

Spatial Dynamic Panel Data Models with Interactive Effects

Ongoing research agenda with several co-authors:
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2025 Stata Economics Virtual Symposium

Model

$$y_{i,t} = \alpha y_{i,t-1} + \psi \sum_{j=1}^N w_{i,j} y_{j,t} + \sum_{\ell=1}^K \beta_{\ell} x_{\ell,i,t} + \underbrace{\lambda_i' \mathbf{f}_t}_{u_{i,t}} + \varepsilon_{i,t}, \quad (1)$$
$$i = 1, \dots, N; \quad t = 1, \dots, T,$$

“State dependence”: Balestra-Nerlove 1966, Anderson-Hsiao 1982, Arellano-Bond 1991, Blundell-Bond 1998;

Spatial lag: “endogenous interactions” due to networks, peer effects, spillovers etc, e.g. Case 1991, Manski 1993, 1995, Fisher 1935, Tobler 1970, Elhorst 2014;

“Causal effects”: K idiosyncratic, time-varying *own* characteristics;

Nonlinear error components: “Latent Common Factors” / “Interactive Effects”; e.g., technological disruptions, energy price shocks, geopolitical conflicts, regulatory changes, financial crises, macro policies etc: e.g. Pesaran 2006, Bai 2009, Sarafidis-Wansbeek 2021.

Comparison with Two-Way (or additive) Effects

The Two-Way Effects model assumes error components enter additively:
 $u_{i,t} = \eta_i + \tau_t + \varepsilon_{i,t}$. But this is a special case of the interactive effects structure.

$$r = 2, \lambda_i = (\eta_i, 1)' \text{ \& } \mathbf{f}_t = (1, \tau_t)' \Rightarrow \lambda_i' \mathbf{f}_t = \eta_i + \tau_t.$$

Neither first-differencing nor the within transformation will remove the common factor component.

The use of multiplicative time dummies at a group level (e.g. using the absorb function in Stata) is not warranted.

To illustrate, let $r = 1$ and $u_{i,t} = \lambda_i f_t + \varepsilon_{i,t}$.

We can rewrite this as $u_{i,t} = u_{i,t} \pm \lambda_{g_i} f_t = \lambda_{g_i} f_t + \varepsilon_{i,t} + (\lambda_i - \lambda_{g_i}) f_t$

$\therefore$ Covariates remain correlated w.r.t. the nonlinear error component.

Technical Issues

$$y_{i,t} = \alpha_i y_{i,t-1} + \psi_i \sum_{j=1}^N w_{i,j} y_{j,t} + \mathbf{x}'_{i,t} \boldsymbol{\beta}_i + \boldsymbol{\lambda}'_i \mathbf{f}_t + \varepsilon_{i,t}.$$

- 3 potential sources of endogeneity
 - ▶ Lagged dependent variable is endogenous by construction;
 - ▶ Spatial lag variable is endogenous by construction;
 - ▶ Covariates may also be correlated with the composite error;
- “How many factors?”
- “Incidental parameters problem”
- “Asymptotic analysis with $N, T \rightarrow \infty$ jointly”
- “Heterogeneous Slope Parameters”

Econometric literature: large N , T asymptotics

$$y_{i,t} = \alpha_i y_{i,t-1} + \psi_i \sum_{j=1}^N w_{i,j} y_{j,t} + \mathbf{x}'_{i,t} \boldsymbol{\beta}_i + \boldsymbol{\lambda}'_i \mathbf{f}_t + \varepsilon_{i,t}$$

Dynamic panels with additive fixed effects: ($\psi = 0$, $\boldsymbol{\lambda}'_i \mathbf{f}_t = \eta_i + \tau_t$) e.g. Hahn-Kuersteiner 2002, Alvarez-Arellano 2003, Hayakawa 2015;

Spatial panels with additive fixed effects: ($\alpha = 0$, $\boldsymbol{\lambda}'_i \mathbf{f}_t = \eta_i + \tau_t$) e.g. Yu-De Jong-Lee 2008, Korniotis 2010, Lee-Yu 2014;

Dynamic panels with “interactive fixed effects”: ($\psi = 0$) e.g. Chudik-Pesaran 2015, Moon-Weidner 2017, Juodis-Sarafidis 2021;

Present agenda sits on the intersection of the above strands of literature. Most approaches available are based on QMLE (Shi-Lee 2017, Bai-Li 2021);

No literature on spatial, dynamic panels with **heterogeneous coefficients**.

Contribution (Homogeneous case)

- Cui-Sarafidis-Yamagata 2023 put forward a two-stage spatial IV (2SIV) estimator; consistent and asy. normal under $N, T \rightarrow \infty$, s.t. $N/T \rightarrow c, 0 < c < \infty$;
- 2SIV is **linear and easy to compute**;
In contrast, for QMLE, estimation of the Jacobian matrix of likelihood function is computational intensive. MC: for $N = T = 200$, QMLE is 60 times slower.
- 2SIV is **asymptotically unbiased**;
QMLE suffers from asy. bias due to incidental parameters $\Rightarrow$ severe size distortions. Bias-correction is based on true # of factors;
- 2SIV can accommodate **endogenous regressors** (provided there are exogenous instruments available.)

Contribution cont. (Heterogeneous case)

- Chen-Cui-Sarafidis-Yamagata 2025 put forward a Mean Group spatial IV estimator; consistent and asy. normal under N , $T \rightarrow \infty$, s.t. $N/T^2 \rightarrow 0$;
- MGIV is given by

$$\hat{\theta}_{MGIV} = \frac{1}{N} \sum_{i=1}^N \hat{\theta}_i,$$

where $\hat{\theta}_i = (\hat{\alpha}_i, \hat{\psi}_i, \hat{\beta}_i')'$.

- There exist no alternative methods in this case.
- Both 2SIV and MGIV are now available in Stata with the *spxtivdfreg* command
- *net install xtivdfreg, from(<https://www.kripfganz.de/stata>) replace*

Generalisations

$$y_{i,t} = \alpha y_{i,t-1} + \psi \sum_{j=1}^N w_{i,j} y_{j,t} + \mathbf{x}'_{i,t} \boldsymbol{\beta} + \boldsymbol{\lambda}'_i \mathbf{f}_t + \varepsilon_{i,t} \\ + \psi_1 \sum_{j=1}^N w_{i,j} y_{j,t-1} + \gamma' \sum_{j=1}^N w_{i,j} \mathbf{x}_{j,t} + \sum_{s=2}^p \alpha_s y_{i,t-s}.$$

“Spatial-time lag” (sometimes “contagion”)

“Exogenous network effects”, or “contextual effects” (the “Spatial Durbin model”)

“AR process of order > 1 ”

Could also think of “spatially-correlated unobservables”, through ε_{it} .
But not jointly identified (Manski, 1993).

Model in stacked form

Stacking the T observations for each i yields

$$\mathbf{y}_i = \alpha \mathbf{y}_{i,-1} + \psi \sum_{j=1}^N w_{i,j} \mathbf{y}_j + \mathbf{X}_i \boldsymbol{\beta} + \mathbf{F} \boldsymbol{\lambda}_i + \boldsymbol{\varepsilon}_i; \quad (2)$$

or

$$\mathbf{y}_i = \mathbf{C}_i \boldsymbol{\theta} + \mathbf{u}_i, \quad (3)$$

where $\mathbf{C}_i = (\mathbf{y}_{i,-1}, \sum_{j=1}^N w_{i,j} \mathbf{y}_j, \mathbf{X}_i)$, $\boldsymbol{\theta} = (\alpha, \psi, \boldsymbol{\beta}')'$ and $\mathbf{u}_i = \mathbf{F} \boldsymbol{\lambda}_i + \boldsymbol{\varepsilon}_i$.

We assume

$$\mathbf{X}_i = \mathbf{F}_x \boldsymbol{\Gamma}_i + \mathbf{V}_i. \quad (4)$$

$\mathbf{F}$ & $\mathbf{F}_x$ can overlap, be identical or completely different. Similarly, $\boldsymbol{\lambda}_i$ and $\boldsymbol{\Gamma}_i$ can be mutually correlated.

Outline of two-stage IV procedure (Stage 1)

Remove $\mathbf{F}_x$ from $\mathbf{X}$ (i.e. we “defactor” $\mathbf{X}$) using PCA (e.g. Bai 2003);

Let $\mathbf{M}_{\hat{\mathbf{F}}_{x,-\tau}} = \mathbf{I}_T - \hat{\mathbf{F}}_{x,-\tau} (\hat{\mathbf{F}}'_{x,-\tau} \hat{\mathbf{F}}_{x,-\tau})^{-1} \hat{\mathbf{F}}'_{x,-\tau}$, where

$$\left(\frac{1}{NT} \sum_{i=1}^N \mathbf{x}_{i,-\tau} \mathbf{x}'_{i,-\tau} \right) \hat{\mathbf{F}}_{x,-\tau} = \hat{\mathbf{F}}_{x,-\tau} \hat{\boldsymbol{\Omega}}_{\tau}. \quad (5)$$

We formulate $\hat{\mathbf{Z}}_i$ based on defactored covariates:

$$\underbrace{\hat{\mathbf{Z}}_i}_{T \times 3K} = \begin{pmatrix} \mathbf{M}_{\hat{\mathbf{F}}_x} \mathbf{x}_i, & \mathbf{M}_{\hat{\mathbf{F}}_{x,-1}} \mathbf{x}_{i,-1}, & \sum_{j=1}^N w_{ij} \mathbf{M}_{\hat{\mathbf{F}}_x} \mathbf{x}_j \end{pmatrix}, \quad (6)$$

and estimate θ using

$$\hat{\theta}_{1SIV} = \left(\hat{\mathbf{A}}' \hat{\mathbf{B}}^{-1} \hat{\mathbf{A}} \right)^{-1} \hat{\mathbf{A}}' \hat{\mathbf{B}}^{-1} \hat{\mathbf{c}}, \quad (7)$$

$$\hat{\mathbf{A}} = \frac{1}{NT} \sum_{i=1}^N \hat{\mathbf{Z}}'_i \mathbf{c}_i; \quad \hat{\mathbf{B}} = \frac{1}{NT} \sum_{i=1}^N \hat{\mathbf{Z}}'_i \hat{\mathbf{Z}}_i; \quad \hat{\mathbf{c}} = \frac{1}{NT} \sum_{i=1}^N \hat{\mathbf{Z}}'_i \mathbf{y}_i.$$

Outline of two-stage IV procedure (Stage 2)

Project out $\mathbf{F}$ from $\mathbf{u}_i$ ($\mathbf{y}_i$) using the 1SIV residuals, $\hat{\mathbf{u}}_i = \mathbf{y}_i - \mathbf{C}_i \hat{\boldsymbol{\theta}}_{1SIV}$;

Next, run IV regression again using the same instruments:

$$\hat{\boldsymbol{\theta}}_{2SIV} = (\tilde{\mathbf{A}}' \tilde{\mathbf{B}}^{-1} \tilde{\mathbf{A}})^{-1} \tilde{\mathbf{A}}' \tilde{\mathbf{B}}^{-1} \tilde{\mathbf{c}} \quad (8)$$

$$\tilde{\mathbf{A}} = \frac{1}{NT} \sum_{i=1}^N \hat{\mathbf{Z}}_i' \mathbf{M}_{\hat{\mathbf{F}}} \mathbf{C}_i, \tilde{\mathbf{B}} = \frac{1}{NT} \sum_{i=1}^N \hat{\mathbf{Z}}_i' \mathbf{M}_{\hat{\mathbf{F}}} \hat{\mathbf{Z}}_i, \tilde{\mathbf{c}} = \frac{1}{NT} \sum_{i=1}^N \hat{\mathbf{Z}}_i' \mathbf{M}_{\hat{\mathbf{F}}} \mathbf{y}_i.$$

$\hat{\boldsymbol{\theta}}_{2SIV}$ is free from asy. bias. QMLE is subject to two sources of asy. bias: (i) “Nickell bias” due to the presence of $\mathbf{y}_{i,-1}$; (ii) bias due to the defactoring of $\mathbf{X}_i$; estimation error in $\hat{\mathbf{F}}$ depends on $\mathbf{U}_i$, and this feeds in $\mathbf{X}_i$ due to defactoring. That is, defactored regressors are asy. correlated with the error term.

Assumption (idiosyncratic error in $\mathbf{y}$)

$\varepsilon_{i,t}$ is independently distributed across i and over t , with mean zero, $\mathbb{E}(\varepsilon_{i,t}^2) = \sigma_\varepsilon^2 > 0$ and $\mathbb{E}|\varepsilon_{i,t}|^{8+\delta} \leq C < \infty$ for some $\delta > 0$.

Assumption (idiosyncratic error in $\mathbf{x}$)

- 1 $\mathbf{v}_{i,t}$ is group-wise independent from $\varepsilon_{i,t}$, $\mathbb{E}(\mathbf{v}_{i,t}) = 0$ and $\mathbb{E}\|\mathbf{v}_{i,t}\|^{8+\delta} \leq C < \infty$;
- 2 Let $\Sigma_{i,j,s,t} \equiv \mathbb{E}(\mathbf{v}_{i,s}\mathbf{v}_{j,t}')$. There exist $\bar{\sigma}_{i,j}$ and $\tilde{\sigma}_{s,t}$, $\|\Sigma_{i,j,s,t}\| \leq \bar{\sigma}_{i,j}$ for all (s, t) , and $\|\Sigma_{i,j,s,t}\| \leq \tilde{\sigma}_{s,t}$ for all (i, j) , such that

$$\frac{1}{N} \sum_{i=1}^N \sum_{j=1}^N \bar{\sigma}_{i,j} \leq C < \infty, \quad \frac{1}{T} \sum_{s=1}^T \sum_{t=1}^T \tilde{\sigma}_{s,t} \leq C < \infty,$$

$$\frac{1}{NT} \sum_{i=1}^N \sum_{j=1}^N \sum_{s=1}^T \sum_{t=1}^T \|\Sigma_{i,j,s,t}\| \leq C < \infty.$$

Assumption (factors)

$\mathbb{E}\|\mathbf{f}_{x,t}\|^4 \leq C < \infty$, $T^{-1}\mathbf{F}'_x\mathbf{F}_x \xrightarrow{p} \Sigma_{F_x} > 0$ as $T \rightarrow \infty$ for some non-random positive definite matrix Σ_{F_x} . $\mathbb{E}\|\mathbf{f}_t\|^4 \leq C < \infty$, $T^{-1}\mathbf{F}'\mathbf{F} \xrightarrow{p} \Sigma_F > 0$ as $T \rightarrow \infty$ for some non-random positive definite matrix Σ_F . $\mathbf{f}_{x,t}$ and $\mathbf{f}_t$ are group-wise independent from $\mathbf{v}_{i,t}$ and $\varepsilon_{i,t}$.

Assumption (factor loadings)

$\Gamma_i \sim \text{i.i.d}(\mathbf{0}, \Sigma_\Gamma)$, $\lambda_i \sim \text{i.i.d}(\mathbf{0}, \Sigma_\lambda)$, where Σ_Γ and Σ_λ are positive definite. $\mathbb{E}\|\Gamma_i\|^4 \leq C < \infty$, $\mathbb{E}\|\lambda_i\|^4 \leq C < \infty$. In addition, Γ_i and λ_i are independent groups from $\varepsilon_{i,t}$, $\mathbf{v}_{i,t}$, $\mathbf{f}_{x,t}$ and $\mathbf{f}_t$.

Assumption (spatial weighting matrix)

- 1 All diagonal elements of $\mathbf{W}_N$ are zeros;
- 2 The row and column sums of the matrices $\mathbf{W}_N$ and $(\mathbf{I}_N - \psi \mathbf{W}_N)^{-1}$ are bounded uniformly in absolute value.

3

$$\sum_{\ell=0}^{\infty} \|[\alpha(\mathbf{I}_N - \psi \mathbf{W}_N)^{-1}]^{\ell}\|_{\infty} \leq C; \quad \sum_{\ell=0}^{\infty} \|[\alpha(\mathbf{I}_N - \psi \mathbf{W}_N)^{-1}]^{\ell}\|_1 \leq C$$

Assumption (identification)

- 1 $\bar{\mathbf{A}} = \text{plim}_{N,T \rightarrow \infty} \frac{1}{NT} \sum_{i=1}^N \mathbf{Z}_i' \mathbf{C}_i$ is fixed with full column rank, and $\bar{\mathbf{B}} = \text{plim}_{N,T \rightarrow \infty} \frac{1}{NT} \sum_{i=1}^N \mathbf{Z}_i' \mathbf{Z}_i$ is fixed and positive definite.
- 2 $\mathbb{E} \|T^{-1} \mathbf{Z}_i' \mathbf{Z}_i\|^{2+2\delta} \leq C < \infty$ and $\mathbb{E} \|T^{-1} \mathbf{Z}_i' \mathbf{C}_i\|^{2+2\delta} \leq C < \infty$ for all i, T .

1SIV - Asymptotic Properties

Proposition

Under Assumptions A-F, we have

$$\frac{1}{\sqrt{NT}} \sum_{i=1}^N \hat{\mathbf{z}}'_i \mathbf{u}_i = \frac{1}{\sqrt{NT}} \sum_{i=1}^N \mathbf{z}'_i \mathbf{u}_i + \sqrt{\frac{T}{N}} \mathbf{b}_1 + \sqrt{\frac{N}{T}} \mathbf{b}_2 + o_p(1).$$

Theorem

Under Assumptions A-F, as $N, T \rightarrow \infty$ such that $N/T \rightarrow c$, where $0 < c < \infty$, we have

$$\sqrt{NT} \left(\hat{\theta}_{1SIV} - \theta \right) = O_p(1). \quad (9)$$

2SIV - Asymptotic Properties

Theorem

Under Assumptions A-F, as $N, T \rightarrow \infty$ such that $N/T \rightarrow c$, where $0 < c < \infty$, $\hat{\theta}_{2SIV}$ is consistent and

$$\sqrt{NT} \left(\hat{\theta}_{2SIV} - \theta \right) \xrightarrow{d} N(\mathbf{0}, \Psi)$$

where $\Psi = \sigma_{\varepsilon}^2 \left(\mathbf{A}'_0 \mathbf{B}_0^{-1} \mathbf{A}_0 \right)^{-1}$, $\mathbf{A}_0 = \text{plim}_{N, T \rightarrow \infty} \mathbf{A}$, $\mathbf{B}_0 = \text{plim}_{N, T \rightarrow \infty} \mathbf{B}$, with

$$\mathbf{A} = \frac{1}{NT} \sum_{i=1}^N \mathbf{z}'_i \mathbf{C}_i, \mathbf{B} = \frac{1}{NT} \sum_{i=1}^N \mathbf{z}'_i \mathbf{z}_i.$$

Moreover, $\tilde{\Psi} - \Psi \xrightarrow{p} \mathbf{0}$ as $N, T \rightarrow \infty$, where $\tilde{\Psi} = \tilde{\sigma}_{\varepsilon}^2 \left(\tilde{\mathbf{A}}' \tilde{\mathbf{B}}^{-1} \tilde{\mathbf{A}} \right)^{-1}$.

Outline of MGIV procedure

We further assume that $\theta_i = \theta + \mathbf{e}_i$, where $\theta = (\alpha, \psi, \beta')'$ and $\mathbf{e}_i$ is a random i.i.d. error with mean zero and variance Σ_θ .

First, recover estimates of θ_i as follows:

$$\hat{\theta}_i = \left(\hat{\mathbf{A}}_i' \hat{\mathbf{B}}_i^{-1} \hat{\mathbf{A}}_i \right)^{-1} \hat{\mathbf{A}}_i' \hat{\mathbf{B}}_i^{-1} \hat{\mathbf{c}}_i,$$

where

$$\hat{\mathbf{A}}_i = T^{-1} \hat{\mathbf{Z}}_i' \mathbf{C}_i, \quad \hat{\mathbf{B}}_i = T^{-1} \hat{\mathbf{Z}}_i' \hat{\mathbf{Z}}_i, \quad \hat{\mathbf{c}}_i = T^{-1} \hat{\mathbf{Z}}_i' \mathbf{y}_i,$$

and $\hat{\mathbf{Z}}_i = (\mathbf{M}_{\hat{\mathbf{F}}} \mathbf{M}_{\hat{\mathbf{F}}-1} \mathbf{X}_{i,-1}, \sum_{j=1}^N w_{ij} \mathbf{M}_{\hat{\mathbf{F}}} \mathbf{X}_j, \mathbf{M}_{\hat{\mathbf{F}}} \mathbf{X}_i)$ as the instruments in the estimation of θ_i .

Subsequently, we construct the sample average of $\hat{\theta}_i$ as

$$\hat{\theta}_{MGIV} = \frac{1}{N} \sum_{i=1}^N \hat{\theta}_i.$$

MGIV - Asymptotic Properties

Theorem

Under aforementioned assumptions, as $N, T \rightarrow \infty$ such that $N/T^2 \rightarrow 0$, then $\hat{\theta}_{MGIV}$ is consistent for the population mean θ . If, it further holds that $N/T^{6/5} \rightarrow 0$, then $\hat{\theta}_{MGIV}$ has the following asymptotic distribution

$$\sqrt{N}(\hat{\theta}_{MGIV} - \theta) \xrightarrow{d} N(\mathbf{0}, \Sigma_{\theta}), \text{ as } N, T \rightarrow \infty.$$

- DGP for covariates: $x_{i,t} = \gamma_i' \mathbf{f}_t + v_{i,t}$;
 - Frequently employed in economics or econometrics (e.g. Pesaran et al. 2013, Westerlund-Urbain 2015, Hansen-Liao 2018 etc.)
- As least one element of β must not equal to zero;
- Endogeneity of $\mathbf{X}_i \Rightarrow$ use external instruments, e.g.
 $\tilde{\mathbf{Z}}_i = \tilde{\mathbf{F}}\tilde{\Gamma}_i + \tilde{\mathbf{V}}_i$;

Simulation Experiments - Design

$$y_{i,t} = \eta_i + \alpha y_{i,t-1} + \psi \sum_{j=1}^N w_{i,j} y_{j,t} + \sum_{\ell=1}^2 \beta_{\ell} x_{\ell,i,t} + \sum_{s=1}^{r_y} \lambda_{s,i} f_{s,t} + \varepsilon_{i,t}; \quad r_y = 3. \quad (10)$$

$$x_{\ell,i,t} = \mu_{\ell,i} + \sum_{s=1}^{r_x} \gamma_{\ell,s,i} f_{(x),s,t} + v_{\ell,i,t}; \quad r_x = 2; \quad i = 1, \dots, N; t = -49, \dots, T. \quad (11)$$

$$i = 1, \dots, N; t = -49, \dots, T.$$

$\varepsilon_{i,t}$, is non-normal and heteroskedastic across both i and t , such that $\varepsilon_{i,t} = \varsigma_{\varepsilon} \sigma_{i,t} (\epsilon_{i,t} - 1) / \sqrt{2}$, $\epsilon_{i,t} \sim i.i.d. \chi_1^2$, with $\sigma_{i,t}^2 = g_i \phi_t$, $g_i \sim i.i.d. \chi_2^2 / 2$, and $\phi_t = t/T$ for $t = 0, 1, \dots, T$ and unity otherwise.

All remaining time-varying error components are AR(1) processes with parameter equal to .5. All individual-specific error components are correlated, $\alpha_{\eta,\mu} = 0.5$.

We set $\varsigma_{\varepsilon}^2$ s.t. $\pi_u \in \{1/4, 3/4\}$. We set $\text{var}(v_{\ell it})$ s.t. $\text{SNR} = 4$. We set $\alpha = 0.4$, $\psi = 0.25$, and $\beta_1 = 3$ and $\beta_2 = 1$, following Bai (2009).

Variance estimator for 2SIV

In order to allow for cross-section and time series heteroskedasticity, the variance estimator for 2SIV is

$$\tilde{\Psi} = \left(\tilde{\mathbf{A}}' \tilde{\mathbf{B}}^{-1} \tilde{\mathbf{A}} \right)^{-1} \tilde{\mathbf{A}}' \tilde{\mathbf{B}}^{-1} \hat{\Omega} \tilde{\mathbf{B}}^{-1} \tilde{\mathbf{A}} \left(\tilde{\mathbf{A}}' \tilde{\mathbf{B}}^{-1} \tilde{\mathbf{A}} \right)^{-1}, \quad (12)$$

with

$$\hat{\Omega} = \frac{1}{NT} \sum_{i=1}^N \hat{\mathbf{z}}_i' \mathbf{M}_{\hat{\mathbf{H}}} \hat{\mathbf{u}}_i \hat{\mathbf{u}}_i' \mathbf{M}_{\hat{\mathbf{H}}} \hat{\mathbf{z}}_i, \quad (13)$$

and $\hat{\mathbf{u}}_i = \mathbf{y}_i - \mathbf{C}_i \hat{\theta}_{1SIV}$.

$$\hat{\mathbf{z}}_i = \left(\mathbf{M}_{\hat{\mathbf{F}}} \mathbf{X}_i, \quad \mathbf{M}_{\hat{\mathbf{F}}_{-1}} \mathbf{X}_{i,-1}, \quad \mathbf{M}_{\hat{\mathbf{F}}} \sum_{j=1}^N w_{ij} \mathbf{X}_j, \quad \mathbf{M}_{\hat{\mathbf{F}}_{-1}} \sum_{j=1}^N w_{ij} \mathbf{X}_{j,-1} \right). \quad (14)$$

Results (homogeneous case)

Table 1A. RMSE, $\pi_u = 3/4$

$\alpha(= 0.4)$	2SIV			QMLE		
τ	1	2	4	1	2	4
$N = 100\tau, T = 25\tau$	.017	.007	.004	.014	.006	.003
$N = 25\tau, T = 100\tau$	.014	.007	.003	.008	.004	.002
$N = 50\tau, T = 50\tau$	.015	.003	.003	.009	.005	.002

$\psi(= 0.25)$	2SIV			QMLE		
τ	1	2	4	1	2	4
$N = 100\tau, T = 25\tau$	.019	.008	.004	.033	.015	.006
$N = 25\tau, T = 100\tau$	.017	.008	.004	.023	.010	.005
$N = 50\tau, T = 50\tau$	.017	.008	.004	.025	.011	.005

$\beta_2(= 1)$	2SIV			QMLE		
τ	1	2	4	1	2	4
$N = 100\tau, T = 25\tau$	.066	.025	.012	.093	.029	.012
$N = 25\tau, T = 100\tau$	.049	.025	.012	.118	.040	.014
$N = 50\tau, T = 50\tau$	.050	.024	.012	.086	.028	.012

Results ctd

Table 1B. ARB, $\pi_u = 3/4$, $ARB \equiv \left(|\hat{\theta}_\ell - \theta_\ell| / \theta_\ell \right) \times 100$

$\alpha(= 0.4)$	2SIV			QMLE		
τ	1	2	4	1	2	4
$N = 100\tau$, $T = 25\tau$	.082	.104	.054	2.52	1.08	.551
$N = 25\tau$, $T = 100\tau$	.116	.033	.008	.169	.087	.080
$N = 50\tau$, $T = 50\tau$	.074	.026	.017	.870	.493	.225

$\psi(= 0.25)$	2SIV			QMLE		
τ	1	2	4	1	2	4
$N = 100\tau$, $T = 25\tau$	.119	.112	.080	.216	.159	.113
$N = 25\tau$, $T = 100\tau$	.054	.009	.016	.156	.226	.007
$N = 50\tau$, $T = 50\tau$	.218	.039	.012	.026	.092	.001

$\beta_2(= 1)$	2SIV			QMLE		
τ	1	2	4	1	2	4
$N = 100\tau$, $T = 25\tau$	.947	.087	.039	6.41	1.35	.379
$N = 25\tau$, $T = 100\tau$	.043	.043	.003	7.10	1.81	.361
$N = 50\tau$, $T = 50\tau$	.222	.023	.023	5.18	1.15	.228

Results ctd

Table 1C. Size (nominal size = 5%), $\pi_u = 3/4$

$\alpha(= 0.4)$	2SIV			QMLE		
τ	1	2	4	1	2	4
$N = 100\tau, T = 25\tau$	.065	.059	.052	.361	.293	.286
$N = 25\tau, T = 100\tau$	.084	.066	.048	.138	.085	.079
$N = 50\tau, T = 50\tau$	.052	.056	.053	.146	.121	.109

$\psi(= 0.25)$	2SIV			QMLE		
τ	1	2	4	1	2	4
$N = 100\tau, T = 25\tau$	.062	.051	.052	.392	.258	.134
$N = 25\tau, T = 100\tau$	.094	.062	.054	.156	.078	.070
$N = 50\tau, T = 50\tau$	.076	.060	.054	.213	.139	.068

$\beta_2(= 1)$	2SIV			QMLE		
τ	1	2	4	1	2	4
$N = 100\tau, T = 25\tau$	.109	.057	.055	.415	.142	.079
$N = 25\tau, T = 100\tau$	.086	.074	.059	.531	.306	.134
$N = 50\tau, T = 50\tau$	.063	.052	.050	.369	.156	.090

Spillovers and Drivers of U.S. Population Growth

Kripfganz-Sarafidis 2025 specify:

$$\Delta y_{i,t} = \delta_i y_{i,t-1} + \psi_i \sum_{j=1}^N w_{i,j} \Delta y_{j,t} + \sum_{\ell=1}^4 \beta_{\ell,i} x_{\ell,i,t} + \lambda_i \mathbf{f}_t + \eta_i + \tau_t + \varepsilon_{i,t}, \quad (15)$$

$i = 1, \dots, N(= 49)$ and $t = 1, \dots, T(= 52)$, i.e. 1966 - 2017.

$\Delta y_{i,t} \equiv \ln(pop_{i,t}) - \ln(pop_{i,t-1})$: population growth;

$y_{i,t-1} \equiv \ln(pop_{i,t-1})$: lagged level of logged population;

$\Delta y_{j,t} \equiv \ln(pop_{j,t})$: population growth of state j ;

$x_{1,i,t} \equiv TFP_{i,t}$: "Total Factor Productivity";

$x_{2,i,t} \equiv \ln(amenities)_{i,t}$: logged "amenities";

$x_{3,i,t} \equiv \ln(income_{i,t})$: logged labour income;

$x_{4,i,t} \equiv \ln(MigCost)_{i,t}$: logged migration frictions.

$\mathbf{f}_t$:= nationwide demographic/institutional shocks (changes in fertility/aging patterns, shifts in federal immigration policy, national housing and credit cycles).

δ_i := conditional convergence: pop. converges (diverges) if $\delta_i < 0$ ($\delta_i > 0$) $\forall i$.

Network Specification

Our baseline model estimates $\mathbf{W}$ from the data using the method of Juodis-Kapetanios-Sarafidis 2025.

We also consider contiguity and distance-based networks:

$$w_{i,j} = \begin{cases} 1, & \text{if } j \text{ shares common border with } i \\ 0, & \text{otherwise,} \end{cases} \quad (16)$$

and

$$w_{i,j} = \begin{cases} 1/d_{i,j}, & \text{if } d_{i,j} \leq c \\ 0, & \text{otherwise,} \end{cases} \quad (17)$$

where c denotes the c th percentile of the empirical distribution of $d_{i,j}$.

Finally, we set $w_{i,j,t} = 1/(\text{trade-inflows})_{i,j,t}$, where $(\text{trade-inflows})_{i,j,t}$ represents the value of trade inflows from state j to state i at time t .

Instruments & Marginal Effects

We use the following instruments:

$$\hat{\mathbf{Z}}_i = \left(\mathbf{M}_{\hat{\mathbf{F}}} \mathbf{X}_i, \mathbf{M}_{\hat{\mathbf{F}}} \mathbf{M}_{\hat{\mathbf{F}}_{-1}} \mathbf{X}_{i,-1}, \mathbf{M}_{\hat{\mathbf{F}}} \mathbf{M}_{\hat{\mathbf{F}}_{-2}} \mathbf{X}_{i,-2}, \right. \\ \left. \mathbf{M}_{\hat{\mathbf{F}}} \sum_{j=1}^N w_{i,j} \mathbf{X}_j, \mathbf{M}_{\hat{\mathbf{F}}} \mathbf{M}_{\hat{\mathbf{F}}_{-1}} \sum_{j=1}^N w_{i,j} \mathbf{X}_{j,-1}, \mathbf{M}_{\hat{\mathbf{F}}} \mathbf{M}_{\hat{\mathbf{F}}_{-2}} \sum_{j=1}^N w_{i,j} \mathbf{X}_{j,-2} \right). \quad (18)$$

Distinguish among **direct, indirect and total effects**:

$$\mathbf{y}_{(t)} = [\mathbf{I}_N - \psi \mathbf{W}]^{-1} \left(\delta \mathbf{y}_{(t-1)} + \sum_{\ell=1}^k \beta_{\ell} \mathbf{x}_{\ell(t)} + \mathbf{u}_{(t)} \right), \quad (19)$$

$$\left[\frac{\partial E(\mathbf{y})}{\partial x_{\ell 1}} \dots \frac{\partial E(\mathbf{y})}{\partial x_{\ell N}} \right] = [\mathbf{I}_N - \psi \mathbf{W}]^{-1} \beta_{\ell}. \quad (20)$$

spxtivdfreg command in Stata

Kripfganz, S. and V. Sarafidis (2025). [Estimating Spatial Dynamic Panel Data Models with Common Factors](#), *Journal of Statistical Software*, 113(6), 1–27.

For time-invariant networks, we specify:

```
spxtivdfreg D.lnPop L.lnPop TFP Amenity  
lnLaborInc_pc MigTradeCost, absorb(statefp  
year) splag spmatrix("W_contiguity.xlsx",  
import) iv(TFP Amenity lnLaborInc_pc  
MigTradeCost, splags lag(2)) mg factmax(4)
```

For time-varying networks we use:

```
spxtivdfreg D.lnPop L.lnPop TFP Amenity  
lnLaborInc_pc MigTradeCost, absorb(statefp  
year) splag spmatrix("W*_trade.xlsx", import)  
iv(TFP Amenity lnLaborInc_pc MigTradeCost,  
splags lag(2)) mg factmax(4)
```

spxtivdfreg command in Stata

If we want to include: (i) **spatial-time lags**; (ii) **spatial lags of covariates (SDM)**; and (iii) **lags of the dependent variable**, we specify:

```
spxtivdfreg D.lnPop L.lnPop TFP Amenity  
lnLaborInc_pc MigTradeCost, absorb(statefp  
year) splag sptlags(#) spindepvars(varlist)  
tlags(#) spmatrix("W_contiguity.xlsx", import)  
iv(TFP Amenity lnLaborInc_pc MigTradeCost,  
splags lag(2)) mg factmax(4)
```

The command is very flexible, as it allows: defactoring individual covariates (useful for common covariates without cross-sectional variation), saving individual-specific estimated coefficients, computing direct/indirect/total effects, computing spillins/spillouts, and many other options.

Table 1: Homogeneous (2SIV) Slope Coefficients

	2SIV					
	$\widehat{W}$	W_1	W_2	W_3	W_4	W_5
$y_{i,t-1}$ (lagged population)	-0.016*** (0.006)	-0.022*** (0.005)	-0.014*** (0.004)	-0.019*** (0.005)	-0.025*** (0.005)	-0.025*** (0.005)
$x_{1,i,t}$ (TFP)	0.000 (0.001)	0.002 (0.001)	0.002** (0.001)	0.003** (0.001)	0.002** (0.001)	0.001 (0.001)
$x_{2,i,t}$ (amenities)	0.005*** (0.000)	0.006*** (0.001)	0.006*** (0.000)	0.006*** (0.000)	0.007*** (0.000)	0.006*** (0.000)
$x_{3,i,t}$ (labour income)	0.038*** (0.004)	0.030*** (0.004)	0.033*** (0.005)	0.031*** (0.005)	0.032*** (0.003)	0.033*** (0.004)
$x_{4,i,t}$ (migration cost)	-0.002*** (0.000)	-0.002*** (0.000)	-0.002*** (0.000)	-0.002*** (0.000)	-0.002*** (0.000)	-0.002*** (0.000)
$\sum_{j=1}^N w_{i,j} \Delta y_{j,t}$ (spatial lag)	0.335*** (0.038)	0.083*** (0.013)	0.169*** (0.037)	0.135*** (0.034)	0.230* (0.125)	0.538*** (0.141)
N	49	49	49	49	49	49
χ^2_J	36.504	35.064	33.895	33.261	34.584	34.678
p_J	0.006	0.009	0.013	0.016	0.011	0.010
r_x	2	2	2	2	2	2
r_y	1	1	1	1	1	1
ρ	0.614	0.702	0.745	0.744	0.739	0.700

$\widehat{W}$ denotes the data-driven network obtained based on Juodis-Kapetanios-Sarafidis 2025. W_1 is contiguity; W_2 – W_3 are inverse-distance (10th/5th percentile cutoffs); W_4 – W_5 are trade-based (time-averaged/time-varying).

Heterogeneity in Conditional Convergence

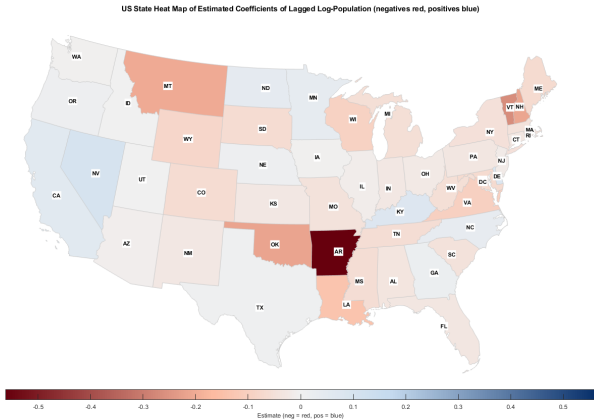


Figure: U.S. Heat Map of Estimated Coefficients of Lagged Log-Population (negatives red, positives blue).

Average Marginal Effects - Direct/Indirect

	MGIV					
	$\hat{W}$	W_1	W_2	W_3	W_4	W_5
Direct effects						
Lagged population	-0.051*** (0.015)	-0.046*** (0.013)	-0.048*** (0.013)	-0.050*** (0.014)	-0.050*** (0.014)	-0.052 —
TFP	0.005** (0.003)	0.001 (0.003)	0.003 (0.003)	0.003 (0.003)	0.005 (0.004)	0.004 —
Amenities	0.007*** (0.001)	0.006*** (0.001)	0.006*** (0.001)	0.006*** (0.001)	0.006*** (0.001)	0.006 —
Labour income	0.051*** (0.012)	0.051*** (0.011)	0.052*** (0.012)	0.053*** (0.013)	0.052*** (0.011)	0.051 —
Migration cost	-0.004*** (0.001)	-0.002*** (0.001)	-0.003*** (0.001)	-0.002*** (0.001)	-0.003*** (0.001)	-0.003 —
Indirect effects						
Lagged population	-0.028** (0.011)	-0.049*** (0.018)	-0.039*** (0.013)	-0.030*** (0.009)	-0.127 (0.135)	-0.075 —
TFP	0.003** (0.001)	0.001 (0.003)	0.002 (0.003)	0.002 (0.002)	0.014 (0.016)	0.005 —
Amenities	0.004*** (0.001)	0.006*** (0.002)	0.005*** (0.002)	0.004*** (0.001)	0.016 (0.017)	0.008 —
Labour income	0.028*** (0.010)	0.054** (0.022)	0.043*** (0.014)	0.032*** (0.009)	0.131 (0.137)	0.074 —
Migration cost	-0.002*** (0.000)	-0.002*** (0.001)	-0.002*** (0.001)	-0.001*** (0.000)	-0.008 (0.008)	-0.004 —

$\hat{W}$ denotes the data-driven network obtained based on Juodis-Kapetanios-Sarafidis 2025. W_1 is contiguity; W_2 – W_3 are inverse-distance (10th/5th percentile cutoffs); W_4 – W_5 are trade-based (time-averaged/time-varying).

Spillouts originating from Midwest States

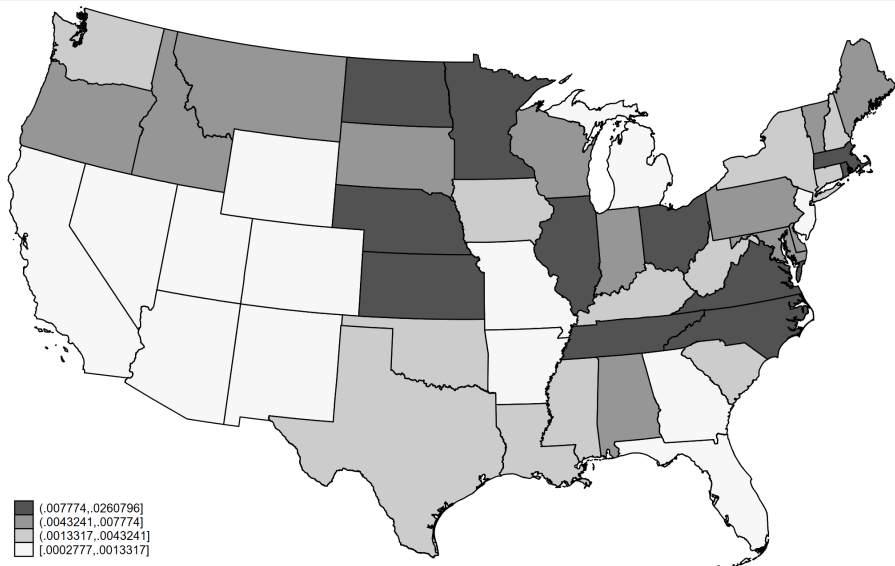


Figure: Spillouts Originating from the Midwest Region.

U.S. Population Growth Network

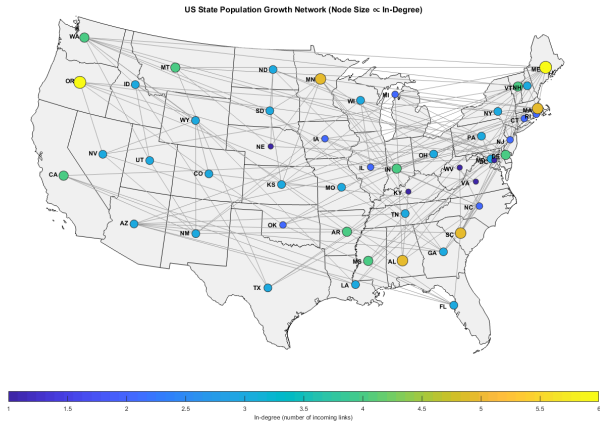


Figure: U.S. States Population Growth Network.

Concluding Remarks

- We put forward two IV estimators for homogeneous and heterogeneous models; Both are asy. unbiased, consistent and asy. normal under $N, T \rightarrow \infty$;
- Both IV estimators are **linear and computationally inexpensive**, and can accommodate **endogeneity**;
- *spxtivdfreg* implements these estimators in Stata and is very flexible as it allows for:
 - importing W from a csv/Excel file;
 - W being time-varying;
 - different instrumentation and defactoring strategies;
 - computation of direct/indirect effects and spillins/spillouts.

Pillars of the *spxtivdfreg* command

The *spxtivdfreg* Stata command draws upon the following work:

- Cui, G., Chen, J., Sarafidis, V., and T. Yamagata. 2025. [Estimating Spatial Dynamic Panel Data Models with Common Factors in Stata](#). Unpublished Manuscript, arXiv:2501.18467v1.
- Cui, G., Sarafidis, V., and T. Yamagata. 2023. [IV Estimation of Spatial Dynamic Panels with Interactive Effects: Large Sample Theory and an Application on Bank Attitude Toward Risk](#). *Econometrics Journal*, Vol. 26(2), pp. 124-146.
- Juodis, A., Sarafidis, V., and G. Kapetanios. 2025. Identification and estimation of panel network models using high-dimensional regression. Unpublished Manuscript.
- Kripfganz, S., and V. Sarafidis. 2025. [Estimating Spatial Dynamic Panel Data Models with Common Factors in Stata](#). *Journal of Statistical Software*, Vol. 113(6), pp. 1-27.
- Kripfganz, S., and V. Sarafidis. 2025. Chasing Opportunity: Spillovers and Drivers of U.S. State Population Growth. Invited contribution.

Thank you so much for listening!

