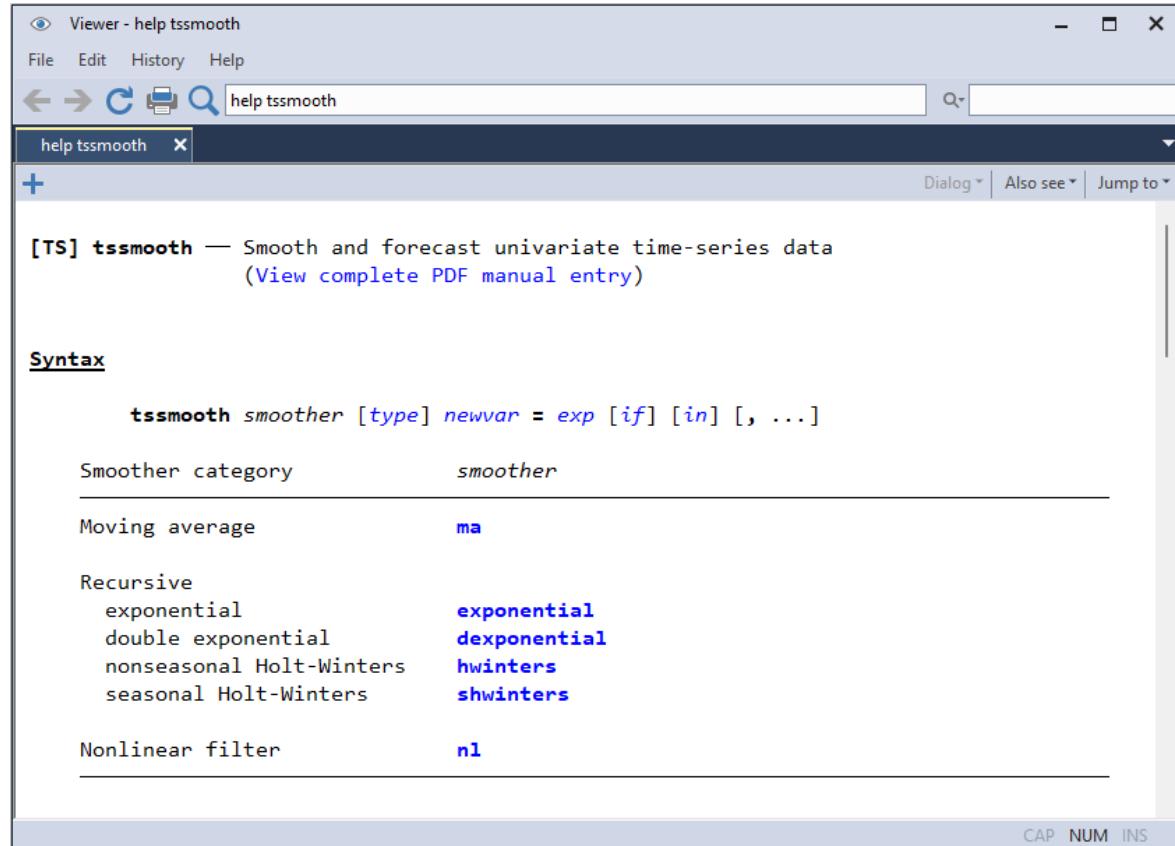
. regress metro

Metro: Parameter stability



```
. estat sbcusum
```

Smoothers in Stata

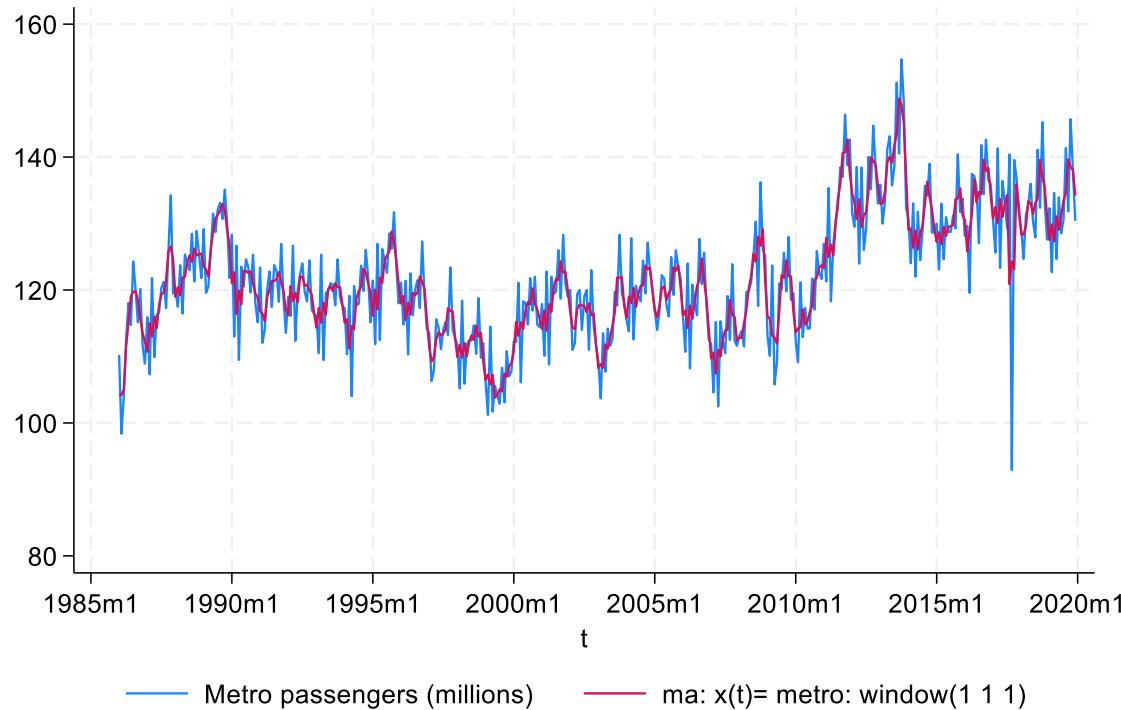


The screenshot shows the Stata Help Viewer window titled "Viewer - help tssmooth". The search bar at the top contains "help tssmooth". The main content area displays the [TS] tssmooth command, which is used for smoothing and forecasting univariate time-series data. It includes a link to the complete PDF manual entry. Below the command is a section titled "Syntax" with the command syntax: `tssmooth smoother [type] newvar = exp [if] [in] [, ...]`. A table follows, mapping smoother categories to their respective commands:

| Smoother category | smoother |
|--------------------------|---------------------------|
| Moving average | <code>ma</code> |
| Recursive | |
| exponential | <code>exponential</code> |
| double exponential | <code>dexponential</code> |
| nonseasonal Holt-Winters | <code>hwinters</code> |
| seasonal Holt-Winters | <code>shwinters</code> |
| Nonlinear filter | <code>n1</code> |

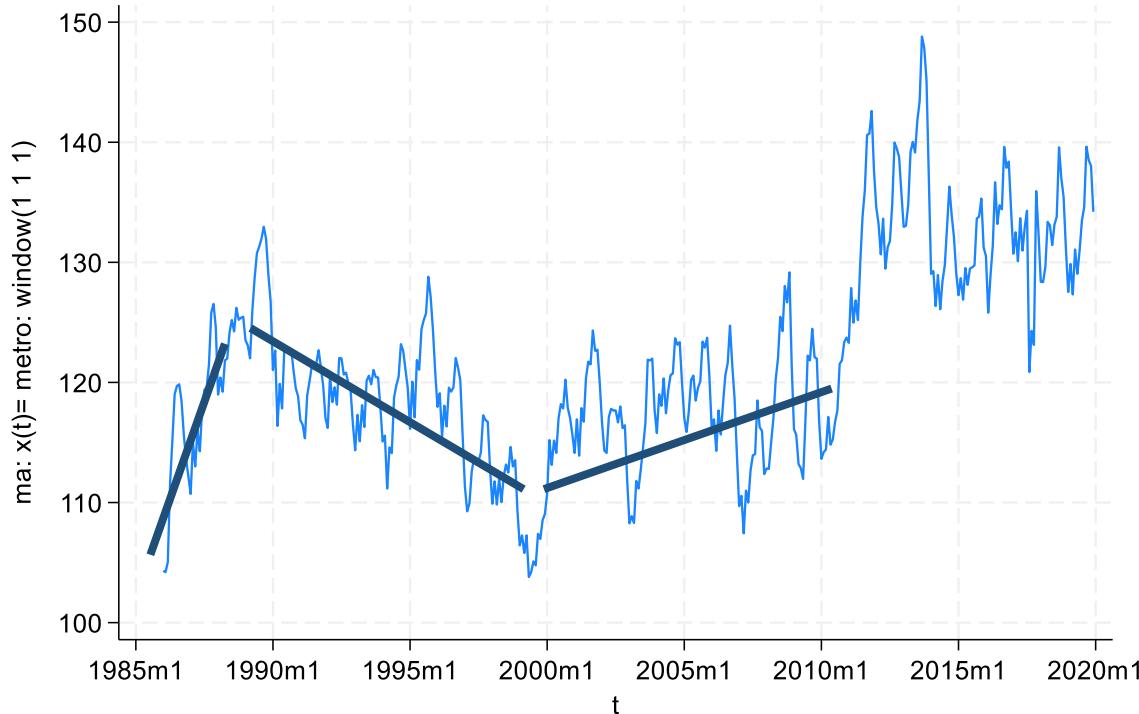
. help tssmooth

Metro: Moving average (1 1 1) smoother



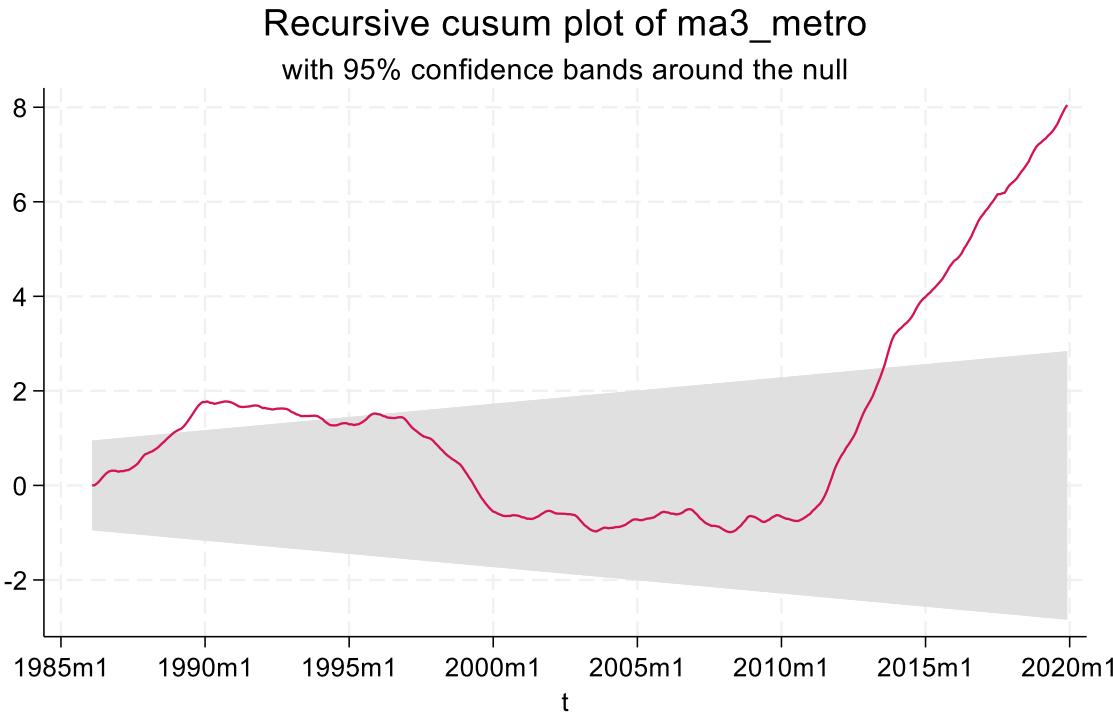
- . tssmooth ma ma3_metro = metro,
window(1 1 1)
- . tsline metro ma3_metro

Metro: Moving average (1 1 1) smoother



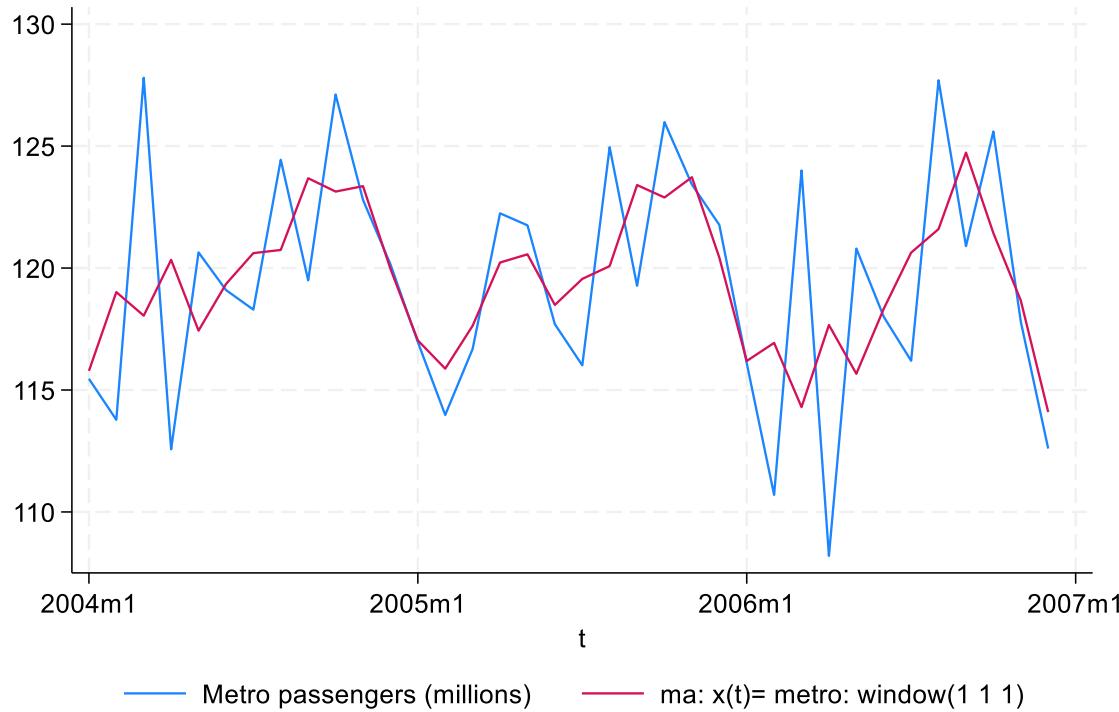
```
. tsline ma3_metro
```

Metro: Moving average (1 1 1) smoother



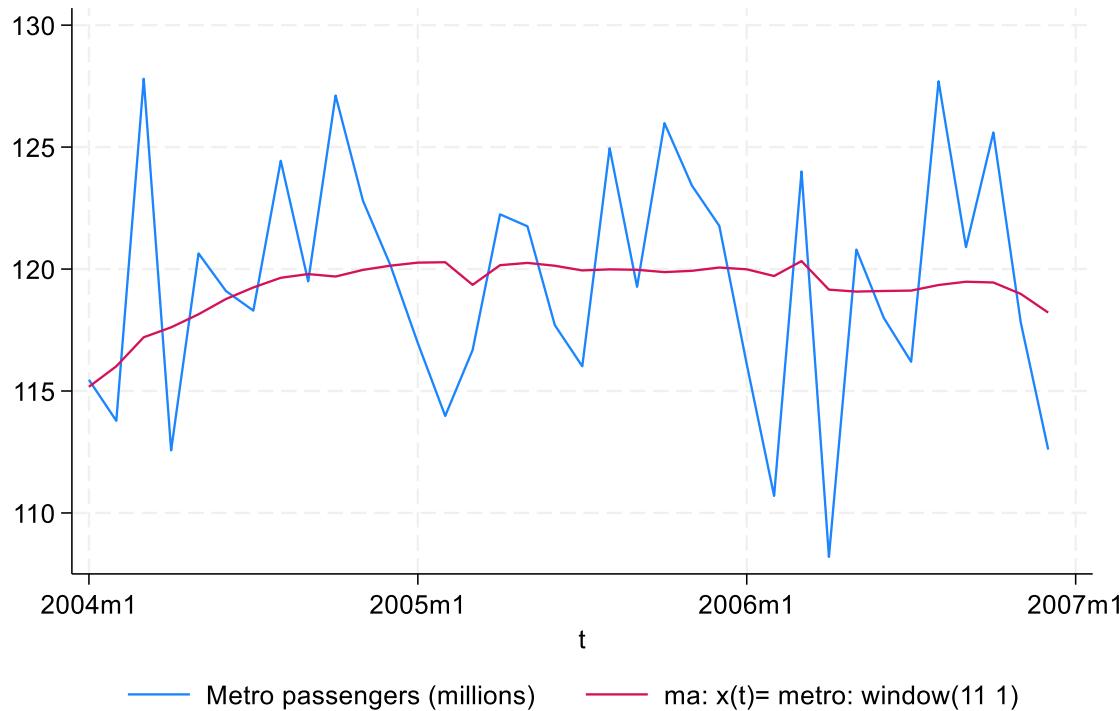
- regress ma3_metro
- estat sbcusum

Metro: Seasonality



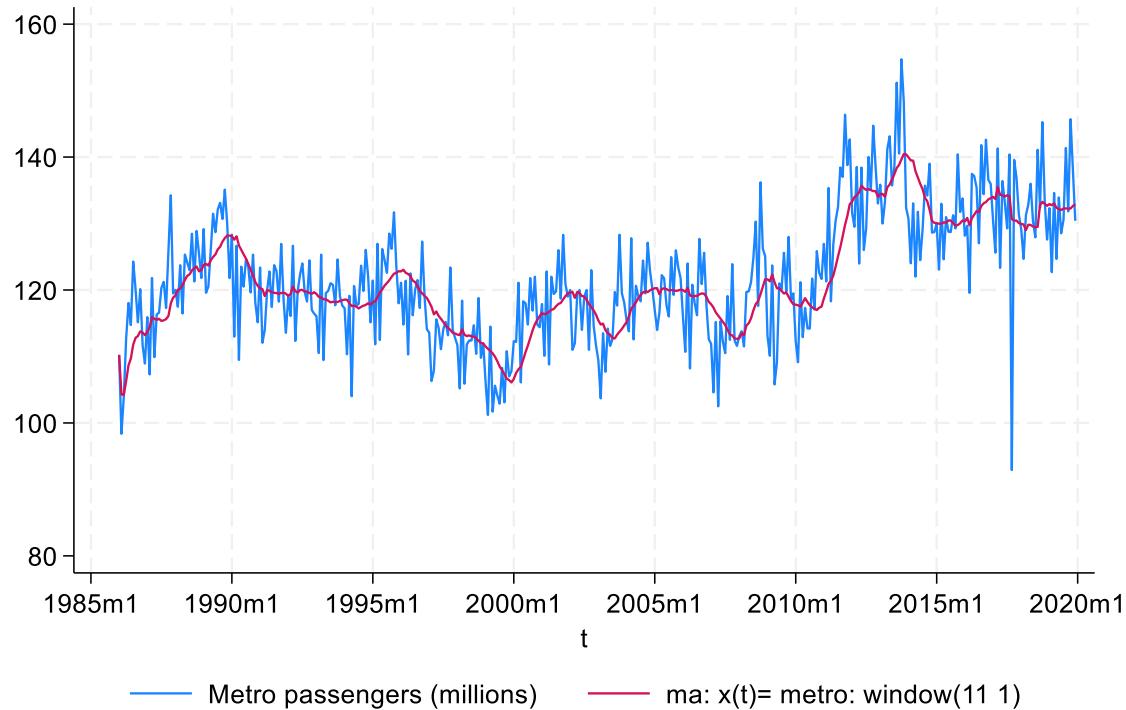
```
. tsline metro ma3_metro if tin(2004m1, 2006m12)
```

Metro: Moving average (11 1) smoother



- . tssmooth ma ma12_metro = metro,
window(11 1)
- . tsline metro ma12_metro if
tin(2004m1, 2006m12)

Metro: Moving average (11 1) smoother



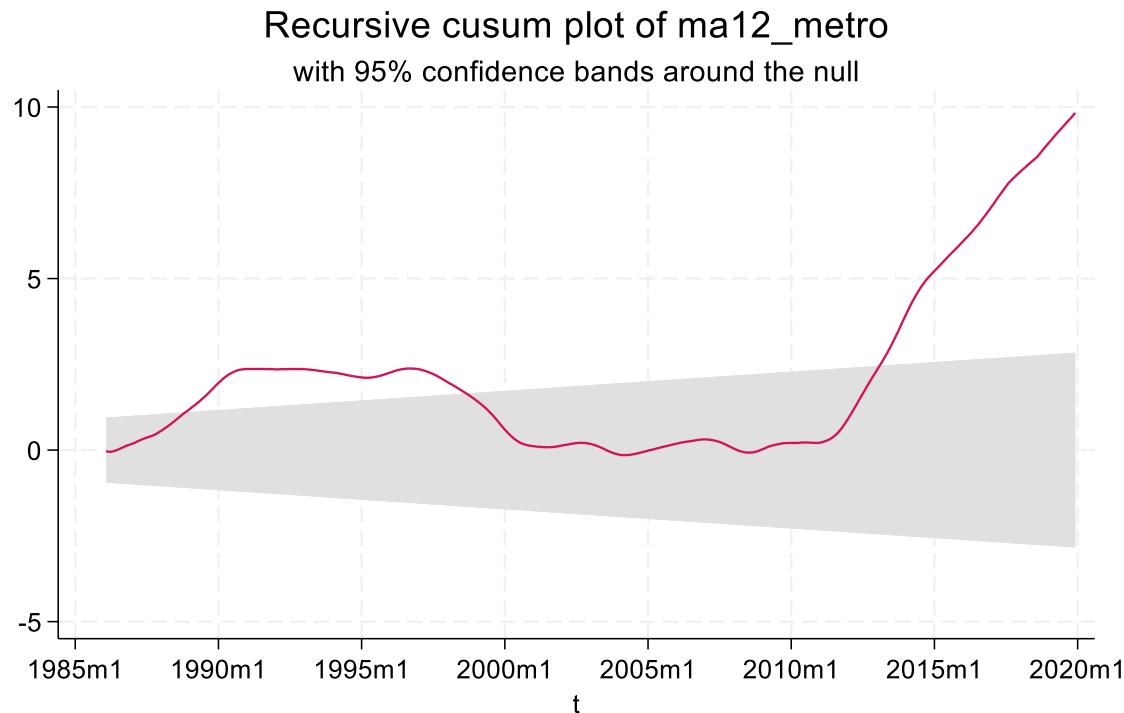
```
. tsline metro ma12_metro
```

Metro: Moving average (11 1) smoother



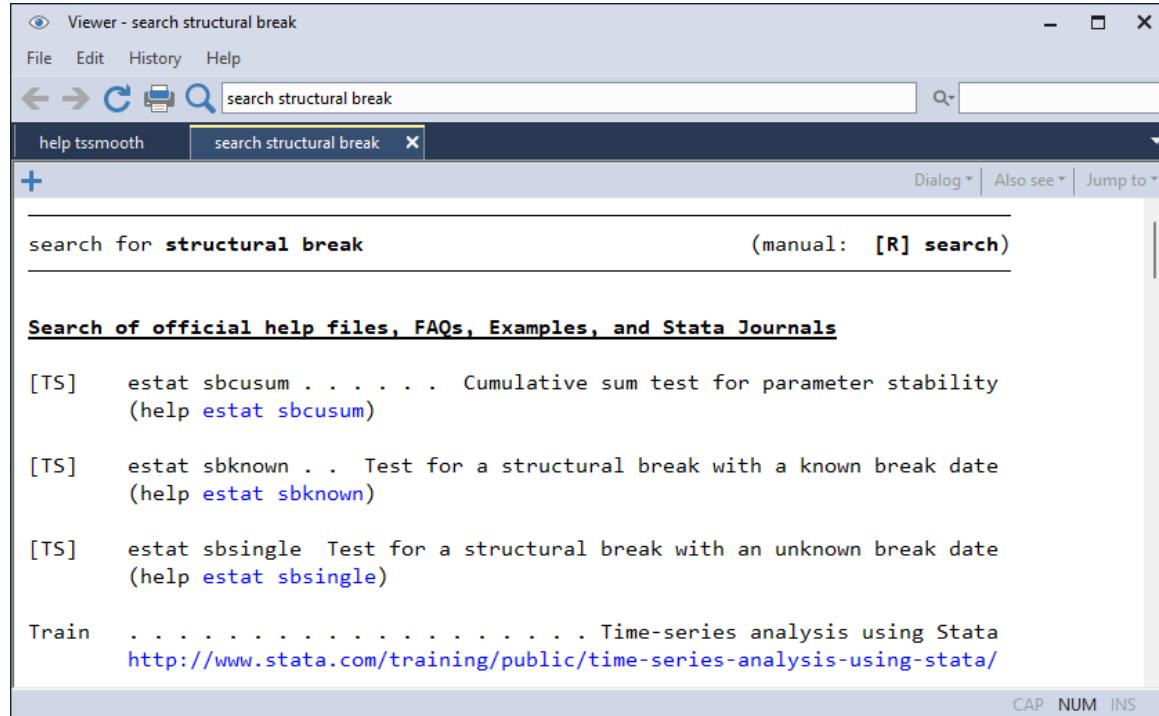
```
. tsline ma12_metro
```

Metro: Moving average (11 1) smoother



- regress ma12_metro
- estat sbcusum

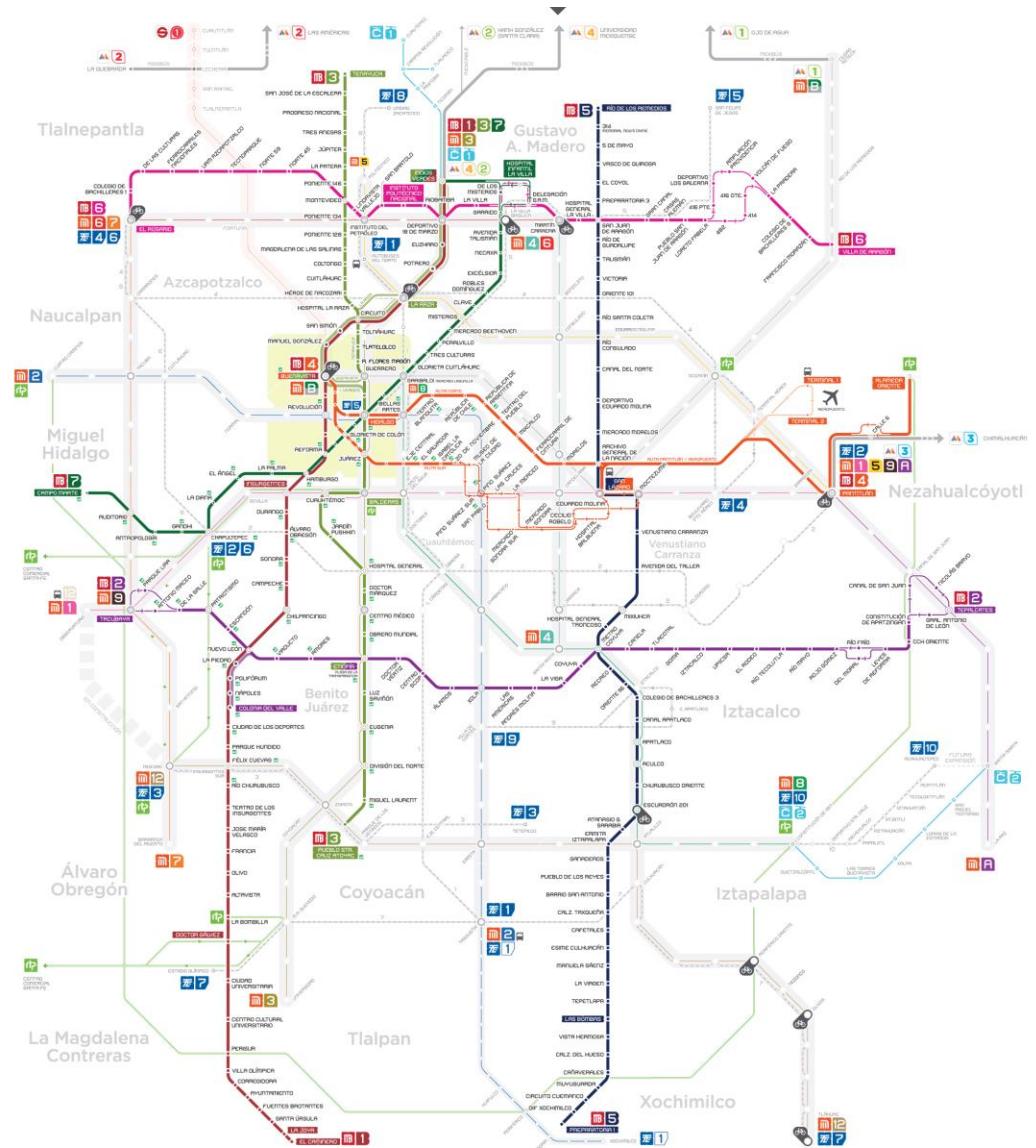
Other structural break tests



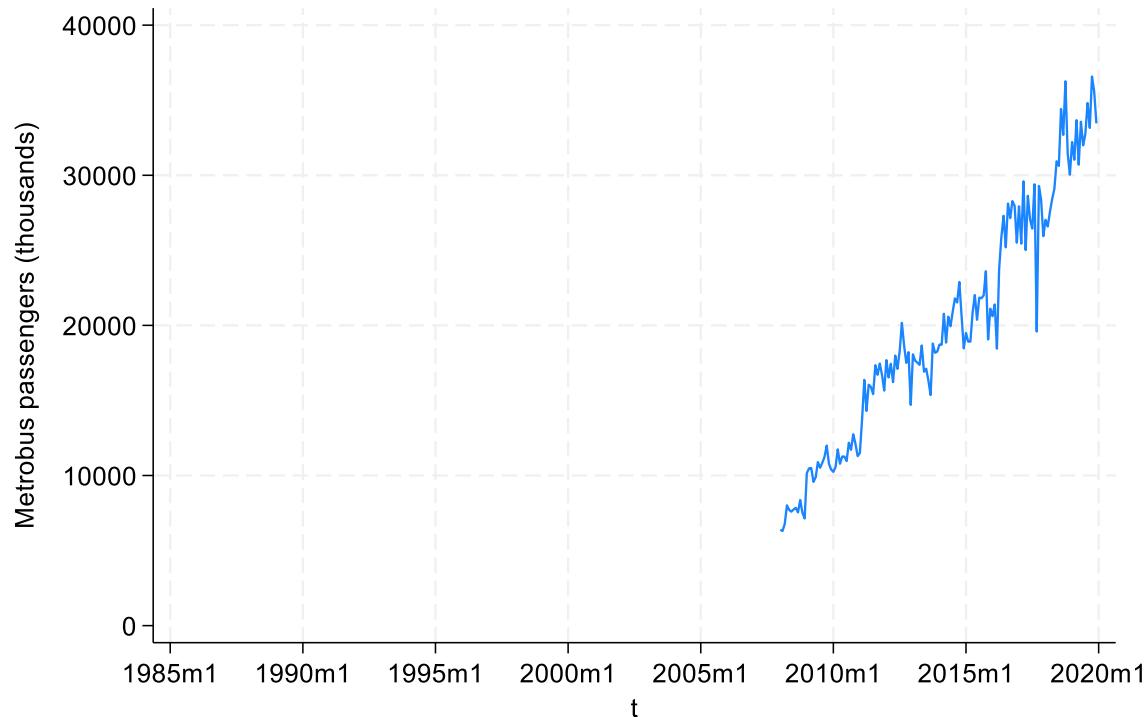
The screenshot shows the Stata Viewer window titled "Viewer - search structural break". The menu bar includes File, Edit, History, and Help. The toolbar has icons for back, forward, search, and print. A search bar contains "search structural break". Below the search bar, tabs show "help tssmooth" and "search structural break". The main pane displays search results for "structural break". It includes a header with "search for structural break" and "(manual: [R] search)". A section titled "Search of official help files, FAQs, Examples, and Stata Journals" lists commands: [TS] estat sbcusum Cumulative sum test for parameter stability (help [estat sbcusum](#)) [TS] estat sbknown . . Test for a structural break with a known break date (help [estat sbknown](#)) [TS] estat sbsingle Test for a structural break with an unknown break date (help [estat sbsingle](#)) Train Time-series analysis using Stata <http://www.stata.com/training/public/time-series-analysis-using-stata/>

- search structural break

Metrobus

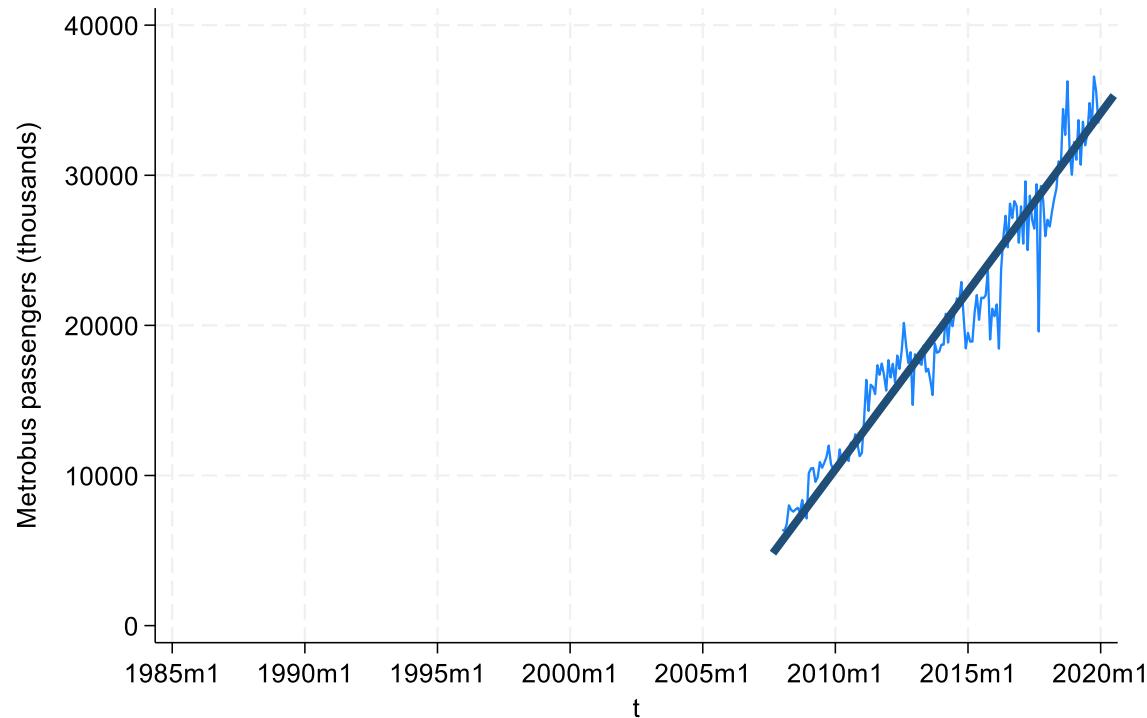


Metrobus: Time series line plot

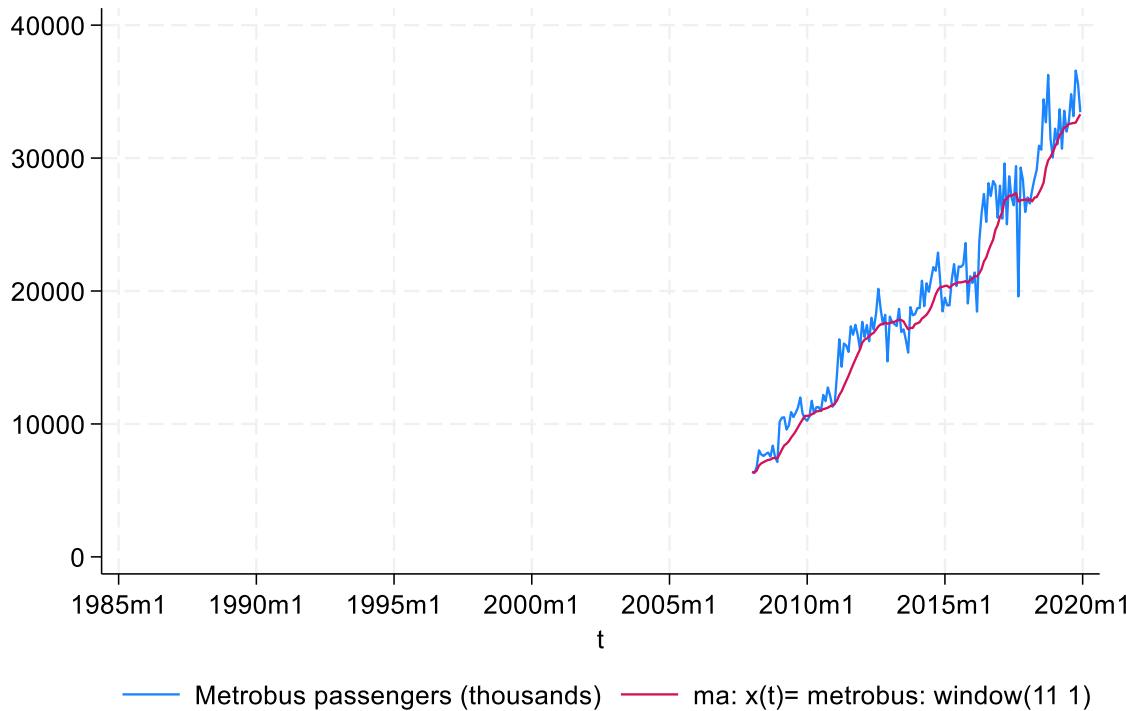


```
. tsline metrobus
```

Metrobus: Time series line plot

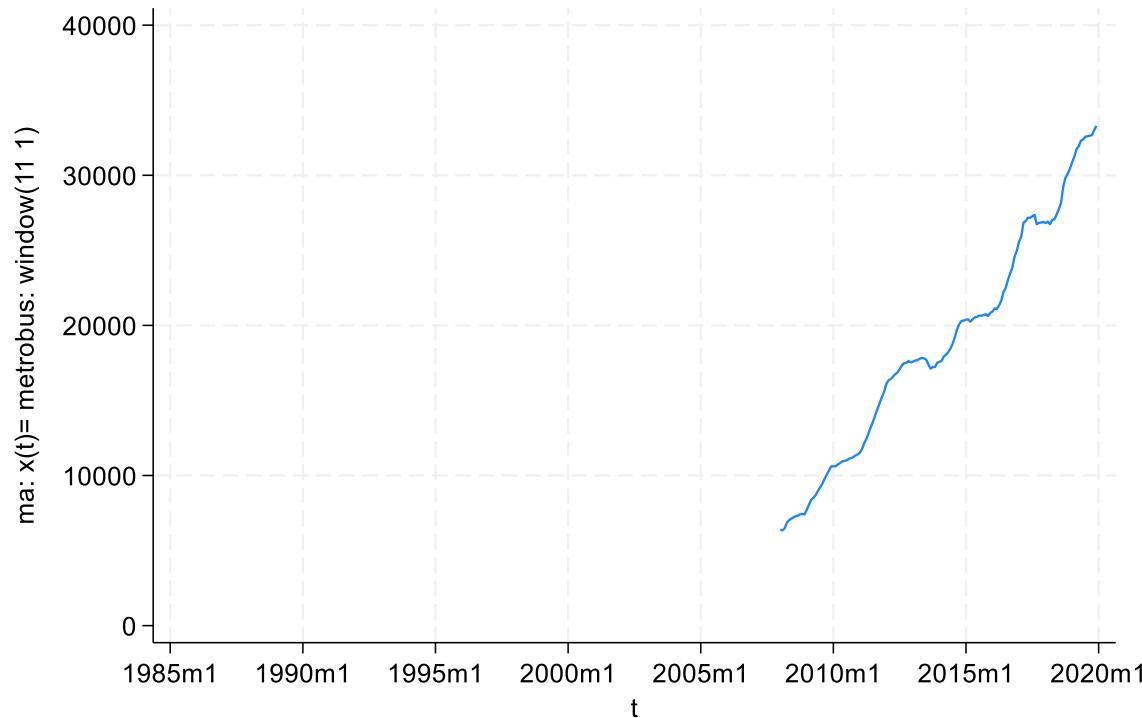


Metrobus: ma window(11 1) smoother



- `tssmooth ma ma12_metrobus = metrobus, window(11 1)`
- `tsline metrobus ma12_metrobus`

Metrobus: ma window(11 1) smoother



```
. tsline ma12_metrobus
```

Metrobus: Unit-root test

```
Dickey-Fuller test for unit root          Number of obs = 143
Variable: metrobus                      Number of lags =  0
```

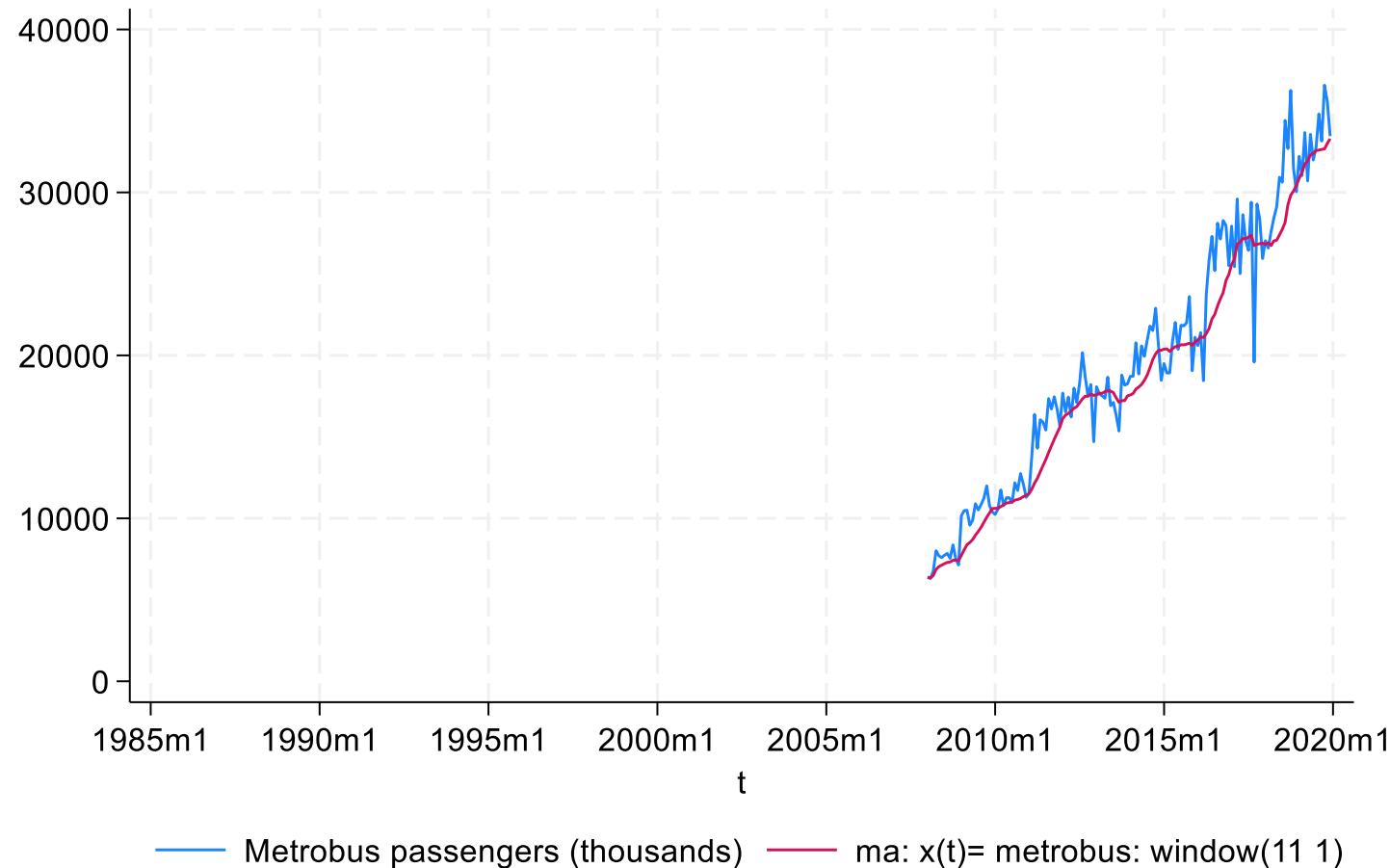
H0: Random walk without drift, d = 0

| Test statistic | Dickey-Fuller critical value | | | |
|----------------|------------------------------|--------|--------|--------|
| | 1% | 5% | 10% | |
| Z(t) | -1.576 | -3.496 | -2.887 | -2.577 |

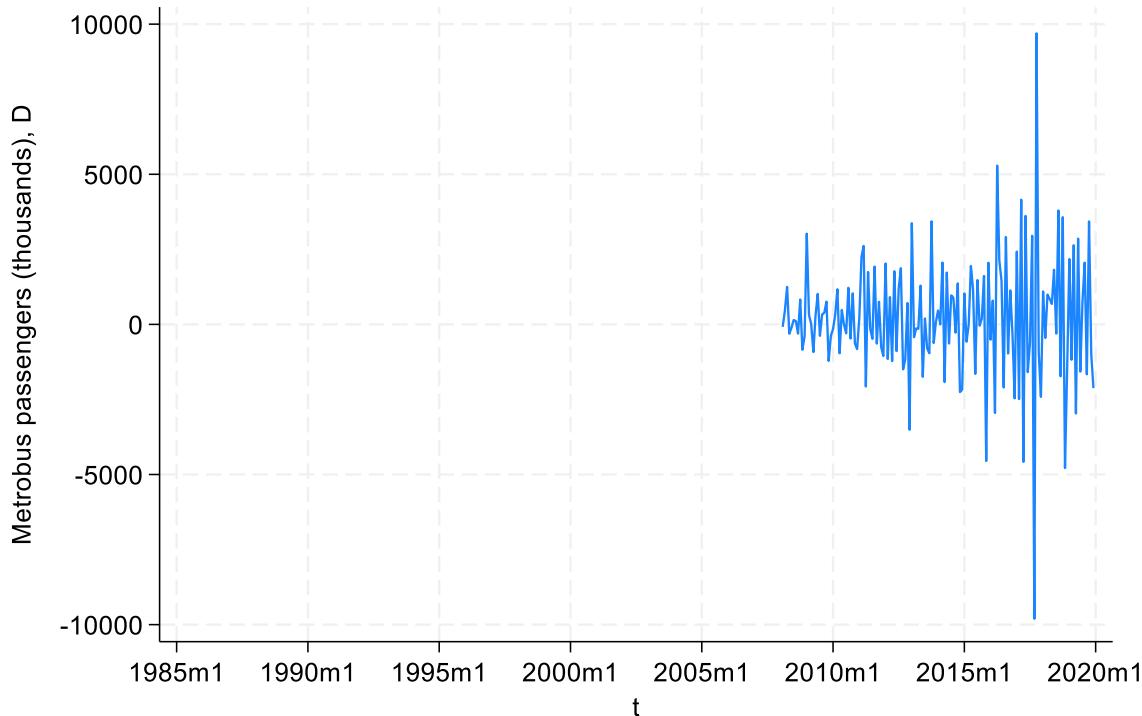
MacKinnon approximate p-value for Z(t) = 0.4956.

```
. dfuller metrobus
```

Metrobus: Unit-root test



Metrobus: First differences



```
. tsline D.metrobus
```

Aside: Difference and lag operators

Differences

D.variable
D2.variable
etc...

Lags

L.variable
L2.variable
etc...

Leads

F.variable
F2.variable
etc...

Seasonal difference

S4.variable
S12.variable

Metrobus: Unit-root test

```
Dickey-Fuller test for unit root          Number of obs = 143
Variable: metrobus                      Number of lags =  0
```

H0: Random walk with or without drift

| Test statistic | Dickey-Fuller critical value | | |
|----------------|------------------------------|--------|--------|
| | 1% | 5% | 10% |
| Z(t) | -7.560 | -4.026 | -3.444 |

MacKinnon approximate p-value for Z(t) = 0.0000.

```
. dfuller metrobus, trend
```

Metrobus: Unit-root test

Dickey-Fuller test for unit root
Variable: D.metrobus

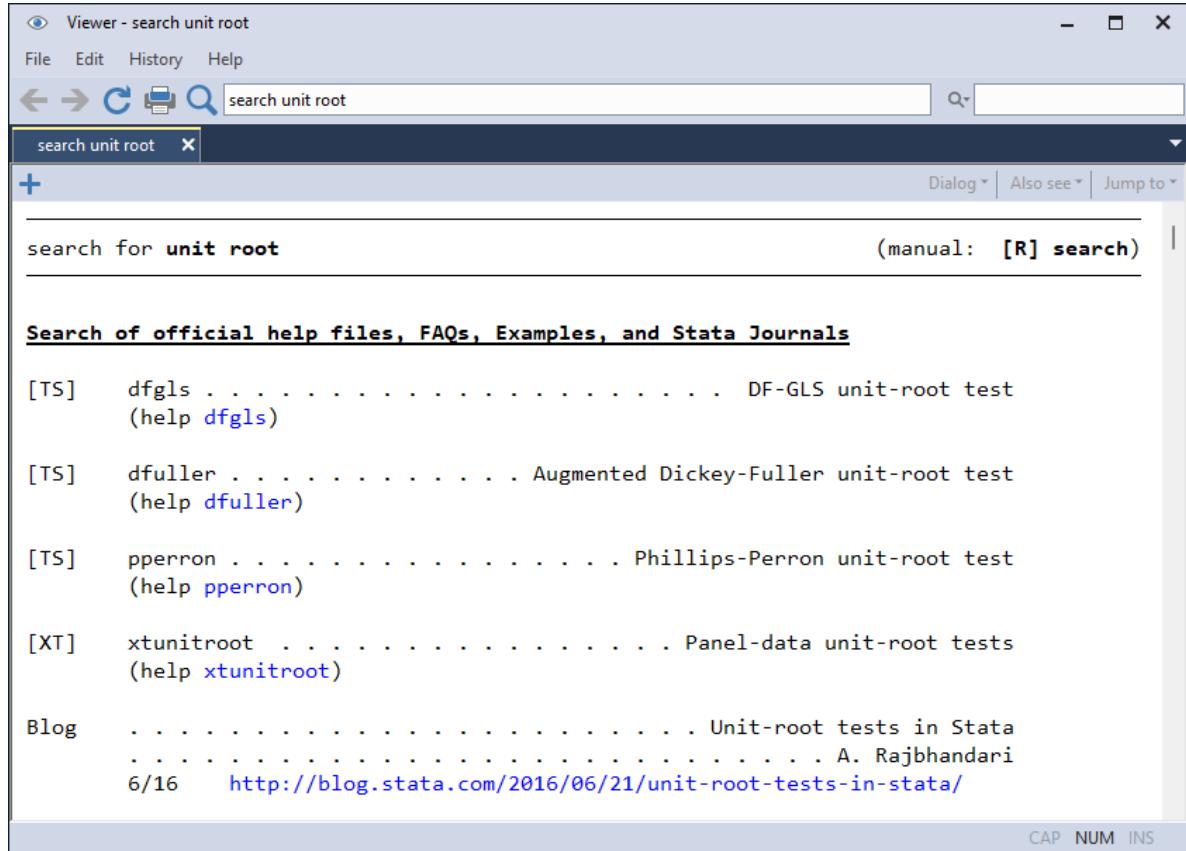
H0: Random walk without drift, d = 0

| Test statistic | Dickey-Fuller critical value | | | |
|----------------|------------------------------|--------|--------|--------|
| | 1% | 5% | 10% | |
| Z(t) | -22.508 | -3.496 | -2.887 | -2.577 |

MacKinnon approximate p-value for Z(t) = 0.0000.

```
. dfuller D.metrobus
```

Other unit-root tests



The screenshot shows the Stata Viewer window titled "Viewer - search unit root". The search bar at the top contains the text "search unit root". Below the search bar, there is a toolbar with icons for back, forward, refresh, and search. A dropdown menu is open, showing options: "Dialog", "Also see", and "Jump to". The main pane displays search results for "unit root". The results are organized into sections: "Search for unit root" and "Search of official help files, FAQs, Examples, and Stata Journals". The "Search for unit root" section lists commands: [TS] dfgls, [TS] dfuller, [TS] pperron, [XT] xtunitroot, and a Blog entry. The "Search of official help files, FAQs, Examples, and Stata Journals" section lists the same commands with their descriptions and help links. At the bottom of the viewer, there are keyboard shortcut keys: CAP, NUM, INS.

Viewer - search unit root

File Edit History Help

← → C search unit root Q

search unit root X

Dialog ▾ Also see ▾ Jump to ▾

+
search for unit root (manual: **[R] search**)

Search of official help files, FAQs, Examples, and Stata Journals

[TS] dfgls DF-GLS unit-root test
(help [dfgls](#))

[TS] dfuller Augmented Dickey-Fuller unit-root test
(help [dfuller](#))

[TS] pperron Phillips-Perron unit-root test
(help [pperron](#))

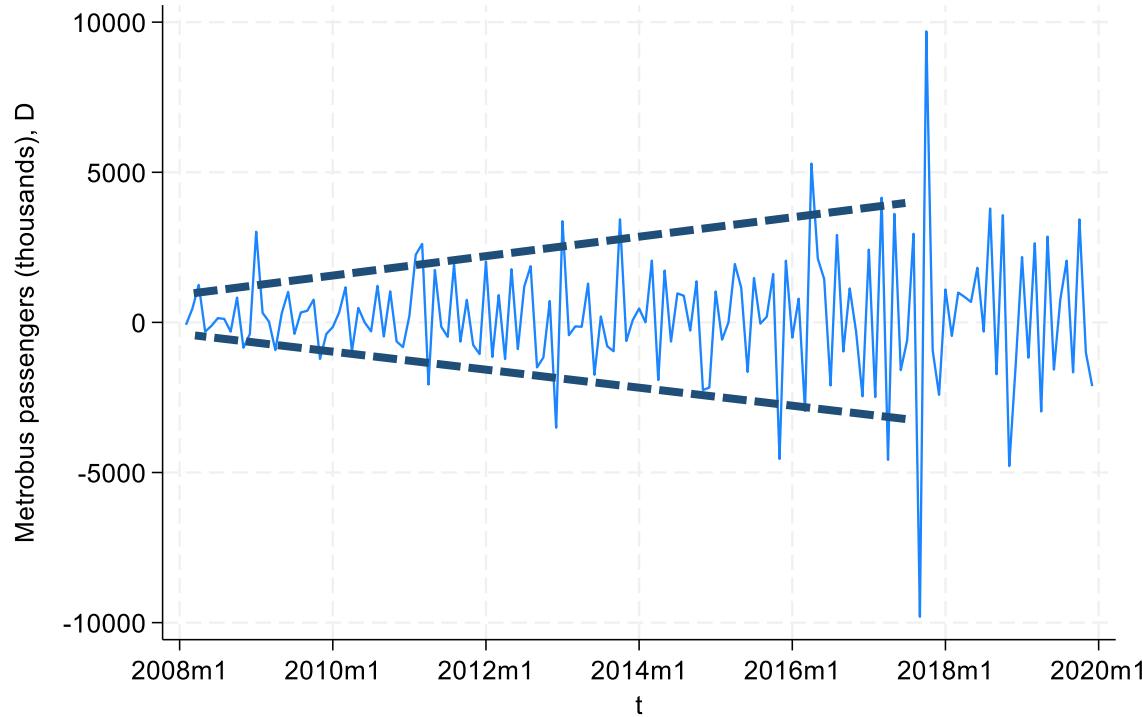
[XT] xtunitroot Panel-data unit-root tests
(help [xtunitroot](#))

Blog Unit-root tests in Stata
A. Rajbhandari
6/16 <http://blog.stata.com/2016/06/21/unit-root-tests-in-stata/>

CAP NUM INS

. search unit root

Metrobus: Constant variance?

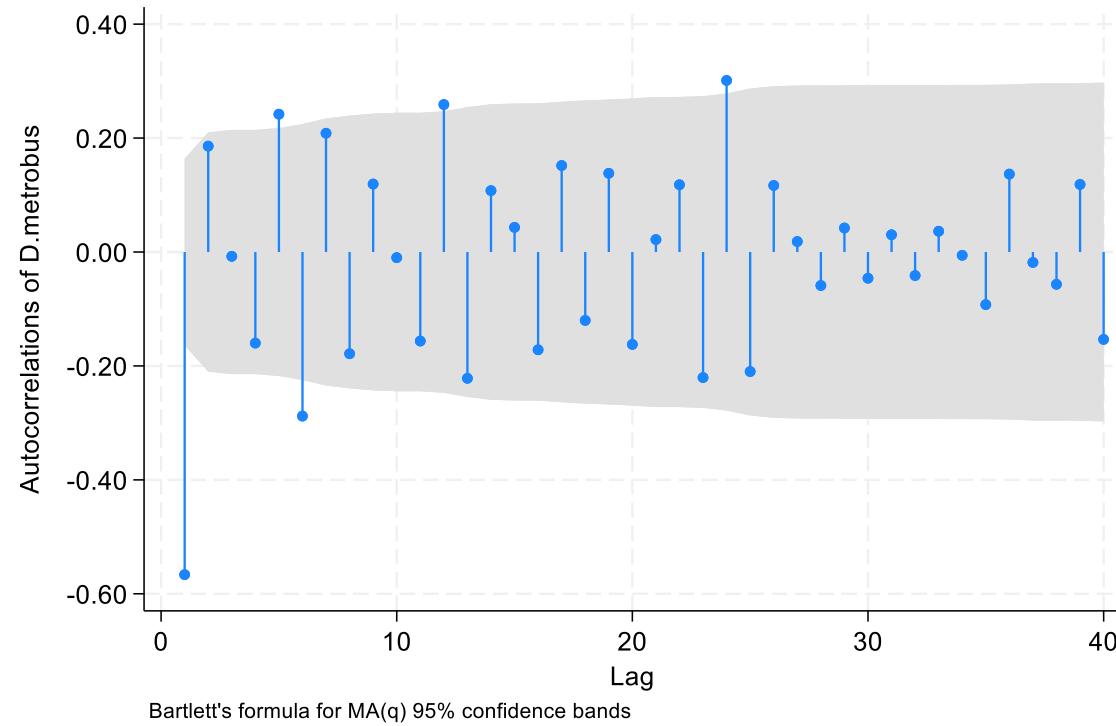


```
. tsline D.metrobus if tin(2008m1,  
2019m12)
```

Metrobus: ARIMA

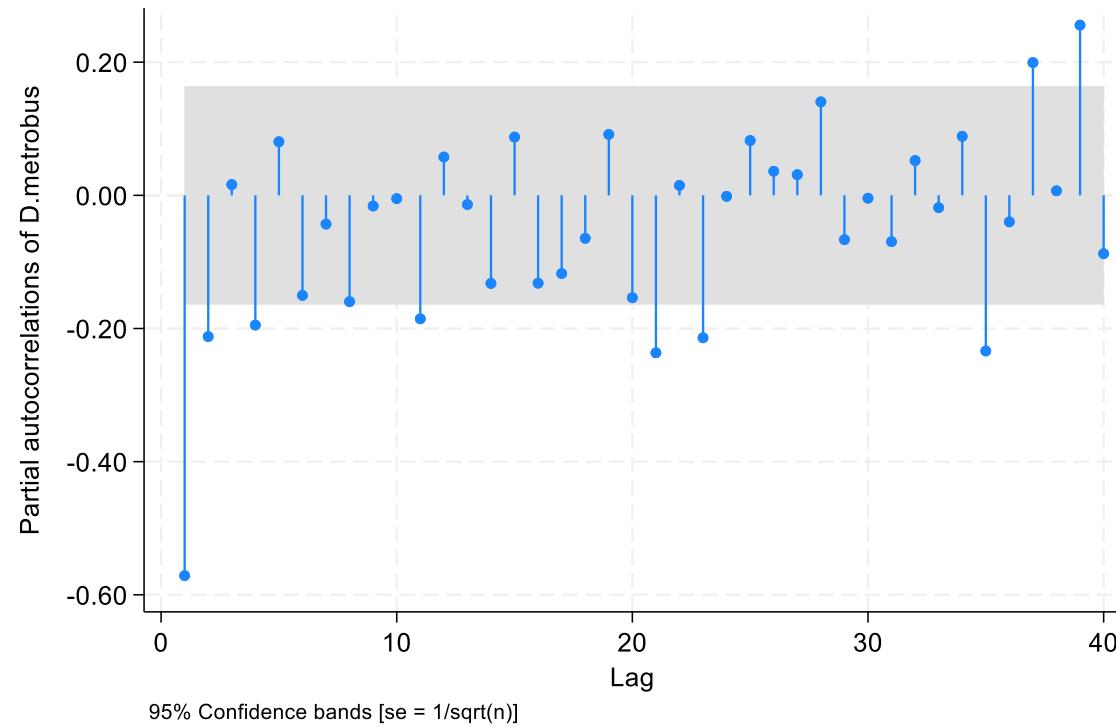
$$d.\text{metrobus}_t = \mu + \phi_1 d.\text{metrobus}_{t-1} + \cdots + \phi_p d.\text{metrobus}_{t-p} \\ + \epsilon_t + \theta_1 \epsilon_{t-1} + \cdots + \theta_q \epsilon_{t-q}$$

Autocorrelogram



• ac *D.metrobus*

Partial autocorrelogram



• pac *D.metrobus*

Model selection with arimasoc

Lag-order selection criteria

Sample: 2008m2 thru 2019m12

Number of obs = 143

| Model | LL | df | AIC | BIC | HQIC |
|-----------|-----------|----|----------|----------|----------|
| ARMA(0,0) | -1296.576 | 2 | 2597.151 | 2603.077 | 2599.559 |
| ARMA(0,1) | -1267.407 | 3 | 2540.814 | 2549.702 | 2544.426 |
| ARMA(0,2) | -1266.229 | 4 | 2540.459 | 2552.31 | 2545.274 |
| ARMA(1,0) | -1268.825 | 3 | 2543.65 | 2552.539 | 2547.262 |
| ARMA(1,1) | -1265.545 | 4 | 2539.09 | 2550.941 | 2543.906 |
| ARMA(1,2) | -1265.508 | 5 | 2541.017 | 2555.831 | 2547.037 |
| ARMA(2,0) | -1265.658 | 4 | 2539.317 | 2551.168 | 2544.133 |
| ARMA(2,1) | -1263.476 | 5 | 2536.951 | 2551.766 | 2542.971 |
| ARMA(2,2) | -1263.171 | 6 | 2538.342 | 2556.12 | 2545.566 |

Selected (max) LL: ARMA(2,2)

Selected (min) AIC: ARMA(2,1)

Selected (min) BIC: ARMA(0,1)

Selected (min) HQIC: ARMA(2,1)

. arimasoc D.metrobus

Metrobus: ARIMA(2, 1, 1)

ARIMA regression

Sample: 2008m2 thru 2019m12 Number of obs = 143
Log likelihood = -1263.476 Wald chi2(3) = 536.43
 Prob > chi2 = 0.0000

| D.metrobus | OPG | | | | | |
|------------|-------------|-----------|--------|-------|----------------------|-----------|
| | Coefficient | std. err. | z | P> z | [95% conf. interval] | |
| metrobus | | | | | | |
| _cons | 197.8784 | 87.02933 | 2.27 | 0.023 | 27.30409 | 368.4528 |
| ARMA | | | | | | |
| ar | | | | | | |
| L1. | -1.381551 | .1067587 | -12.94 | 0.000 | -1.590794 | -1.172307 |
| L2. | -.5842782 | .0561559 | -10.40 | 0.000 | -.6943418 | -.4742146 |
| ma | | | | | | |
| L1. | .7644672 | .1315618 | 5.81 | 0.000 | .5066109 | 1.022324 |
| /sigma | 1659.666 | 72.87977 | 22.77 | 0.000 | 1516.824 | 1802.508 |

Note: The test of the variance against zero is one sided, and the two-sided confidence interval is truncated at zero.

- ```
. arima metrobus, arima(2, 1, 1)
. estimates store arima21
```

## Metrobus: ARCH

$$d.metrobus_t = \mu + \phi_1 d.metrobus_{t-1} + \cdots + \phi_p d.metrobus_{t-p} \\ + \epsilon_t + \theta_1 \epsilon_{t-1} + \cdots + \theta_q \epsilon_{t-q}$$

$$\sigma_t^2 = \gamma_0 + \gamma_1 \epsilon_{t-1}^2 + \cdots + \gamma_m \epsilon_{t-m}^2$$

# Metrobus: ARCH effects test

LM test for autoregressive conditional heteroskedasticity (ARCH)

| lags( <i>p</i> ) | chi2   | df | Prob > chi2 |
|------------------|--------|----|-------------|
| 1                | 32.956 | 1  | 0.0000      |

H0: no ARCH effects      vs.    H1: ARCH(*p*) disturbance

- . quietly regress D.metrobus
- . estat archlm, lags(1)

# Metrobus: ARMA(2,1) with ARCH(1) disturbances

ARCH family regression -- ARMA disturbances

Sample: 2008m2 thru 2019m12 Number of obs = 143  
Wald chi2(3) = 182.94  
Prob > chi2 = 0.0000  
Log likelihood = -1253.196

| OPG        |             |           |          |       |                      |                     |
|------------|-------------|-----------|----------|-------|----------------------|---------------------|
|            | Coefficient | std. err. | z        | P> z  | [95% conf. interval] |                     |
| D.metrobus |             |           |          |       |                      |                     |
| metrobus   | _cons       | 146.1883  | 69.72694 | 2.10  | 0.036                | 9.525977 282.8505   |
| ARMA       |             |           |          |       |                      |                     |
|            | ar          |           |          |       |                      |                     |
|            | L1.         | -1.168511 | .4180182 | -2.80 | 0.005                | -1.987812 -.3492107 |
|            | L2.         | -.4133894 | .2131822 | -1.94 | 0.052                | -.8312189 .0044401  |
|            | ma          |           |          |       |                      |                     |
|            | L1.         | .5519442  | .4585955 | 1.20  | 0.229                | -.3468865 1.450775  |
| ARCH       |             |           |          |       |                      |                     |
|            | arch        |           |          |       |                      |                     |
|            | L1.         | .6602451  | .213515  | 3.09  | 0.002                | .2417633 1.078727   |
|            | _cons       | 1395431   | 256825.7 | 5.43  | 0.000                | 892062.1 1898800    |

```
. arch D.metrobus, ar(1 2) ma(1)
arch(1)
```

# Metrobus: AR(2) with ARCH(1) disturbances

ARCH family regression -- AR disturbances

Sample: 2008m2 thru 2019m12 Number of obs = 143  
Wald chi2(2) = 73.36  
Prob > chi2 = 0.0000  
Log likelihood = -1253.454

| OPG             |             |           |       |       |                      |           |
|-----------------|-------------|-----------|-------|-------|----------------------|-----------|
| D.metrobus      | Coefficient | std. err. | z     | P> z  | [95% conf. interval] |           |
| <b>metrobus</b> |             |           |       |       |                      |           |
| _cons           | 155.7661    | 62.14133  | 2.51  | 0.012 | 33.97133             | 277.5609  |
| ARMA            |             |           |       |       |                      |           |
| ar              |             |           |       |       |                      |           |
| L1.             | -.6555086   | .1004949  | -6.52 | 0.000 | -.852475             | -.4585421 |
| L2.             | -.1295425   | .0979355  | -1.32 | 0.186 | -.3214926            | .0624076  |
| ARCH            |             |           |       |       |                      |           |
| arch            |             |           |       |       |                      |           |
| L1.             | .703343     | .1981944  | 3.55  | 0.000 | .3148891             | 1.091797  |
| _cons           | 1362397     | 240384.3  | 5.67  | 0.000 | 891252.9             | 1833542   |

. arch D.metrobus, ar(1 2) arch(1)

# Metrobus: AR(1) with ARCH(1) disturbances

ARCH family regression -- AR disturbances

Sample: 2008m2 thru 2019m12  
Number of obs = 143  
Wald chi2(1) = 55.66  
Prob > chi2 = 0.0000  
Log likelihood = -1254.34

| OPG        |             |           |          |       |                      |                    |
|------------|-------------|-----------|----------|-------|----------------------|--------------------|
|            | Coefficient | std. err. | z        | P> z  | [95% conf. interval] |                    |
| D.metrobus |             |           |          |       |                      |                    |
| metrobus   | _cons       | 158.3452  | 70.99336 | 2.23  | 0.026                | 19.20079 297.4896  |
| ARMA       |             |           |          |       |                      |                    |
|            | ar          |           |          |       |                      |                    |
|            | L1.         | -.5558053 | .0744961 | -7.46 | 0.000                | -.701815 -.4097956 |
| ARCH       |             |           |          |       |                      |                    |
|            | arch        |           |          |       |                      |                    |
|            | L1.         | .6144126  | .1385206 | 4.44  | 0.000                | .3429173 .8859079  |
|            | _cons       | 1454262   | 221030.7 | 6.58  | 0.000                | 1021050 1887474    |

- . arch D.metrobus, ar(1) arch(1)
- . estimates store arch1

# Metrobus: Model comparison

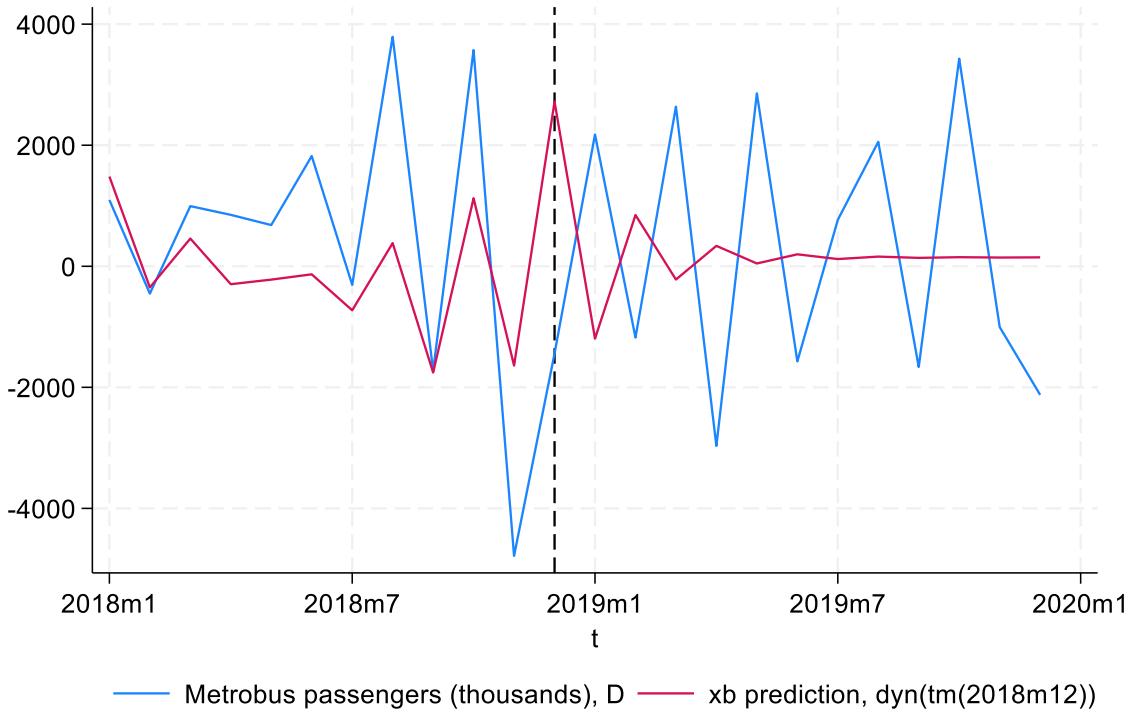
Akaike's information criterion and Bayesian information criterion

| Model   | N   | ll(null) | ll(model) | df | AIC      | BIC      |
|---------|-----|----------|-----------|----|----------|----------|
| arima21 | 143 | .        | -1263.476 | 5  | 2536.951 | 2551.766 |
| arch1   | 143 | .        | -1254.34  | 4  | 2516.68  | 2528.531 |

Note: BIC uses N = number of observations. See [\[R\] BIC note](#).

```
. estimates stats arima21 arch1
```

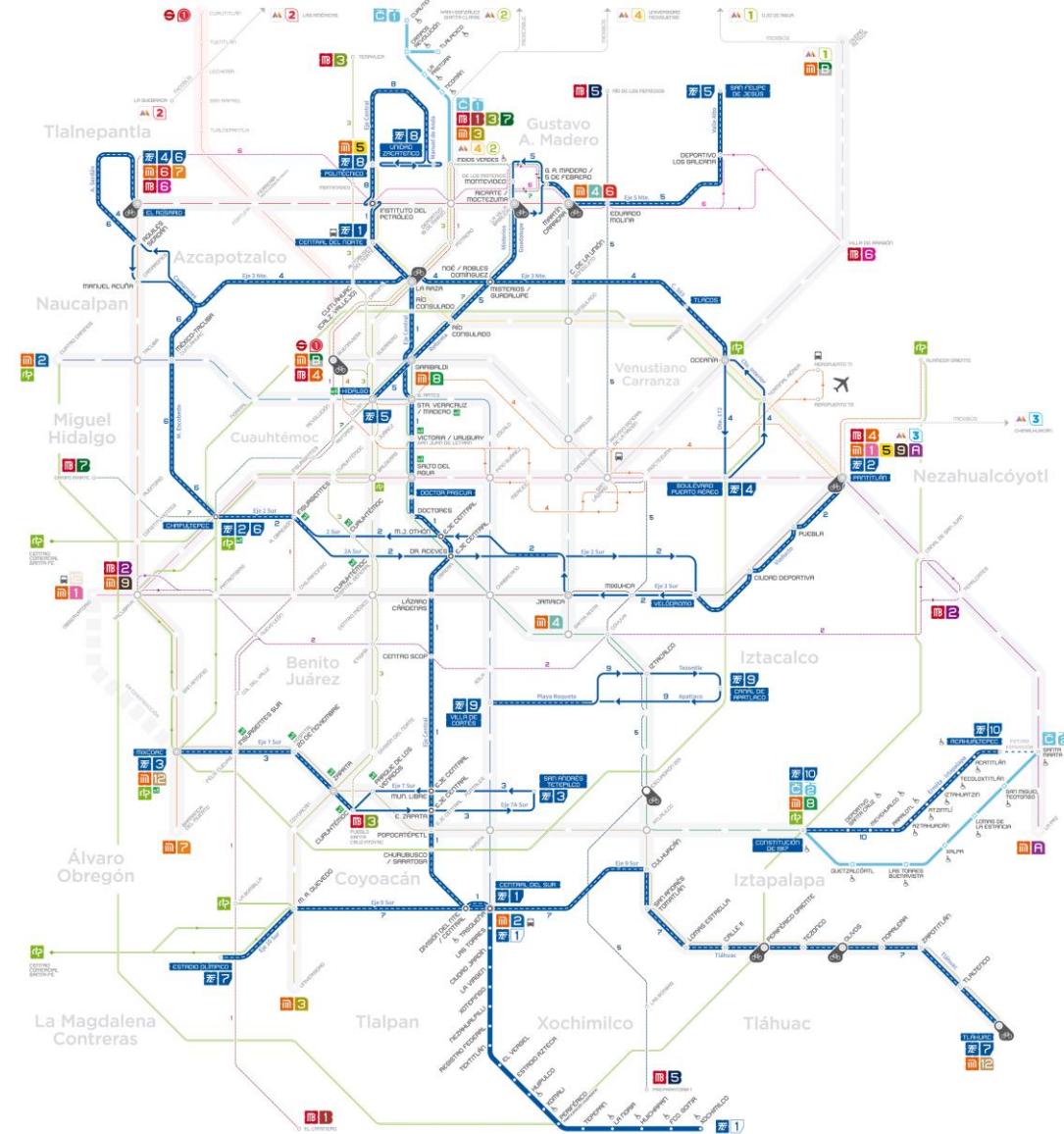
# Metrobus: 2019 forecast



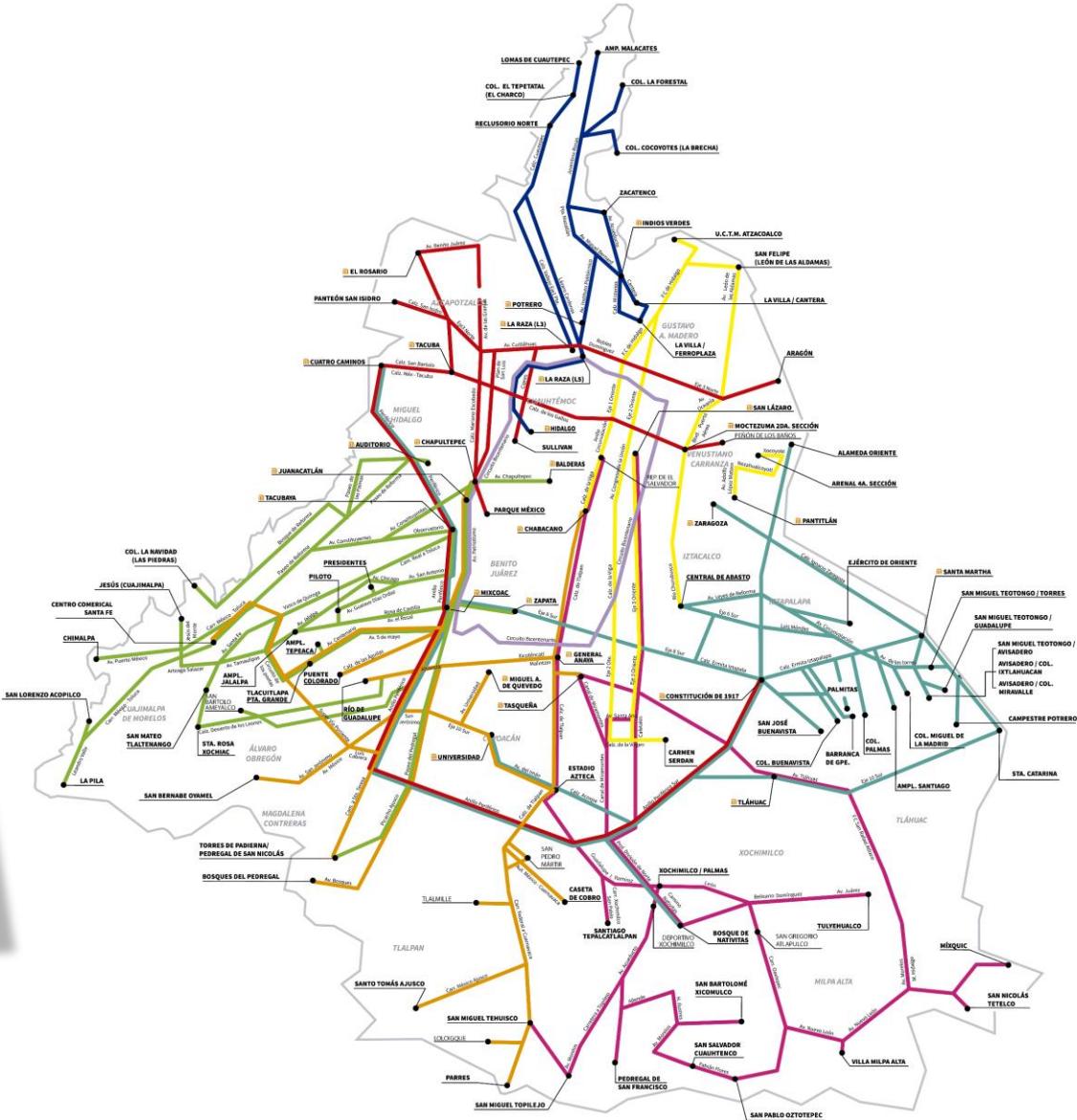
- `arch D.metrobus if tin(2008m1, 2018m12), ar(1) arch(1)`
- `predict fcst_arch1 in tin(2008m1, 2019m12), dynamic(tm(2018m12))`
- `tsline D.metrobus fcst_arch1 if tin(2018m1, 2019m12), tline(2018m12)`

## **Part II. Multivariate time-series analysis**

# Trolley bus



# RTP



# The dataset

The screenshot shows the Stata Data Editor (Browse) window for a dataset named [var\_ptmex]. The main view displays 14 rows of data with the following structure:

|    | date      | d_metro   | d_metrobus | d_trolley | d_rtp     |
|----|-----------|-----------|------------|-----------|-----------|
| 1  | 05jan2015 | 1.242085  | 3.481033   | 3.42668   | -1.556734 |
| 2  | 06jan2015 | .1757893  | 1.720243   | 1.196019  | .2009903  |
| 3  | 07jan2015 | .2469624  | 1.116559   | 2.394182  | .1769749  |
| 4  | 08jan2015 | -.0164806 | 1.023347   | 1.110079  | .4144409  |
| 5  | 09jan2015 | .931869   | .9210421   | -.9818314 | .2410533  |
| 6  | 12jan2015 | .0305322  | .8562469   | 1.590774  | .7253451  |
| 7  | 13jan2015 | .168649   | -.4410605  | -.6486164 | -1.70464  |
| 8  | 14jan2015 | -.99567   | -.4756604  | -.1325982 | .416592   |
| 9  | 15jan2015 | .7037176  | .8317384   | .5290978  | 1.532328  |
| 10 | 16jan2015 | .0017397  | .7911649   | -.6334136 | -.5504839 |
| 11 | 19jan2015 | .4245895  | -1.425354  | -.6473138 | -1.587711 |
| 12 | 20jan2015 | -.4003676 | -.6383936  | -1.295054 | .1525764  |
| 13 | 21jan2015 | -.7422836 | -1.317292  | -1.781026 | -1.58423  |
| 14 | 22jan2015 | -1.628885 | -1.512212  | .8079062  | -.348318  |

The Variables pane on the right lists the variables and their properties:

| Name       | Label                              | Type  | Format | Value |
|------------|------------------------------------|-------|--------|-------|
| date       |                                    | float | %td    |       |
| d_metro    | Metro passengers (daily change)    | float | %9.0g  |       |
| d_metrobus | Metrobus passengers (daily change) | float | %9.0g  |       |
| d_trolley  | Trolley passengers (daily change)  | float | %9.0g  |       |
| d_rtp      | RTP passengers (daily change)      | float | %9.0g  |       |

The Properties pane shows the dataset's properties:

| Variables   | Properties |
|-------------|------------|
| Name        | date       |
| Label       |            |
| Type        | float      |
| Format      | %td        |
| Value label |            |
| Notes       |            |

| Data      | Properties                |
|-----------|---------------------------|
| Frame     | default                   |
| Filename  | var_ptmex.dta             |
| Label     | Mexico City transport VAR |
| Notes     |                           |
| Variables | 5                         |

At the bottom, the status bar indicates: Vars: 5 Order: Dataset Obs: 997 Filter: Off Mode: Browse CAP NUM.

# The dataset

```
. tsset date
Time variable: date, 05jan2015 to 30oct2018, but with gaps
Delta: 1 day
```

```
. tsset date
```

# The dataset

| date      |
|-----------|
| 05jan2015 |
| 06jan2015 |
| 07jan2015 |
| 08jan2015 |
| 09jan2015 |
| 12jan2015 |
| 13jan2015 |
| 14jan2015 |
| 15jan2015 |
| 16jan2015 |

# Step 1: Create a business calendar

Business calendar mycal (format %tbmycal):

Purpose:

Range: 05jan2015 30oct2018  
20093 21487 in %td units  
0 996 in %tbmycal units

Center: 05jan2015  
20093 in %td units  
0 in %tbmycal units

Omitted: 398 days  
104.2 approx. days/year

Included: 997 days  
261.0 approx. days/year

Notes:

Business calendar file mycal.stbcal saved.

. bcal create mycal, from(date)

## Step 2: Load the business calendar

```
loading .\mycal.stbcal ...
```

```
1. * Business calendar "mycal" created by -bcal create-
2. * Created/replaced on 13 Mar 2023
3.
4. version 17
5. dateformat ymd
6.
7. range 2015jan05 2018oct30
8. centerdate 2015jan05
9.
10. omit dayofweek (Sa Su)
```

```
(calendar loaded successfully)
```

```
. bcal load mycal
```

## Step 3: Generate business calendar variable

|    | date      | d_metro   | d_metrobus | d_trolley | d_rtp     | bcaldate |
|----|-----------|-----------|------------|-----------|-----------|----------|
| 1  | 05jan2015 | 1.242085  | 3.481033   | 3.42668   | -1.55673  | 0        |
| 2  | 06jan2015 | .1757893  | 1.720243   | 1.196019  | .2009903  | 1        |
| 3  | 07jan2015 | .2469624  | 1.116559   | 2.394182  | .1769749  | 2        |
| 4  | 08jan2015 | -.0164806 | 1.023347   | 1.110079  | .4144409  | 3        |
| 5  | 09jan2015 | .931869   | .9210421   | -.9818314 | .2410533  | 4        |
| 6  | 12jan2015 | .0305322  | .8562469   | 1.590774  | .7253451  | 5        |
| 7  | 13jan2015 | .168649   | -.4410605  | -.6486164 | -1.70461  | 6        |
| 8  | 14jan2015 | -.99567   | -.4756604  | -.1325982 | .416592   | 7        |
| 9  | 15jan2015 | .7037176  | .8317384   | .5290978  | 1.532323  | 8        |
| 10 | 16jan2015 | .0017397  | .7911649   | -.6334136 | -.5504839 | 9        |
| 11 | 19jan2015 | .4245895  | -1.425354  | -.6473138 | -1.58771  | 10       |
| 12 | 20jan2015 | -.4003676 | -.6383936  | -1.295054 | .1525761  | 11       |
| 13 | 21jan2015 | -.7422836 | -1.317292  | -1.781026 | -1.58423  | 12       |
| 14 | 22jan2015 | -1.628885 | -1.512212  | .8079062  | -.348313  | 13       |

- generate bcaldate = bofd("mycal", date)

## Step 4: Format business calendar variable

|    | date      | d_metro   | d_metrobus | d_trolley | d_rtp     | bcaldate  |
|----|-----------|-----------|------------|-----------|-----------|-----------|
| 1  | 05jan2015 | 1.242085  | 3.481033   | 3.42668   | -1.55673  | 05jan2015 |
| 2  | 06jan2015 | .1757893  | 1.720243   | 1.196019  | .2009903  | 06jan2015 |
| 3  | 07jan2015 | .2469624  | 1.116559   | 2.394182  | .1769740  | 07jan2015 |
| 4  | 08jan2015 | -.0164806 | 1.023347   | 1.110079  | .4144400  | 08jan2015 |
| 5  | 09jan2015 | .931869   | .9210421   | -.9818314 | .2410533  | 09jan2015 |
| 6  | 12jan2015 | .0305322  | .8562469   | 1.590774  | .725345   | 12jan2015 |
| 7  | 13jan2015 | .168649   | -.4410605  | -.6486164 | -1.7046   | 13jan2015 |
| 8  | 14jan2015 | -.99567   | -.4756604  | -.1325982 | .41659    | 14jan2015 |
| 9  | 15jan2015 | .7037176  | .8317384   | .5290978  | 1.53232   | 15jan2015 |
| 10 | 16jan2015 | .0017397  | .7911649   | -.6334136 | -.5504830 | 16jan2015 |
| 11 | 19jan2015 | .4245895  | -1.425354  | -.6473138 | -1.58771  | 19jan2015 |
| 12 | 20jan2015 | -.4003676 | -.6383936  | -1.295054 | .152576   | 20jan2015 |
| 13 | 21jan2015 | -.7422836 | -1.317292  | -1.781026 | -1.5842   | 21jan2015 |
| 14 | 22jan2015 | -1.628885 | -1.512212  | .8079062  | -.34831   | 22jan2015 |

. format %tbmycal bcaldate

# Business calendar variable

```
. tsset bcaldate
```

```
Time variable: bcaldate, 05jan2015 to 30oct2018
Delta: 1 day
```

```
. tsset bcaldate
```

# Vector autoregression intuition

$$\begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} = \begin{bmatrix} 0 & a_{12} & a_{13} & a_{14} \\ a_{21} & 0 & a_{23} & a_{24} \\ a_{31} & a_{32} & 0 & a_{34} \\ a_{41} & a_{42} & a_{43} & 0 \end{bmatrix} \begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} + \begin{bmatrix} a_{11}^1 & a_{12}^1 & a_{13}^1 & a_{14}^1 \\ a_{21}^1 & a_{22}^1 & a_{23}^1 & a_{24}^1 \\ a_{31}^1 & a_{32}^1 & a_{33}^1 & a_{34}^1 \\ a_{41}^1 & a_{42}^1 & a_{43}^1 & a_{44}^1 \end{bmatrix} \begin{bmatrix} metro_{t-1} \\ metrobus_{t-1} \\ trolley_{t-1} \\ rtp_{t-1} \end{bmatrix} + \dots + \begin{bmatrix} b_{11} & b_{12} & b_{13} & b_{14} \\ b_{21} & b_{22} & b_{23} & b_{24} \\ b_{31} & b_{32} & b_{33} & b_{34} \\ b_{41} & b_{42} & b_{43} & b_{44} \end{bmatrix} \begin{bmatrix} \epsilon_{1,t} \\ \epsilon_{2,t} \\ \epsilon_{3,t} \\ \epsilon_{4,t} \end{bmatrix}$$

# VAR intuition: Contemporaneous effects

$$\begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} = \begin{bmatrix} 0 & a_{12} & a_{13} & a_{14} \\ a_{21} & 0 & a_{23} & a_{24} \\ a_{31} & a_{32} & 0 & a_{34} \\ a_{41} & a_{42} & a_{43} & 0 \end{bmatrix} \begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} + \begin{bmatrix} a_{11}^1 & a_{12}^1 & a_{13}^1 & a_{14}^1 \\ a_{21}^1 & a_{22}^1 & a_{23}^1 & a_{24}^1 \\ a_{31}^1 & a_{32}^1 & a_{33}^1 & a_{34}^1 \\ a_{41}^1 & a_{42}^1 & a_{43}^1 & a_{44}^1 \end{bmatrix} \begin{bmatrix} metro_{t-1} \\ metrobus_{t-1} \\ trolley_{t-1} \\ rtp_{t-1} \end{bmatrix} + \dots + \begin{bmatrix} b_{11} & b_{12} & b_{13} & b_{14} \\ b_{21} & b_{22} & b_{23} & b_{24} \\ b_{31} & b_{32} & b_{33} & b_{34} \\ b_{41} & b_{42} & b_{43} & b_{44} \end{bmatrix} \begin{bmatrix} \epsilon_{1,t} \\ \epsilon_{2,t} \\ \epsilon_{3,t} \\ \epsilon_{4,t} \end{bmatrix}$$

# VAR intuition: Contemporaneous effects

$$\begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} = \begin{bmatrix} 0 & a_{12} & a_{13} & a_{14} \\ a_{21} & 0 & a_{23} & a_{24} \\ a_{31} & a_{32} & 0 & a_{34} \\ a_{41} & a_{42} & a_{43} & 0 \end{bmatrix} \begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} + \begin{bmatrix} a_{11}^1 & a_{12}^1 & a_{13}^1 & a_{14}^1 \\ a_{21}^1 & a_{22}^1 & a_{23}^1 & a_{24}^1 \\ a_{31}^1 & a_{32}^1 & a_{33}^1 & a_{34}^1 \\ a_{41}^1 & a_{42}^1 & a_{43}^1 & a_{44}^1 \end{bmatrix} \begin{bmatrix} metro_{t-1} \\ metrobus_{t-1} \\ trolley_{t-1} \\ rtp_{t-1} \end{bmatrix} + \dots + \begin{bmatrix} b_{11} & b_{12} & b_{13} & b_{14} \\ b_{21} & b_{22} & b_{23} & b_{24} \\ b_{31} & b_{32} & b_{33} & b_{34} \\ b_{41} & b_{42} & b_{43} & b_{44} \end{bmatrix} \begin{bmatrix} \epsilon_{1,t} \\ \epsilon_{2,t} \\ \epsilon_{3,t} \\ \epsilon_{4,t} \end{bmatrix}$$

# VAR intuition: Contemporaneous effects

$$\begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} = \begin{bmatrix} 0 & a_{12} & a_{13} & a_{14} \\ a_{21} & 0 & a_{23} & a_{24} \\ a_{31} & a_{32} & 0 & a_{34} \\ a_{41} & a_{42} & a_{43} & 0 \end{bmatrix} \begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} + \begin{bmatrix} a_{11}^1 & a_{12}^1 & a_{13}^1 & a_{14}^1 \\ a_{21}^1 & a_{22}^1 & a_{23}^1 & a_{24}^1 \\ a_{31}^1 & a_{32}^1 & a_{33}^1 & a_{34}^1 \\ a_{41}^1 & a_{42}^1 & a_{43}^1 & a_{44}^1 \end{bmatrix} \begin{bmatrix} metro_{t-1} \\ metrobus_{t-1} \\ trolley_{t-1} \\ rtp_{t-1} \end{bmatrix} + \dots + \begin{bmatrix} b_{11} & b_{12} & b_{13} & b_{14} \\ b_{21} & b_{22} & b_{23} & b_{24} \\ b_{31} & b_{32} & b_{33} & b_{34} \\ b_{41} & b_{42} & b_{43} & b_{44} \end{bmatrix} \begin{bmatrix} \epsilon_{1,t} \\ \epsilon_{2,t} \\ \epsilon_{3,t} \\ \epsilon_{4,t} \end{bmatrix}$$

- If a commuter is not using one transportation system today, they may be using another.

# VAR intuition: Lagged effects

$$\begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} = \begin{bmatrix} 0 & a_{12} & a_{13} & a_{14} \\ a_{21} & 0 & a_{23} & a_{24} \\ a_{31} & a_{32} & 0 & a_{34} \\ a_{41} & a_{42} & a_{43} & 0 \end{bmatrix} \begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} + \begin{bmatrix} a_{11}^1 & a_{12}^1 & a_{13}^1 & a_{14}^1 \\ a_{21}^1 & a_{22}^1 & a_{23}^1 & a_{24}^1 \\ a_{31}^1 & a_{32}^1 & a_{33}^1 & a_{34}^1 \\ a_{41}^1 & a_{42}^1 & a_{43}^1 & a_{44}^1 \end{bmatrix} \begin{bmatrix} metro_{t-1} \\ metrobus_{t-1} \\ trolley_{t-1} \\ rtp_{t-1} \end{bmatrix} + \dots + \begin{bmatrix} b_{11} & b_{12} & b_{13} & b_{14} \\ b_{21} & b_{22} & b_{23} & b_{24} \\ b_{31} & b_{32} & b_{33} & b_{34} \\ b_{41} & b_{42} & b_{43} & b_{44} \end{bmatrix} \begin{bmatrix} \epsilon_{1,t} \\ \epsilon_{2,t} \\ \epsilon_{3,t} \\ \epsilon_{4,t} \end{bmatrix}$$

# VAR intuition: Lagged effects

$$\begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} = \begin{bmatrix} 0 & a_{12} & a_{13} & a_{14} \\ a_{21} & 0 & a_{23} & a_{24} \\ a_{31} & a_{32} & 0 & a_{34} \\ a_{41} & a_{42} & a_{43} & 0 \end{bmatrix} \begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} + \begin{bmatrix} a_{11}^1 & a_{12}^1 & a_{13}^1 & a_{14}^1 \\ a_{21}^1 & a_{22}^1 & a_{23}^1 & a_{24}^1 \\ a_{31}^1 & a_{32}^1 & a_{33}^1 & a_{34}^1 \\ a_{41}^1 & a_{42}^1 & a_{43}^1 & a_{44}^1 \end{bmatrix} \begin{bmatrix} metro_{t-1} \\ metrobus_{t-1} \\ trolley_{t-1} \\ rtp_{t-1} \end{bmatrix} + \dots + \begin{bmatrix} b_{11} & b_{12} & b_{13} & b_{14} \\ b_{21} & b_{22} & b_{23} & b_{24} \\ b_{31} & b_{32} & b_{33} & b_{34} \\ b_{41} & b_{42} & b_{43} & b_{44} \end{bmatrix} \begin{bmatrix} \epsilon_{1,t} \\ \epsilon_{2,t} \\ \epsilon_{3,t} \\ \epsilon_{4,t} \end{bmatrix}$$

- Negative autocorrelation?  
Probably not. People don't go to work/school just every other day.
- Positive autocorrelation? Maybe, because days of above-average changes in passenger volumes tend to be followed by more days of above-average changes. Same for below-average days.

# VAR intuition: Innovations

$$\begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} = \begin{bmatrix} 0 & a_{12} & a_{13} & a_{14} \\ a_{21} & 0 & a_{23} & a_{24} \\ a_{31} & a_{32} & 0 & a_{34} \\ a_{41} & a_{42} & a_{43} & 0 \end{bmatrix} \begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} + \begin{bmatrix} a_{11}^1 & a_{12}^1 & a_{13}^1 & a_{14}^1 \\ a_{21}^1 & a_{22}^1 & a_{23}^1 & a_{24}^1 \\ a_{31}^1 & a_{32}^1 & a_{33}^1 & a_{34}^1 \\ a_{41}^1 & a_{42}^1 & a_{43}^1 & a_{44}^1 \end{bmatrix} \begin{bmatrix} metro_{t-1} \\ metrobus_{t-1} \\ trolley_{t-1} \\ rtp_{t-1} \end{bmatrix} + \dots + \begin{bmatrix} b_{11} & b_{12} & b_{13} & b_{14} \\ b_{21} & b_{22} & b_{23} & b_{24} \\ b_{31} & b_{32} & b_{33} & b_{34} \\ b_{41} & b_{42} & b_{43} & b_{44} \end{bmatrix} \begin{bmatrix} \epsilon_{1,t} \\ \epsilon_{2,t} \\ \epsilon_{3,t} \\ \epsilon_{4,t} \end{bmatrix}$$

# VAR intuition: Innovations

$$\begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} = \begin{bmatrix} 0 & a_{12} & a_{13} & a_{14} \\ a_{21} & 0 & a_{23} & a_{24} \\ a_{31} & a_{32} & 0 & a_{34} \\ a_{41} & a_{42} & a_{43} & 0 \end{bmatrix} \begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} + \begin{bmatrix} a_{11}^1 & a_{12}^1 & a_{13}^1 & a_{14}^1 \\ a_{21}^1 & a_{22}^1 & a_{23}^1 & a_{24}^1 \\ a_{31}^1 & a_{32}^1 & a_{33}^1 & a_{34}^1 \\ a_{41}^1 & a_{42}^1 & a_{43}^1 & a_{44}^1 \end{bmatrix} \begin{bmatrix} metro_{t-1} \\ metrobus_{t-1} \\ trolley_{t-1} \\ rtp_{t-1} \end{bmatrix} + \dots + \begin{bmatrix} b_{11} & b_{12} & b_{13} & b_{14} \\ b_{21} & b_{22} & b_{23} & b_{24} \\ b_{31} & b_{32} & b_{33} & b_{34} \\ b_{41} & b_{42} & b_{43} & b_{44} \end{bmatrix} \begin{bmatrix} \epsilon_{1,t} \\ \epsilon_{2,t} \\ \epsilon_{3,t} \\ \epsilon_{4,t} \end{bmatrix}$$

# VAR theory review: Setup

$$\begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} = \begin{bmatrix} 0 & a_{12} & a_{13} & a_{14} \\ a_{21} & 0 & a_{23} & a_{24} \\ a_{31} & a_{32} & 0 & a_{34} \\ a_{41} & a_{42} & a_{43} & 0 \end{bmatrix} \begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} + \begin{bmatrix} a_{11}^1 & a_{12}^1 & a_{13}^1 & a_{14}^1 \\ a_{21}^1 & a_{22}^1 & a_{23}^1 & a_{24}^1 \\ a_{31}^1 & a_{32}^1 & a_{33}^1 & a_{34}^1 \\ a_{41}^1 & a_{42}^1 & a_{43}^1 & a_{44}^1 \end{bmatrix} \begin{bmatrix} metro_{t-1} \\ metrobus_{t-1} \\ trolley_{t-1} \\ rtp_{t-1} \end{bmatrix} + \dots + \begin{bmatrix} b_{11} & b_{12} & b_{13} & b_{14} \\ b_{21} & b_{22} & b_{23} & b_{24} \\ b_{31} & b_{32} & b_{33} & b_{34} \\ b_{41} & b_{42} & b_{43} & b_{44} \end{bmatrix} \begin{bmatrix} \epsilon_{1,t} \\ \epsilon_{2,t} \\ \epsilon_{3,t} \\ \epsilon_{4,t} \end{bmatrix}$$

## VAR theory review: Structural to reduced form

$$\begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} = \begin{bmatrix} 0 & a_{12} & a_{13} & a_{14} \\ a_{21} & 0 & a_{23} & a_{24} \\ a_{31} & a_{32} & 0 & a_{34} \\ a_{41} & a_{42} & a_{43} & 0 \end{bmatrix} \begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} + \begin{bmatrix} a_{11}^1 & a_{12}^1 & a_{13}^1 & a_{14}^1 \\ a_{21}^1 & a_{22}^1 & a_{23}^1 & a_{24}^1 \\ a_{31}^1 & a_{32}^1 & a_{33}^1 & a_{34}^1 \\ a_{41}^1 & a_{42}^1 & a_{43}^1 & a_{44}^1 \end{bmatrix} \begin{bmatrix} metro_{t-1} \\ metrobus_{t-1} \\ trolley_{t-1} \\ rtp_{t-1} \end{bmatrix} + \dots + \begin{bmatrix} b_{11} & b_{12} & b_{13} & b_{14} \\ b_{21} & b_{22} & b_{23} & b_{24} \\ b_{31} & b_{32} & b_{33} & b_{34} \\ b_{41} & b_{42} & b_{43} & b_{44} \end{bmatrix} \begin{bmatrix} \epsilon_{1,t} \\ \epsilon_{2,t} \\ \epsilon_{3,t} \\ \epsilon_{4,t} \end{bmatrix}$$

!!!                          !!!

## VAR theory review: Structural to reduced form

$$\begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} = \begin{bmatrix} 0 & a_{12} & a_{13} & a_{14} \\ a_{21} & 0 & a_{23} & a_{24} \\ a_{31} & a_{32} & 0 & a_{34} \\ a_{41} & a_{42} & a_{43} & 0 \end{bmatrix} \begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} + \begin{bmatrix} a_{11}^1 & a_{12}^1 & a_{13}^1 & a_{14}^1 \\ a_{21}^1 & a_{22}^1 & a_{23}^1 & a_{24}^1 \\ a_{31}^1 & a_{32}^1 & a_{33}^1 & a_{34}^1 \\ a_{41}^1 & a_{42}^1 & a_{43}^1 & a_{44}^1 \end{bmatrix} \begin{bmatrix} metro_{t-1} \\ metrobus_{t-1} \\ trolley_{t-1} \\ rtp_{t-1} \end{bmatrix} + \dots + \begin{bmatrix} b_{11} & b_{12} & b_{13} & b_{14} \\ b_{21} & b_{22} & b_{23} & b_{24} \\ b_{31} & b_{32} & b_{33} & b_{34} \\ b_{41} & b_{42} & b_{43} & b_{44} \end{bmatrix} \begin{bmatrix} \epsilon_{1,t} \\ \epsilon_{2,t} \\ \epsilon_{3,t} \\ \epsilon_{4,t} \end{bmatrix}$$



$$\begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} - \begin{bmatrix} 0 & a_{12} & a_{13} & a_{14} \\ a_{21} & 0 & a_{23} & a_{24} \\ a_{31} & a_{32} & 0 & a_{34} \\ a_{41} & a_{42} & a_{43} & 0 \end{bmatrix} \begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} = \begin{bmatrix} a_{11}^1 & a_{12}^1 & a_{13}^1 & a_{14}^1 \\ a_{21}^1 & a_{22}^1 & a_{23}^1 & a_{24}^1 \\ a_{31}^1 & a_{32}^1 & a_{33}^1 & a_{34}^1 \\ a_{41}^1 & a_{42}^1 & a_{43}^1 & a_{44}^1 \end{bmatrix} \begin{bmatrix} metro_{t-1} \\ metrobus_{t-1} \\ trolley_{t-1} \\ rtp_{t-1} \end{bmatrix} + \dots + \begin{bmatrix} b_{11} & b_{12} & b_{13} & b_{14} \\ b_{21} & b_{22} & b_{23} & b_{24} \\ b_{31} & b_{32} & b_{33} & b_{34} \\ b_{41} & b_{42} & b_{43} & b_{44} \end{bmatrix} \begin{bmatrix} \epsilon_{1,t} \\ \epsilon_{2,t} \\ \epsilon_{3,t} \\ \epsilon_{4,t} \end{bmatrix}$$

## VAR theory review: Structural to reduced form

$$\begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} = \begin{bmatrix} 0 & a_{12} & a_{13} & a_{14} \\ a_{21} & 0 & a_{23} & a_{24} \\ a_{31} & a_{32} & 0 & a_{34} \\ a_{41} & a_{42} & a_{43} & 0 \end{bmatrix} \begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} + \begin{bmatrix} a_{11}^1 & a_{12}^1 & a_{13}^1 & a_{14}^1 \\ a_{21}^1 & a_{22}^1 & a_{23}^1 & a_{24}^1 \\ a_{31}^1 & a_{32}^1 & a_{33}^1 & a_{34}^1 \\ a_{41}^1 & a_{42}^1 & a_{43}^1 & a_{44}^1 \end{bmatrix} \begin{bmatrix} metro_{t-1} \\ metrobus_{t-1} \\ trolley_{t-1} \\ rtp_{t-1} \end{bmatrix} + \dots + \begin{bmatrix} b_{11} & b_{12} & b_{13} & b_{14} \\ b_{21} & b_{22} & b_{23} & b_{24} \\ b_{31} & b_{32} & b_{33} & b_{34} \\ b_{41} & b_{42} & b_{43} & b_{44} \end{bmatrix} \begin{bmatrix} \epsilon_{1,t} \\ \epsilon_{2,t} \\ \epsilon_{3,t} \\ \epsilon_{4,t} \end{bmatrix}$$

$$\begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} - \begin{bmatrix} 0 & a_{12} & a_{13} & a_{14} \\ a_{21} & 0 & a_{23} & a_{24} \\ a_{31} & a_{32} & 0 & a_{34} \\ a_{41} & a_{42} & a_{43} & 0 \end{bmatrix} \begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} = \begin{bmatrix} a_{11}^1 & a_{12}^1 & a_{13}^1 & a_{14}^1 \\ a_{21}^1 & a_{22}^1 & a_{23}^1 & a_{24}^1 \\ a_{31}^1 & a_{32}^1 & a_{33}^1 & a_{34}^1 \\ a_{41}^1 & a_{42}^1 & a_{43}^1 & a_{44}^1 \end{bmatrix} \begin{bmatrix} metro_{t-1} \\ metrobus_{t-1} \\ trolley_{t-1} \\ rtp_{t-1} \end{bmatrix} + \dots + \begin{bmatrix} b_{11} & b_{12} & b_{13} & b_{14} \\ b_{21} & b_{22} & b_{23} & b_{24} \\ b_{31} & b_{32} & b_{33} & b_{34} \\ b_{41} & b_{42} & b_{43} & b_{44} \end{bmatrix} \begin{bmatrix} \epsilon_{1,t} \\ \epsilon_{2,t} \\ \epsilon_{3,t} \\ \epsilon_{4,t} \end{bmatrix}$$

→

$$\begin{bmatrix} 1 & -a_{12} & -a_{13} & -a_{14} \\ -a_{21} & 1 & -a_{23} & -a_{24} \\ -a_{31} & -a_{32} & 1 & -a_{34} \\ -a_{41} & -a_{42} & -a_{43} & 1 \end{bmatrix} \begin{bmatrix} metro_t \\ metrobus_t \\ trolley_t \\ rtp_t \end{bmatrix} = \begin{bmatrix} a_{11}^1 & a_{12}^1 & a_{13}^1 & a_{14}^1 \\ a_{21}^1 & a_{22}^1 & a_{23}^1 & a_{24}^1 \\ a_{31}^1 & a_{32}^1 & a_{33}^1 & a_{34}^1 \\ a_{41}^1 & a_{42}^1 & a_{43}^1 & a_{44}^1 \end{bmatrix} \begin{bmatrix} metro_{t-1} \\ metrobus_{t-1} \\ trolley_{t-1} \\ rtp_{t-1} \end{bmatrix} + \dots + \begin{bmatrix} b_{11} & b_{12} & b_{13} & b_{14} \\ b_{21} & b_{22} & b_{23} & b_{24} \\ b_{31} & b_{32} & b_{33} & b_{34} \\ b_{41} & b_{42} & b_{43} & b_{44} \end{bmatrix} \begin{bmatrix} \epsilon_{1,t} \\ \epsilon_{2,t} \\ \epsilon_{3,t} \\ \epsilon_{4,t} \end{bmatrix}$$

*A*

*y<sub>t</sub>*

*A<sub>1</sub>*

*y<sub>t-1</sub>*

*B*

*ε<sub>t</sub>*

## VAR theory review: Structural to reduced form

$$Ay_t = A_1y_{t-1} + \dots + A_py_{t-p} + B\epsilon_t$$

## VAR theory review: Structural to reduced form

$$Ay_t = A_1y_{t-1} + \dots + A_py_{t-p} + B\epsilon_t$$

$$y_t = \underbrace{A^{-1}A_1}_{\Phi_1} y_{t-1} + \dots + \underbrace{A^{-1}A_p}_{\Phi_p} y_{t-p} + \underbrace{A^{-1}B\epsilon_t}_{u_t}$$

## VAR theory review: Structural to reduced form

$$Ay_t = A_1y_{t-1} + \dots + A_py_{t-p} + B\epsilon_t$$

$$y_t = \underbrace{A^{-1}A_1}_{\Phi_1} y_{t-1} + \dots + \underbrace{A^{-1}A_p}_{\Phi_p} y_{t-p} + \underbrace{A^{-1}B\epsilon_t}_{u_t}$$

$$y_t = \Phi_1 y_{t-1} + \dots + \Phi_p y_{t-p} + u_t$$

# VAR: Lag order

Lag-order selection criteria

Sample: 12jan2015 thru 30oct2018

Number of obs = 992

| Lag | LL      | LR     | df | p     | FPE      | AIC       | HQIC      | SBIC     |
|-----|---------|--------|----|-------|----------|-----------|-----------|----------|
| 0   | 4527.17 |        |    |       | 1.3e-09  | -9.1193   | -9.11179  | -9.09954 |
| 1   | 6067.36 | 3080.4 | 16 | 0.000 | 6.0e-11  | -12.1923  | -12.1547  | -12.0935 |
| 2   | 6153.1  | 171.48 | 16 | 0.000 | 5.2e-11  | -12.3329  | -12.2653  | -12.155* |
| 3   | 6184.62 | 63.04* | 16 | 0.000 | 5.0e-11* | -12.3642* | -12.2665* | -12.1073 |
| 4   | 6192.31 | 15.39  | 16 | 0.496 | 5.1e-11  | -12.3474  | -12.2197  | -12.0115 |
| 5   | 6196.83 | 9.0334 | 16 | 0.912 | 5.2e-11  | -12.3243  | -12.1665  | -11.9094 |

\* optimal lag

Endogenous: d\_metro d\_metrobus d\_trolley d\_rtp

Exogenous: \_cons

- varsoc d\_metro d\_metrobus d\_trolley d\_rtp

# VAR: Output

Vector autoregression

Sample: 08jan2015 thru 30oct2018 Number of obs = 994  
Log likelihood = -2057.746 AIC = 4.244961  
FPE = .0008197 HQIC = 4.342451  
Det(Sigma\_m1) = .0007383 SBIC = 4.50139

| Equation   | Parms | RMSE    | R-sq   | chi2     | P>chi2 |
|------------|-------|---------|--------|----------|--------|
| d_metro    | 13    | .411561 | 0.8329 | 4954.318 | 0.0000 |
| d.metrobus | 13    | .581226 | 0.6617 | 1944.278 | 0.0000 |
| d_trolley  | 13    | .925986 | 0.1391 | 160.5786 | 0.0000 |
| d_rtp      | 13    | .981036 | 0.0497 | 51.96537 | 0.0000 |

```
. var d_metro d.metrobus d_trolley
d_rtp, lags(1 2 3)
```

# VAR: Output

|            | Coefficient | Std. err. | z     | P> z  | [95% conf. interval] |
|------------|-------------|-----------|-------|-------|----------------------|
| d_metro    |             |           |       |       |                      |
| d_metro    |             |           |       |       |                      |
| L1.        | .0578853    | .0382751  | 1.51  | 0.130 | -.0171325 .1329031   |
| L2.        | .108086     | .0464578  | 2.33  | 0.020 | .0170304 .1991416    |
| L3.        | .1416069    | .0375527  | 3.77  | 0.000 | .0680049 .2152089    |
| d_metrobus |             |           |       |       |                      |
| L1.        | -.1588305   | .1139093  | -1.39 | 0.163 | -.3820885 .0644276   |
| L2.        | -.2908373   | .0945086  | -3.08 | 0.002 | -.4760708 -.1056038  |
| L3.        | .0977986    | .0398539  | 2.45  | 0.014 | .0196864 .1759108    |
| d_trolley  |             |           |       |       |                      |
| L1.        | .0341848    | .0200201  | 1.71  | 0.088 | -.0050539 .0734234   |
| L2.        | .0284608    | .0287286  | 0.99  | 0.322 | -.0278462 .0847679   |
| L3.        | .0385756    | .0269324  | 1.43  | 0.152 | -.0142109 .091362    |
| d_rtp      |             |           |       |       |                      |
| L1.        | .5980455    | .074328   | 8.05  | 0.000 | .4523653 .7437257    |
| L2.        | .6297207    | .0803916  | 7.83  | 0.000 | .4721561 .7872854    |
| L3.        | .3153713    | .0453119  | 6.96  | 0.000 | .2265616 .404181     |
| _cons      | -.0038782   | .0129925  | -0.30 | 0.765 | -.029343 .0215867    |

# VAR: Output

|            |           |          |       |       |           |          |
|------------|-----------|----------|-------|-------|-----------|----------|
| d_metrobus |           |          |       |       |           |          |
| d.metro    |           |          |       |       |           |          |
| L1.        | .3077106  | .0540539 | 5.69  | 0.000 | .2017669  | .4136543 |
| L2.        | -.0260303 | .0656099 | -0.40 | 0.692 | -.1546233 | .1025628 |
| L3.        | -.0008957 | .0530337 | -0.02 | 0.987 | -.10484   | .1030485 |
| d.metrobus |           |          |       |       |           |          |
| L1.        | .0615783  | .160868  | 0.38  | 0.702 | -.2537172 | .3768738 |
| L2.        | -.2176465 | .1334695 | -1.63 | 0.103 | -.479242  | .0439489 |
| L3.        | .0721852  | .0562836 | 1.28  | 0.200 | -.0381286 | .1824989 |
| d_trolley  |           |          |       |       |           |          |
| L1.        | .1889079  | .0282733 | 6.68  | 0.000 | .1334933  | .2443225 |
| L2.        | .1050341  | .0405719 | 2.59  | 0.010 | .0255147  | .1845536 |
| L3.        | .0957912  | .0380351 | 2.52  | 0.012 | .0212437  | .1703387 |
| d_rtp      |           |          |       |       |           |          |
| L1.        | .418431   | .1049695 | 3.99  | 0.000 | .2126945  | .6241674 |
| L2.        | .0648947  | .1135328 | 0.57  | 0.568 | -.1576256 | .2874149 |
| L3.        | .0730707  | .0639916 | 1.14  | 0.254 | -.0523506 | .1984919 |
| _cons      | -.0057634 | .0183486 | -0.31 | 0.753 | -.041726  | .0301992 |

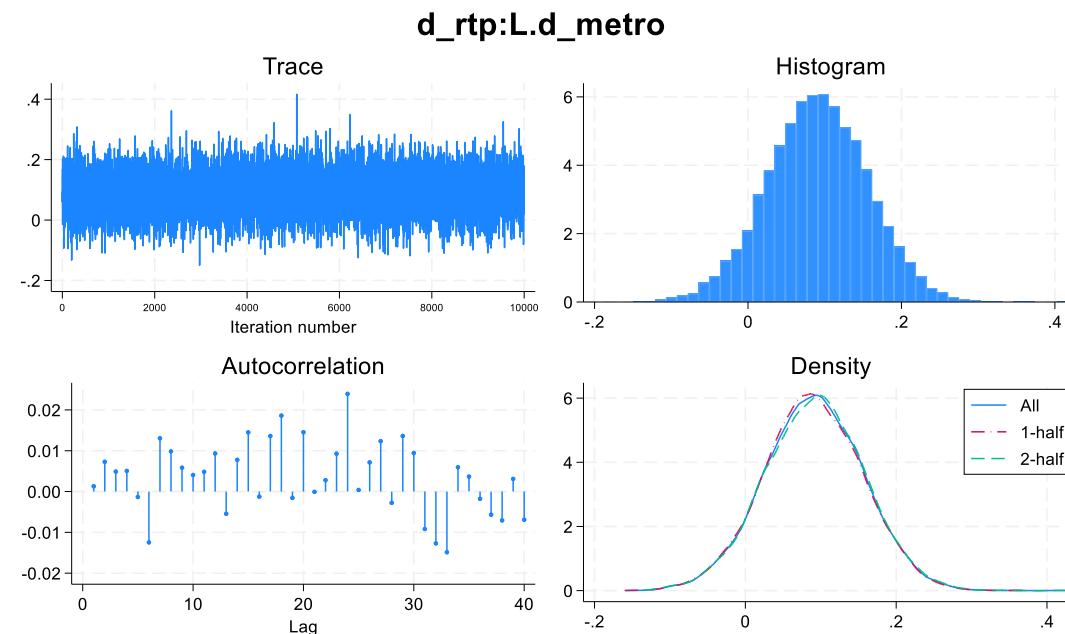
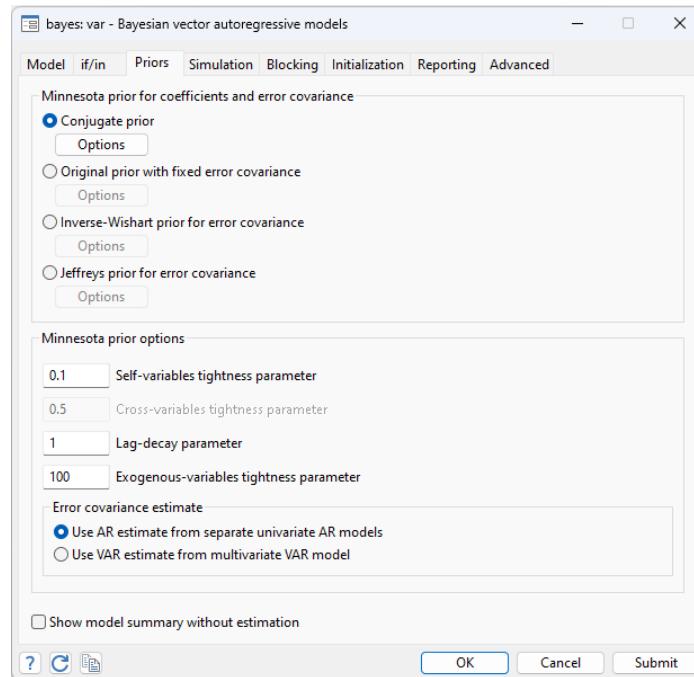
# VAR: Output

| d_trolley  |           |          |       |       |           |          |
|------------|-----------|----------|-------|-------|-----------|----------|
| d_metro    |           |          |       |       |           |          |
| L1.        | .1137616  | .0861166 | 1.32  | 0.186 | -.0550238 | .2825469 |
| L2.        | -.0588601 | .1045272 | -0.56 | 0.573 | -.2637296 | .1460094 |
| L3.        | -.0256809 | .0844913 | -0.30 | 0.761 | -.1912808 | .1399191 |
| d_metrobus |           |          |       |       |           |          |
| L1.        | .2076194  | .2562887 | 0.81  | 0.418 | -.2946972 | .709936  |
| L2.        | .0436953  | .2126385 | 0.21  | 0.837 | -.3730684 | .460459  |
| L3.        | .0777061  | .0896688 | 0.87  | 0.386 | -.0980415 | .2534537 |
| d_trolley  |           |          |       |       |           |          |
| L1.        | -.0152065 | .0450439 | -0.34 | 0.736 | -.103491  | .0730779 |
| L2.        | -.0088138 | .0646376 | -0.14 | 0.892 | -.1355011 | .1178735 |
| L3.        | .0516183  | .0605961 | 0.85  | 0.394 | -.0671479 | .1703845 |
| d_rtp      |           |          |       |       |           |          |
| L1.        | .1036687  | .1672333 | 0.62  | 0.535 | -.2241027 | .43144   |
| L2.        | -.0593307 | .1808761 | -0.33 | 0.743 | -.4138413 | .2951799 |
| L3.        | -.0253078 | .101949  | -0.25 | 0.804 | -.2251241 | .1745085 |
| _cons      | -.005603  | .0292323 | -0.19 | 0.848 | -.0628973 | .0516912 |

# VAR: Output

| d_rtp      |           |          |       |       |           |          |
|------------|-----------|----------|-------|-------|-----------|----------|
| d_metro    |           |          |       |       |           |          |
| L1.        | .1021072  | .0912362 | 1.12  | 0.263 | -.0767124 | .2809268 |
| L2.        | -.0348227 | .1107413 | -0.31 | 0.753 | -.2518716 | .1822262 |
| L3.        | .0238819  | .0895143 | 0.27  | 0.790 | -.1515629 | .1993267 |
| d_metrobus |           |          |       |       |           |          |
| L1.        | .0221895  | .271525  | 0.08  | 0.935 | -.5099897 | .5543687 |
| L2.        | -.4005451 | .2252798 | -1.78 | 0.075 | -.8420853 | .0409952 |
| L3.        | .1591715  | .0949996 | 1.68  | 0.094 | -.0270242 | .3453672 |
| d_trolley  |           |          |       |       |           |          |
| L1.        | .0124564  | .0477217 | 0.26  | 0.794 | -.0810765 | .1059893 |
| L2.        | .0050517  | .0684802 | 0.07  | 0.941 | -.1291671 | .1392705 |
| L3.        | .0785933  | .0641985 | 1.22  | 0.221 | -.0472335 | .2044201 |
| d_rtp      |           |          |       |       |           |          |
| L1.        | .0610577  | .1771753 | 0.34  | 0.730 | -.2861995 | .408315  |
| L2.        | .2549217  | .1916291 | 1.33  | 0.183 | -.1206644 | .6305079 |
| L3.        | .1552565  | .1080098 | 1.44  | 0.151 | -.0564388 | .3669518 |
| _cons      | -.0000959 | .0309702 | -0.00 | 0.998 | -.0607963 | .0606045 |

# The bayes prefix



```
. bayes: var d_metro d.metrobus d_trolley d_rtp, lags(1 2 3)
```

# Structural vector autoregression

$$Ay_t = A_1y_{t-1} + \dots + A_py_{t-p} + B\epsilon_t$$

$$y_t = \underbrace{A^{-1}A_1}_{\Phi_1} y_{t-1} + \dots + \underbrace{A^{-1}A_p}_{\Phi_p} y_{t-p} + \underbrace{A^{-1}B\epsilon_t}_{u_t}$$

$$y_t = \Phi_1 y_{t-1} + \dots + \Phi_p y_{t-p} + u_t$$

# SVAR

$$Ay_t = A_1y_{t-1} + \dots + A_py_{t-p} + B\epsilon_t$$

$$y_t = \underbrace{A^{-1}A_1}_{\Phi_1} y_{t-1} + \dots + \underbrace{A^{-1}A_p}_{\Phi_p} y_{t-p} + \underbrace{A^{-1}B\epsilon_t}_{u_t}$$

$$y_t = \Phi_1 y_{t-1} + \dots + \Phi_p y_{t-p} + u_t$$


$$E[u_t u_t'] = \Sigma$$

# SVAR: Identification

Information we have

$$\Sigma = \begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} & \sigma_{14} \\ \sigma_{21} & \sigma_{22} & \sigma_{23} & \sigma_{24} \\ \sigma_{31} & \sigma_{32} & \sigma_{33} & \sigma_{34} \\ \sigma_{41} & \sigma_{42} & \sigma_{43} & \sigma_{44} \end{bmatrix}$$

10 covariances

Information we want

$$A = \begin{bmatrix} 1 & -a_{12} & -a_{13} & -a_{14} \\ -a_{21} & 1 & -a_{23} & -a_{24} \\ -a_{31} & -a_{32} & 1 & -a_{34} \\ -a_{41} & -a_{42} & -a_{43} & 1 \end{bmatrix}$$

28 parameters

$$B = \begin{bmatrix} b_{11} & b_{12} & b_{13} & b_{14} \\ b_{21} & b_{22} & b_{23} & b_{24} \\ b_{31} & b_{32} & b_{33} & b_{34} \\ b_{41} & b_{42} & b_{43} & b_{44} \end{bmatrix}$$

# SVAR: Cholesky decomposition

Information we have

$$\Sigma = \begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} & \sigma_{14} \\ \sigma_{21} & \sigma_{22} & \sigma_{23} & \sigma_{24} \\ \sigma_{31} & \sigma_{32} & \sigma_{33} & \sigma_{34} \\ \sigma_{41} & \sigma_{42} & \sigma_{43} & \sigma_{44} \end{bmatrix}$$

10 covariances

Information we want

$$A = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -a_{21} & 1 & 0 & 0 \\ -a_{31} & -a_{32} & 1 & 0 \\ -a_{41} & -a_{42} & -a_{43} & 1 \end{bmatrix}$$

10 parameters

$$B = \begin{bmatrix} b_{11} & 0 & 0 & 0 \\ 0 & b_{22} & 0 & 0 \\ 0 & 0 & b_{33} & 0 \\ 0 & 0 & 0 & b_{44} \end{bmatrix}$$

## SVAR ordering

$$\begin{bmatrix} rtp_t \\ trolley_t \\ metrobus_t \\ metro_t \end{bmatrix}$$

# SVAR: Other identification strategies

The screenshot shows a PDF viewer window titled "ts.pdf". The main content area displays a section titled "Long-run SVAR models" with a blue oval highlighting it. Below this, there is a mathematical equation  $y_t = C e_t$ . The text discusses the form of a long-run SVAR and the constraints placed on the matrix  $C$ . It mentions that similar to the short-run model, the  $P_{lr}P'_{lr} = \Sigma$  identifies the structural impulse-response functions. The  $P_{lr} = C$  is identified by the restrictions placed on the parameters in  $C$ . There are  $K^2$  parameters in  $C$ , and the order condition for identification requires that there be at least  $K(K + 1)/2$  restrictions placed on those parameters. A section titled "802 var svar — Structural vector autoregressive models" is also visible.

The screenshot shows the Stata "Viewer - search var\_nr" window. The search bar contains "search var\_nr". The results section shows a single package found: "var\_nr from http://fmwww.bc.edu/RePEc/bocode/v". The description states: "VAR\_NR module to estimate set identified SVARS / The toolbox var\_nr allows for the estimation of set identified / SVARS in Stata using sign and narrative restrictions. The suite / is able to produce impulse responses functions, forecast error / variance decompositions, and". Below the description are links: "(click here to return to the previous screen)" and "(end of search)".

# SVAR(3)

Sample: 08jan2015 thru 30oct2018  
 Exactly identified model  
 Number of obs = 994  
 Log likelihood = -2057.746

|           | Coefficient     | Std. err. | z       | P> z  | [95% conf. interval] |
|-----------|-----------------|-----------|---------|-------|----------------------|
| <i>/A</i> |                 |           |         |       |                      |
| 1_1       | 1 (constrained) |           |         |       |                      |
| 2_1       | -.5707443       | .023845   | -23.94  | 0.000 | -.6174796 -.5240089  |
| 3_1       | -.5982546       | .0047149  | -126.89 | 0.000 | -.6074956 -.5890136  |
| 4_1       | -.8871721       | .0558795  | -15.88  | 0.000 | -.9966938 -.7776504  |
| 1_2       | 0 (constrained) |           |         |       |                      |
| 2_2       | 1 (constrained) |           |         |       |                      |
| 3_2       | .0319603        | .0049952  | 6.40    | 0.000 | .0221699 .0417506    |
| 4_2       | .2263981        | .0145668  | 15.54   | 0.000 | .1978476 .2549485    |
| 1_3       | 0 (constrained) |           |         |       |                      |
| 2_3       | 0 (constrained) |           |         |       |                      |
| 3_3       | 1 (constrained) |           |         |       |                      |
| 4_3       | 1.031821        | .0906478  | 11.38   | 0.000 | .8541541 1.209487    |
| 1_4       | 0 (constrained) |           |         |       |                      |
| 2_4       | 0 (constrained) |           |         |       |                      |
| 3_4       | 0 (constrained) |           |         |       |                      |
| 4_4       | 1 (constrained) |           |         |       |                      |
| <i>/B</i> |                 |           |         |       |                      |
| 1_1       | .9745992        | .0218584  | 44.59   | 0.000 | .9317576 1.017441    |
| 2_1       | 0 (constrained) |           |         |       |                      |
| 3_1       | 0 (constrained) |           |         |       |                      |
| 4_1       | 0 (constrained) |           |         |       |                      |
| 1_2       | 0 (constrained) |           |         |       |                      |
| 2_2       | .7326836        | .0164327  | 44.59   | 0.000 | .7004761 .764891     |
| 3_2       | 0 (constrained) |           |         |       |                      |
| 4_2       | 0 (constrained) |           |         |       |                      |
| 1_3       | 0 (constrained) |           |         |       |                      |
| 2_3       | 0 (constrained) |           |         |       |                      |
| 3_3       | .1153879        | .0025879  | 44.59   | 0.000 | .1103156 .1204601    |
| 4_3       | 0 (constrained) |           |         |       |                      |
| 1_4       | 0 (constrained) |           |         |       |                      |
| 2_4       | 0 (constrained) |           |         |       |                      |
| 3_4       | 0 (constrained) |           |         |       |                      |
| 4_4       | .3297697        | .0073961  | 44.59   | 0.000 | .3152736 .3442658    |

```
matrix input A = (1, 0, 0, 0\ ///
. , 1, 0, 0\ ///
. , . , 1, 0\ ///
. , . , . , 1)
```

```
matrix input B = (., 0, 0, 0\ ///
0, ., 0, 0\ ///
0, 0, ., 0\ ///
0, 0, 0, .)
```

```
. svar d_rtp d_trolley d_metrobus
d_metro, aeq(A) beq(B) lags(1 2 3)
```

# Impulse-response Function

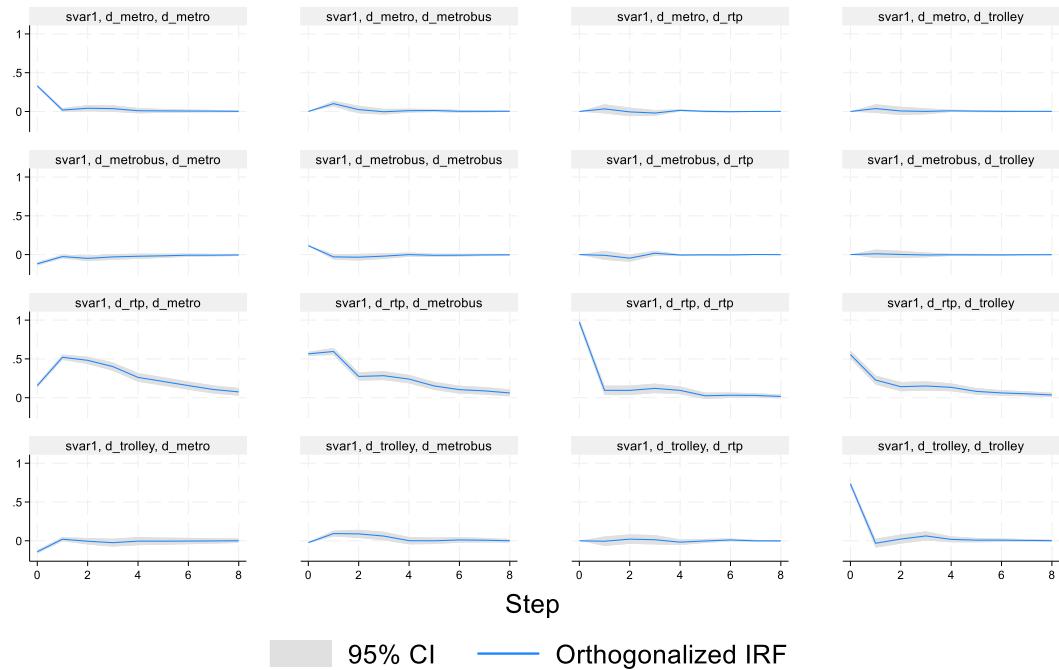
```
. irf set "myIRF"
(file myIRF.irf created)
(file myIRF.irf now active)

. irf create svar1
(file myIRF.irf updated)
```

```
. irf set "myIRF"

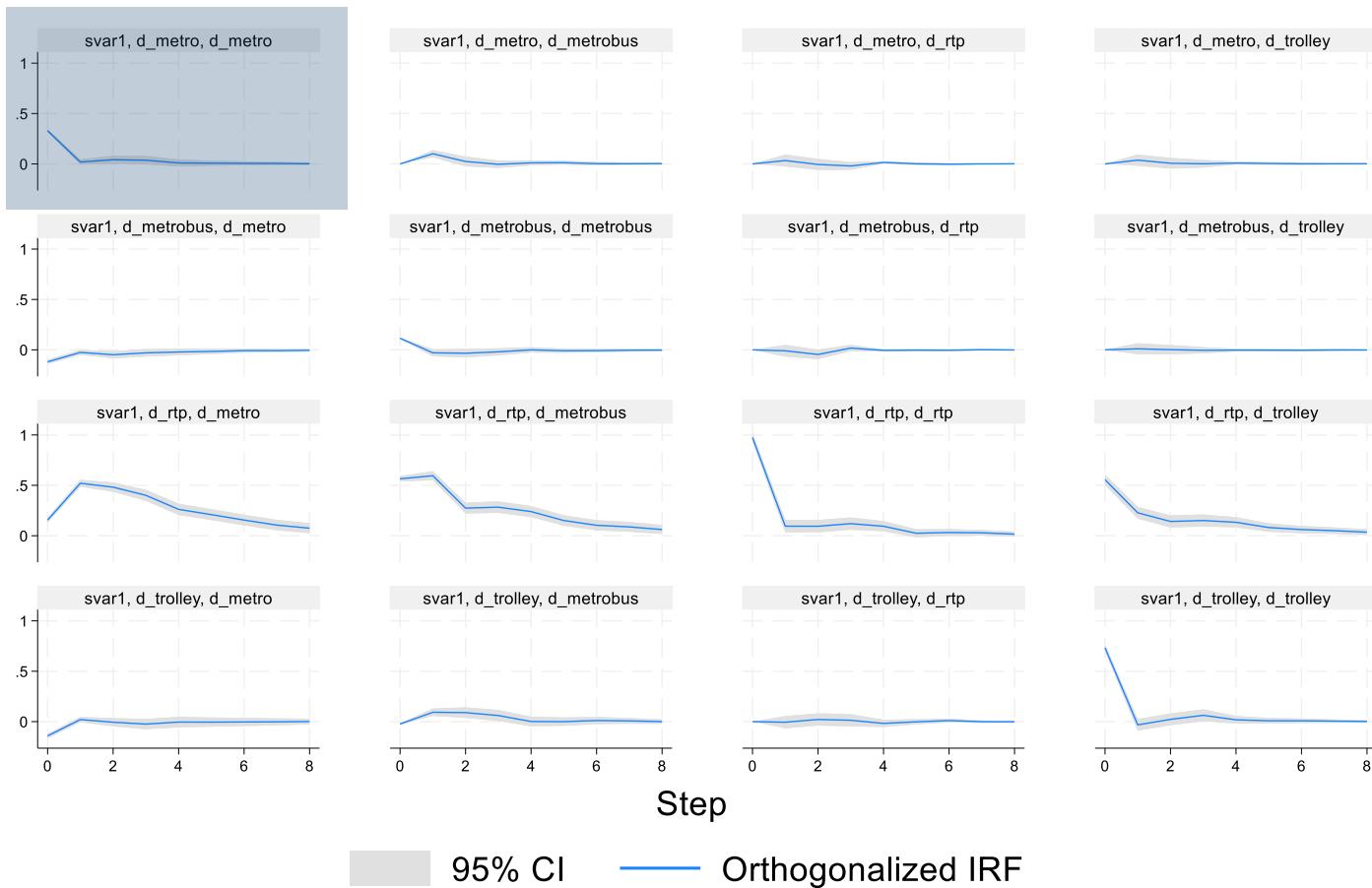
. irf create svar1
```

# IRF graphs



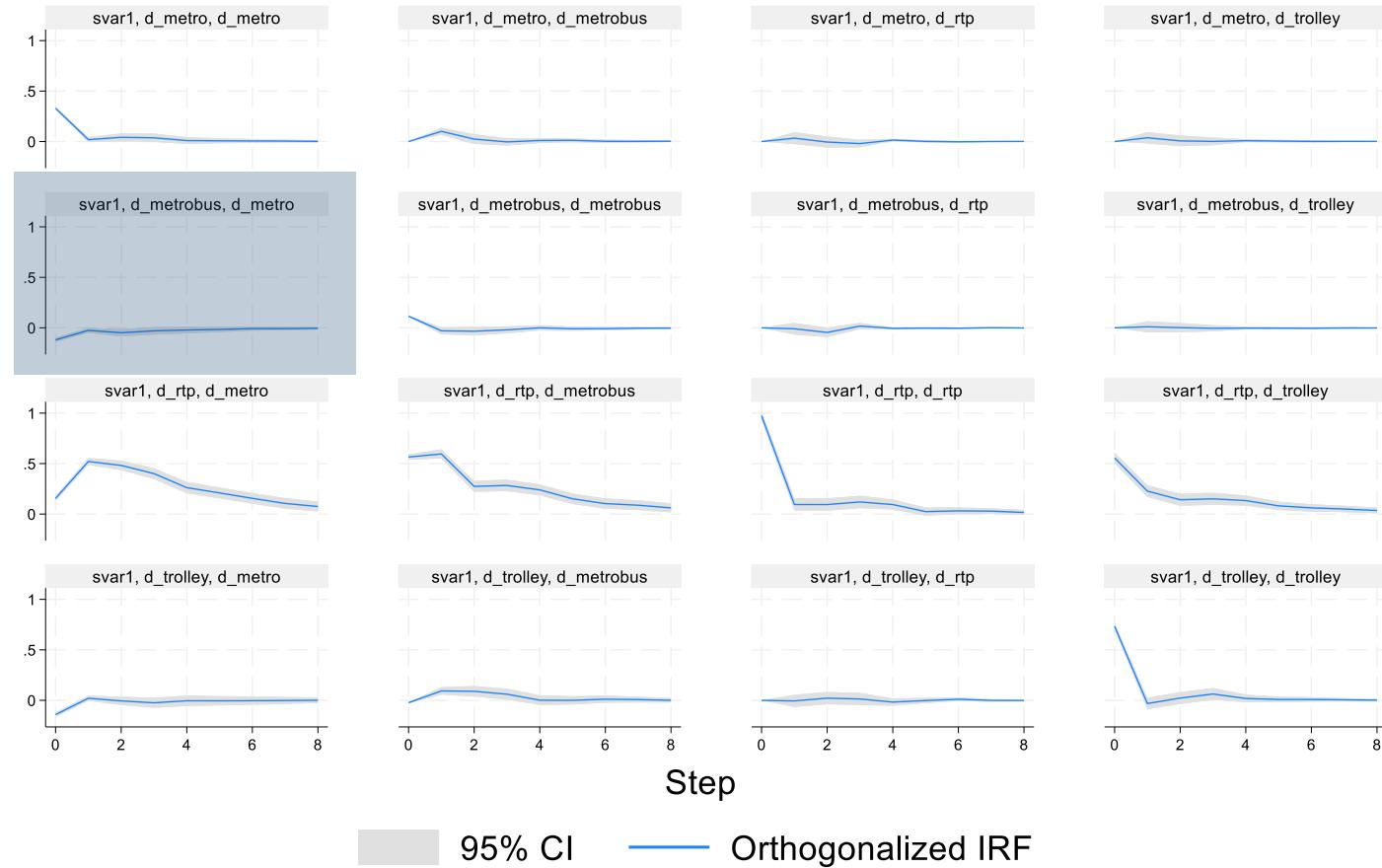
• `irf graph oirf`

# IRF graphs



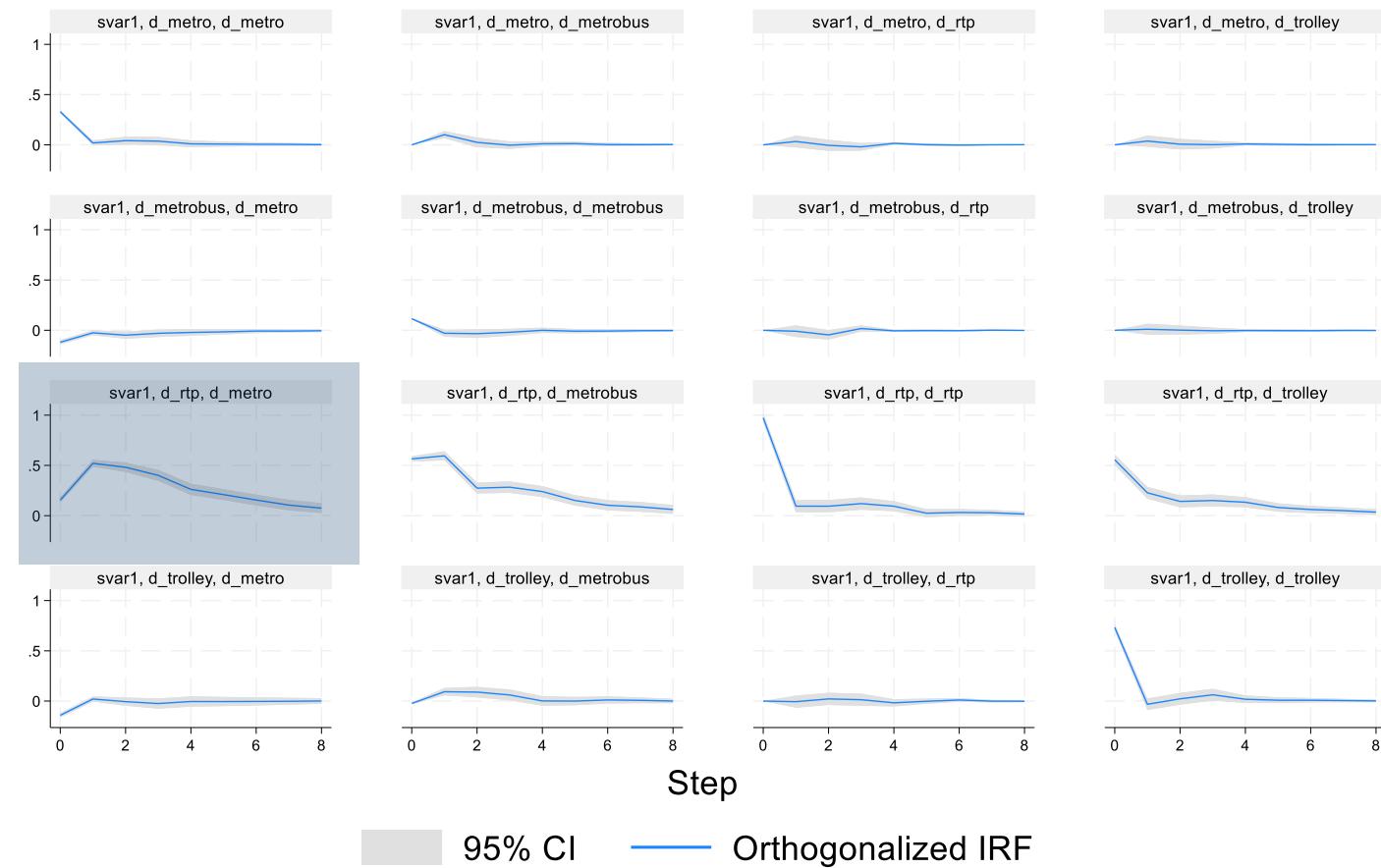
Graphs by irfname, impulse variable, and response variable

# IRF graphs



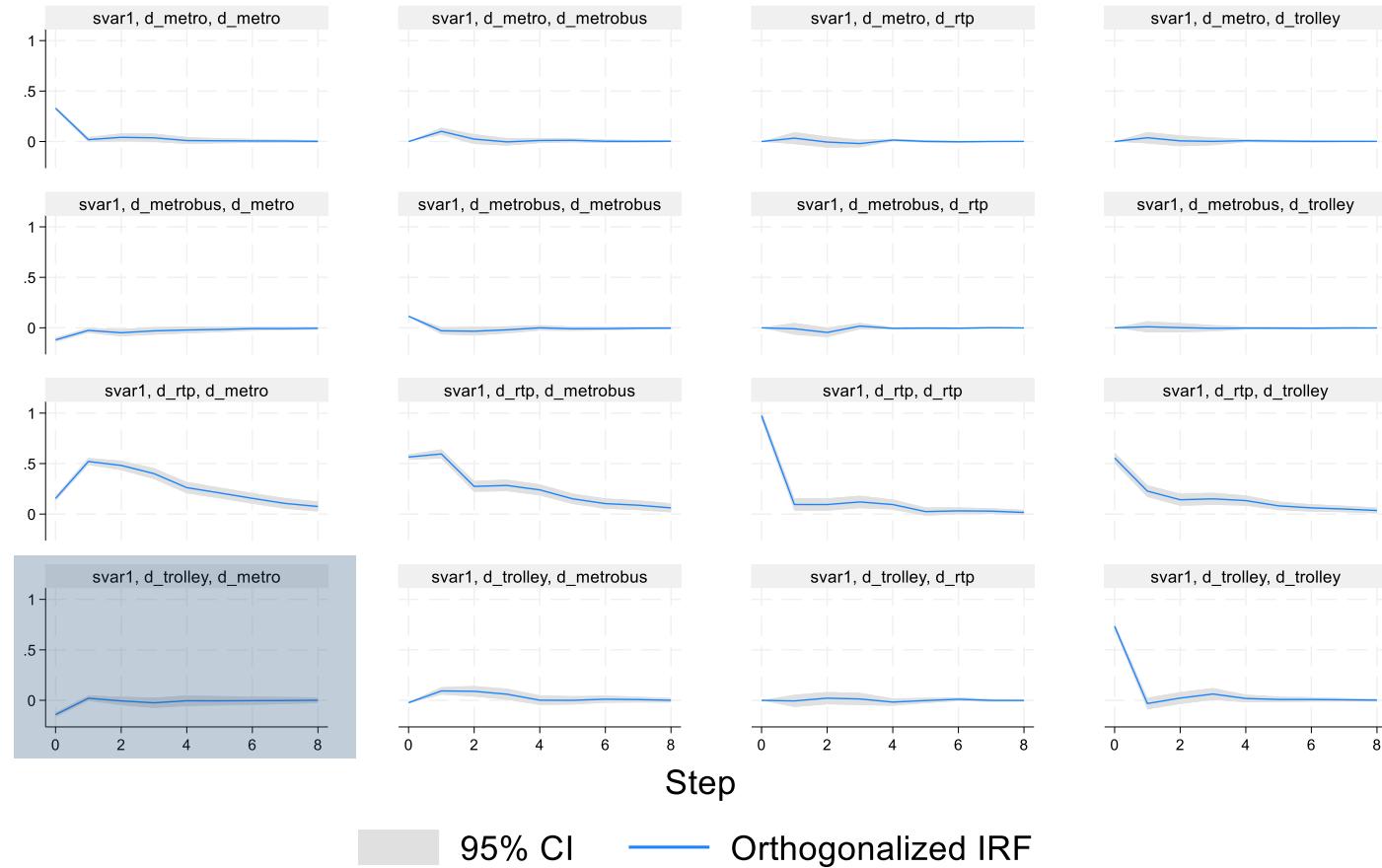
Graphs by irfname, impulse variable, and response variable

# IRF graphs



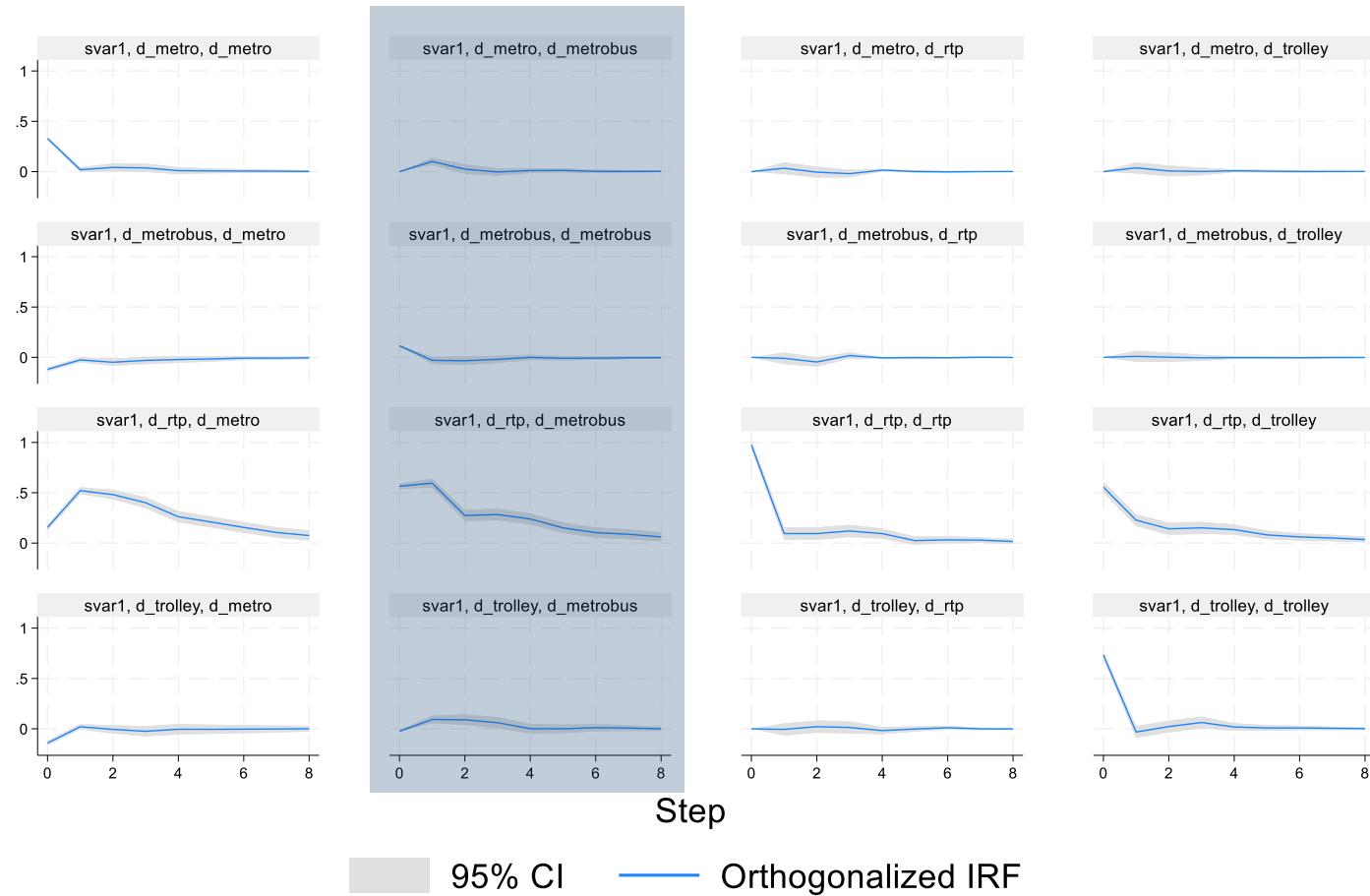
Graphs by irfname, impulse variable, and response variable

# IRF graphs

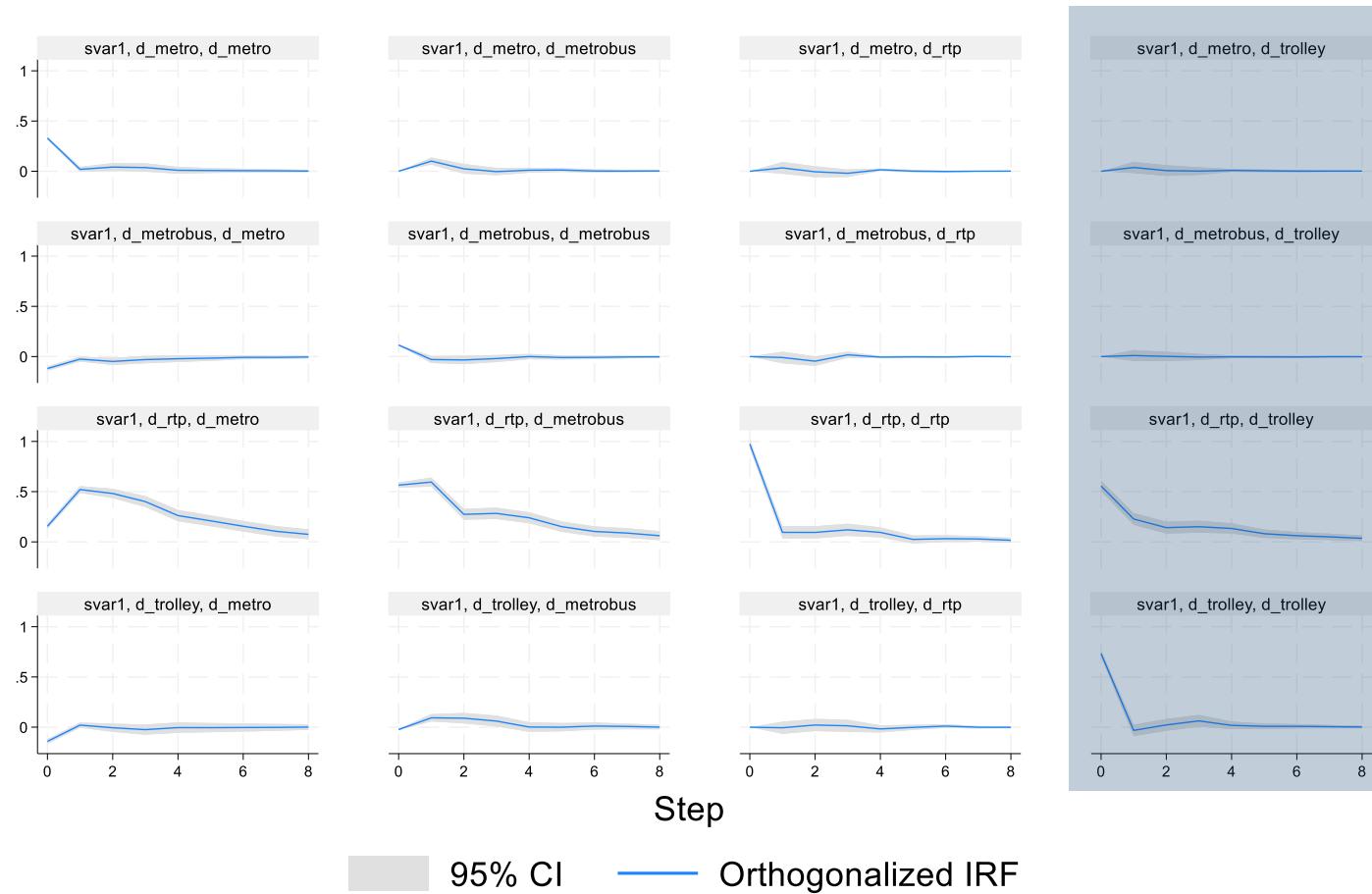


Graphs by irfname, impulse variable, and response variable

# IRF graphs

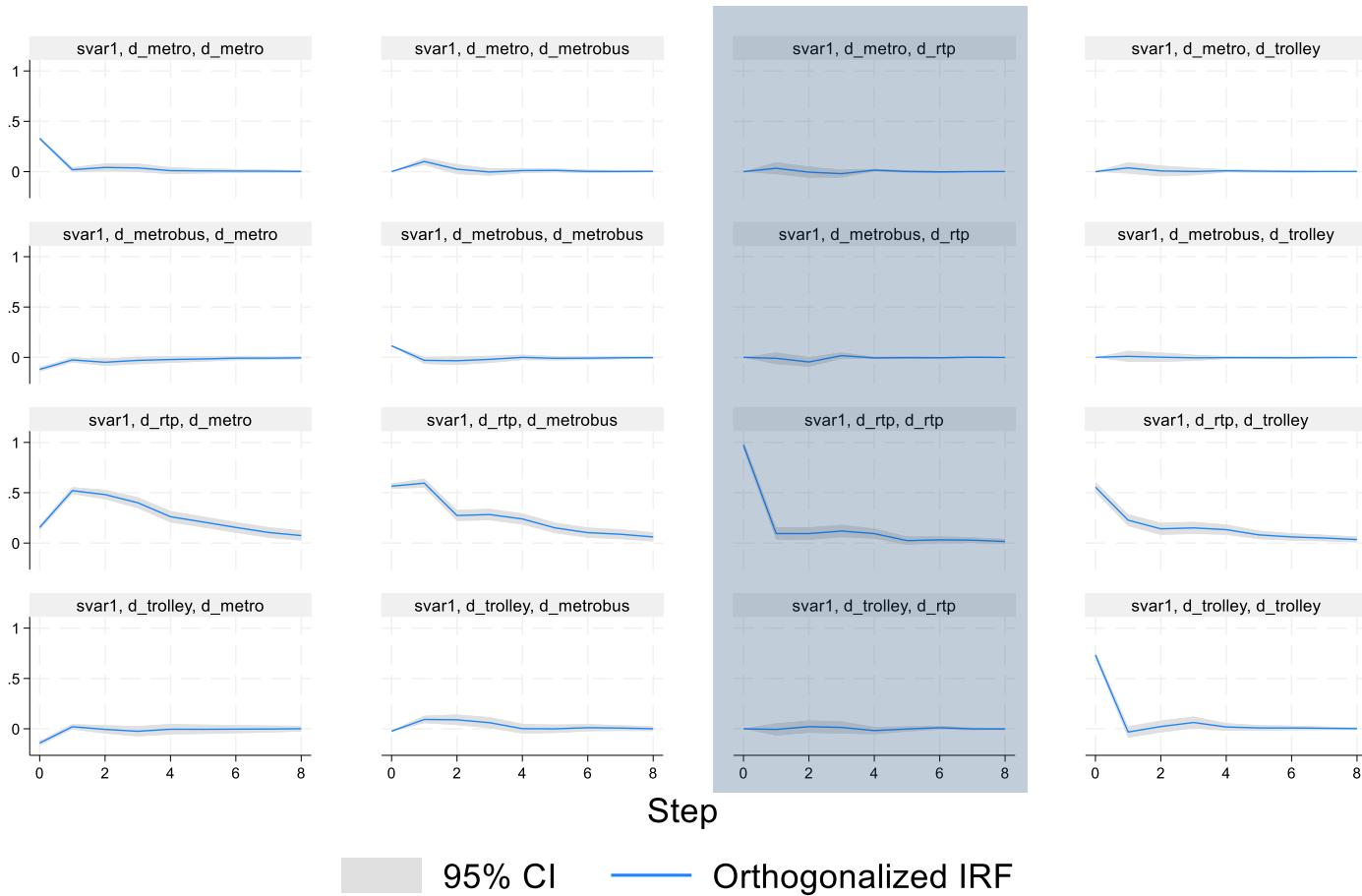


# IRF graphs



Graphs by irfname, impulse variable, and response variable

# IRF graphs



Graphs by irfname, impulse variable, and response variable

**Thank you for joining us!**

