

Identification and Estimation of Average Causal Effects in Fixed Effects Logit Models

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Outline

- 1 Introduction
- 2 Identification
- 3 Estimation and inference
- 4 Simulations
- 5 The Stata command mlogit
- 6 Conclusion

Binary outcomes with panels: the current practice

- Suppose we seek to identify the effect of a variable X_{kt} on a binary outcome Y_t with panel data.
- Usual parameters of interest:
 1. AME=effect on Y_T of a universal, exogenous, infinitesimal change in X_{kT} .
 2. ATE=effect on Y_T of a universal, exogenous change in X_{kT} from 0 to 1.
- Following Angrist (2001) and Angrist & Pischke (2008), applied economists most often use fixed effects (FE) linear models to estimate AME and ATE.
- Idea behind: even if wrong, such models deliver the best linear approximation of the true model.

Binary outcomes with panels: the current practice

- Yet, the results can be misleading for at least two reasons.
- 1st issue: FE linear models only use “movers” (on X); yet “stayers” may be very different from movers (and also more numerous).
- 2nd issue: nonlinearities can matter. The best linear approximation may still be bad, and identify the opposite sign of the true AME/ATE.

An alternative: the fixed effect logit model

- Logit model with fixed effects (FE):

$$Y_t = \mathbb{1}\{X_t'\beta_0 + \alpha + \varepsilon_t \geq 0\} \tag{1}$$

$$\varepsilon_t | X, \alpha \sim \text{logistic, i.i.d over } t \leq T.$$

- “FE” approach: the distribution of $\alpha|X$ (with $X := (X_1', \dots, X_T')$) is left unrestricted.
- Advantages:
 1. The model allows for heterogeneous marginal/treatment effects;
 2. The model accounts for $E(Y_t|X, \alpha) \in (0, 1)$.
- Efficient estimation of β_0 already considered by Rasch (1961); see also Andersen (1970) and Chamberlain (1980).
- But to date, no specific study of the AME and ATE in this model.

Our contribution

- We first study the identification of AME and ATE in this model:
 1. reformulate the problem as an extremal moment problem;
 2. derive simple, optimization-free, sharp bounds.
- Based on this analysis, we suggest two paths for inference:
 1. Estimate the sharp bounds.
Requires nonparam. estimation and, for inference, some regularity on $F_{\alpha|X}$.
 2. Estimate very simple outer bounds of the AME/ATE.
Avoids nonparam. est. and seems to work very well in practice.
- Our analysis extends to other parameters (e.g., average structural functions) and the ordered FE logit model.

Selected Literature Review

- **Marginal Effects in nonlinear FE parametric panel models**

Honoré & Tamer (2006), Aguirregabiria and Carro (2020), Liu, Poirier and Shu (2021) ...

- **Moment problem**

Theory: Karlin & Shapley (1953), Krein & Nudelman (1977), Schmüdgen (2017)... and old results from Chebyshev and Markov!

Application to stats & econometrics Dette & Studden (1997), D'Haultfœuille & Rathelot (2017), Dobronyi, Gu and Kim (2021)...

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The problem

- We focus on the AME at period T (say) for variable X_{kT} , defined by:

$$\Delta := E \left[\frac{\partial P(Y_T = 1 | X, \alpha)}{\partial X_{kT}} \right] = \beta_{0k} E [\Lambda'(X'_T \beta_0 + \alpha)],$$

with $\Lambda(x) = 1/(1 + \exp(-x))$, $X_t = (X_{1T}, \dots, X_{pT})'$ and $X = (X'_1, \dots, X'_T)'$.

- Analysis similar for the ATE if X_{kT} is binary, and the average structural function.
- β_0 is identified by maximizing the conditional log-likelihood if

$$E \left[\sum_{s,t=1}^T (X_s - X_t)(X_s - X_t)'\right] \text{ is nonsingular.} \quad (2)$$

- But unclear how to get $E [\Lambda'(X'_T \beta_0 + \alpha)]$.

Intuition

- Since no constraints b/w $F_{\alpha|X=x}$ and $F_{\alpha|X=x'}$, we can focus on

$$\Delta(x) := \beta_{0k} E [\Lambda'(x'_T \beta_0 + \alpha) | X = x].$$

⇒ A known moment of the unobserved variable α .

- Constraints on $F_{\alpha|X=x}$, given by the data and the model.
- By sufficiency of $S = \sum_{t=1}^T Y_t$, all these constraints are, for $k = 0, \dots, T$:

$$P(S = k | X = x) = C_k(x, \beta_0) \int \frac{\exp(ka)}{\prod_{t=1}^T [1 + \exp(x'_t \beta_0 + a)]} dF_{\alpha|X=x}(a)$$

where $C_k(x, \beta) = \sum_{(d_1, \dots, d_T) \in \{0,1\}^T: \sum_{t=1}^T d_t = k} \exp\left(\sum_{t=1}^T d_t x'_t \beta\right)$.

Intuition (c'ed)

⇒ For known m, g_0, \dots, g_T , possible values of the moment $\int m(x, \alpha) dF_{\alpha|X=x}(\alpha)$, given other moments $\int g_k(x, \alpha) dF_{\alpha|X=x}(\alpha)$ ($k = 0, \dots, T$)?

- A so-called moment problem.
- We first transform this moment problem into the “standard” Markov moment problem:
 1. By an appropriate transformation of the constraints;
 1. By an appropriate change of variables.
- We then use results on the Markov moment problem to solve ours.

The Markov moment problem

- Let \mathcal{D} be the set of positive measures on $[0, 1]$ and:

$$\mathcal{M}_T = \left\{ (m_0, \dots, m_T) \in \mathbb{R}^{T+1} : \exists \mu \in \mathcal{D} : \int u^t d\mu(u) = m_t, t = 0, \dots, T \right\},$$

$$\mathcal{D}(m) = \left\{ \mu \in \mathcal{D} : \int u^t d\mu(u) = m_t, t = 0, \dots, T \right\} \quad \text{for } m \in \mathcal{M}_T.$$

- Then define:

$$\underline{q}_T(m) := \inf_{\mu \in \mathcal{D}(m)} \int_0^1 u^{T+1} d\mu(u),$$

$$\bar{q}_T(m) := \sup_{\mu \in \mathcal{D}(m)} \int_0^1 u^{T+1} d\mu(u).$$

- $\underline{q}_T(m)$ and $\bar{q}_T(m)$ can be obtained simply by solving univ. linear eqs

[Details](#)

Some definitions

- For $t = 0, \dots, T$, define:

$\lambda_t(x, \beta) :=$ coeff of degree t of the polynomial

$$u \mapsto u(1-u) \prod_{t=1}^{T-1} (1 + u(\exp((x_t - x_T)' \beta) - 1)),$$

$$Z_t := \binom{T-t}{S-t} \frac{\exp(SX_T' \beta_0)}{C_S(X; \beta_0)},$$

$$m_t(x) := \frac{E(Z_t | X = x)}{E(Z_0 | X = x)},$$

$$m(x) := (m_0(x), \dots, m_T(x))'.$$

- To remember here: all these are identified and easy to estimate, except $m(x)$ that involves conditional expectations.

Key result

Theorem 1

Suppose that (1)-(2) hold. Then, there exists a collection of probability measures $(\mu_x)_{x \in \text{Supp}(X)}$, with $\mu_x \in \mathcal{D}(m(x))$, such that

$$\Delta = \beta_{0k} E \left[\sum_{t=0}^T Z_t \lambda_t(x; \beta_0) + Z_0 \lambda_{T+1}(X, \beta_0) \int_0^1 u^{T+1} d\mu_x(u) \right]. \quad (3)$$

Moreover, the sharp identified set of Δ is $[\underline{\Delta}, \overline{\Delta}]$, with

$$\begin{aligned} \underline{\Delta} &= E \left[\sum_{t=0}^T Z_t \lambda_t(x; \beta_0) + \beta_{0k} Z_0 \lambda_{T+1}(X, \beta_0) (\underline{q}_T(m(X))) \right. \\ &\quad \left. \mathbb{1} \{ \beta_{0k} \lambda_{T+1}(X, \beta_0) \geq 0 \} + \overline{q}_T(m(X)) \mathbb{1} \{ \beta_{0k} \lambda_{T+1}(X, \beta_0) < 0 \} \right], \\ \overline{\Delta} &= E \left[\sum_{t=0}^T Z_t \lambda_t(x; \beta_0) + \beta_{0k} Z_0 \lambda_{T+1}(X, \beta_0) (\overline{q}_T(m(X))) \right. \\ &\quad \left. \mathbb{1} \{ \beta_{0k} \lambda_{T+1}(X, \beta_0) \geq 0 \} + \underline{q}_T(m(X)) \mathbb{1} \{ \beta_{0k} \lambda_{T+1}(X, \beta_0) < 0 \} \right]. \end{aligned}$$

Simple outer bounds: idea

- Drawback of the sharp bounds: use $m(x)$, which requires nonparam. estim.
- Actually, Eq. (3) also useful for obtaining simple outer bounds.
- Δ is not identified solely because of $\int_0^1 u^{T+1} d\mu_X(u)$.
- Imagine that instead of u^{T+1} , we had $P(u) = \sum_{k=0}^T b_k u^k$.
- Then, using $\int_0^1 u^k d\mu_X(u) = E(Z_k|X)/E(Z_0|X)$, we would get for Δ :

$$\beta_{0k} E \left[\sum_{t=0}^T (\lambda_t(X, \beta_0) + b_t \lambda_{T+1}(X, \beta_0)) Z_t \right].$$

Very simple expectation!

Simple outer bounds: idea (c'ed)

- Now, if $\sup_{u \in [0,1]} \left| u^{T+1} - \sum_{k=0}^T b_k u^k \right| \leq K$ for some $K > 0$, we obtain the outer bounds for Δ :

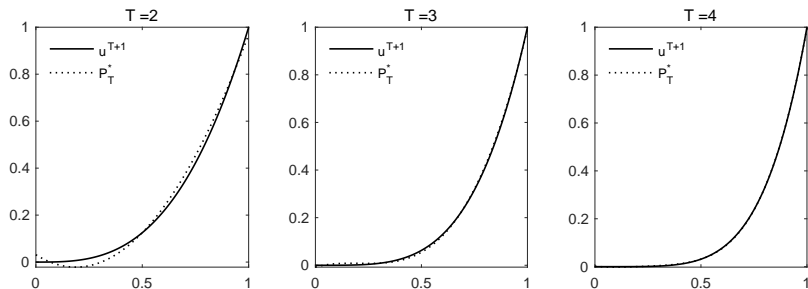
$$\left[\beta_{0k} E \left(\sum_{t=0}^T (\lambda_t(X, \beta_0) + b_t \lambda_{T+1}(X, \beta_0)) Z_t \right) \pm K E(Z_0 | \beta_{0k} \lambda_{T+1}(X, \beta_0)) \right].$$

- We can optimize these bounds, by choosing appropriately (b_0, \dots, b_T) .
- Specifically, we consider the best sup-norm approximation of $u \mapsto u^{T+1}$ by a polynomial of degree T :

$$\mathbf{b}^* = \operatorname{argmin}_{\mathbf{b} \in \mathbb{R}^{T+1}} \sup_{u \in [0,1]} \left| u^{T+1} - \sum_{k=0}^T b_k u^k \right| \quad (4)$$

Simple outer bounds

- \mathbf{b}^* very simple to compute, using Chebyshev polynomials.
- Figures below plot $u \mapsto u^{T+1}$ and $P_T^*(u) = \sum_{k=0}^T b_k^* u^k$.



- P_2^* approximates already very well $u \mapsto u^3$, curves indistinguishable for $T = 4$.
- With $\mathbf{b} = \mathbf{b}^*$, we have $K = 1/(2 \times 4^T)$.

Are the bounds informative?

Proposition 1 (Some properties of the bounds on Δ)

Suppose that (1)-(2) hold. Then:

1. The outer bounds may coincide with the sharp bounds.
2. $\bar{\Delta} - \underline{\Delta} \leq E[Z_0|\lambda_{T+1}(X, \beta_0)|] / 4^T$. If also $|(X_t - X_T)' \beta_0| \leq \ln(2)$ a.s.,

$$\bar{\Delta} - \underline{\Delta} \leq \frac{1}{4^T}.$$

3. Δ is point identified if and only if $\beta_{0k} = 0$ or

$$P\left(\min_{t < T} |(X_t - X_T)' \beta_0| = 0 \cup |\text{Supp}(\alpha|X)| \leq T/2\right) = 1.$$

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Estimation of the sharp bounds

- Recall that

$$\bar{\Delta} = E \left[\sum_{t=0}^T Z_t \lambda_t(x; \beta_0) + \beta_{0k} Z_0 \lambda_{T+1}(X, \beta_0) (\bar{q}_T(m(X)) \mathbb{1} \{ \beta_{0k} \lambda_{T+1}(X, \beta_0) \geq 0 \} + \underline{q}_T(m(X)) \mathbb{1} \{ \beta_{0k} \lambda_{T+1}(X, \beta_0) < 0 \}) \right],$$

$$m(X) = (m_0(X), \dots, m_T(X))', \quad m_t(x) := \frac{E(Z_t | X = x)}{E(Z_0 | X = x)},$$

$$Z_t = \binom{T-t}{S-t} \frac{\exp(SX'_T \beta_0)}{C_S(X; \beta_0)}.$$

- All terms can be estimated easily, except $m_t(X)$.
- We first estimate by local polynomial regression $E(Z_t | X = x)$ and obtain a plug-in estimator of $m(X)$.
- We modify this initial estimator to ensure that $\hat{m}(X)$ is a true moment vector (e.g., the corresponding variance is positive).

Asymptotic distribution of $(\widehat{\underline{\Delta}}, \widehat{\overline{\Delta}})$

Theorem 2

Suppose we have i.i.d. data and (1)-(2) and Assumption 1 hold [Details](#). Then, there exist $(\underline{\psi}_i, \overline{\psi}_i)_{i=1, \dots, n}$ i.i.d. such that:

1. If $\beta_{0k} > 0$, then

$$\sqrt{n} \begin{pmatrix} \widehat{\overline{\Delta}} - \overline{\Delta} \\ \widehat{\underline{\Delta}} - \underline{\Delta} \end{pmatrix} = \frac{1}{\sqrt{n}} \sum_{i=1}^n \begin{pmatrix} \overline{\psi}_i \\ \underline{\psi}_i \end{pmatrix} + o_P(1).$$

If $\beta_{0k} < 0$, same but with $\underline{\psi}_i$ and $\overline{\psi}_i$ switched.

2. If $\beta_{0k} = 0$, then

$$\sqrt{n} \begin{pmatrix} \widehat{\overline{\Delta}} - \overline{\Delta} \\ \widehat{\underline{\Delta}} - \underline{\Delta} \end{pmatrix} = \begin{pmatrix} \max \left(\frac{1}{\sqrt{n}} \sum_{i=1}^n \overline{\psi}_i, \frac{1}{\sqrt{n}} \sum_{i=1}^n \underline{\psi}_i \right) \\ \min \left(\frac{1}{\sqrt{n}} \sum_{i=1}^n \overline{\psi}_i, \frac{1}{\sqrt{n}} \sum_{i=1}^n \underline{\psi}_i \right) \end{pmatrix} + o_P(1).$$

- We also show that we can consistently estimate $\Sigma := V((\underline{\psi}, \overline{\psi})')$.

Construction of confidence intervals (CI)

- The estimated bounds are not asymptotically normal when $\beta_{0k} = 0$.
- ⇒ The CI of Imbens and Manski (2004) works when $\beta_{0k} \neq 0$, but possibly not when $\beta_{0k} = 0$.
- We modify them in a simple way. Let φ_α a test of $\beta_{0k} = 0$. Then let:

$$CI_{1-\alpha}^1 := \begin{cases} \left[\hat{\Delta} - c_\alpha \left(\frac{\hat{\Sigma}_{11}}{n} \right)^{1/2}, \hat{\Delta} + c_\alpha \left(\frac{\hat{\Sigma}_{22}}{n} \right)^{1/2} \right] & \text{if } \varphi_\alpha = 1, \\ \left[\min \left(0, \hat{\Delta} - c_\alpha \left(\frac{\hat{\Sigma}_{11}}{n} \right)^{1/2} \right), \max \left(0, \hat{\Delta} + c_\alpha \left(\frac{\hat{\Sigma}_{22}}{n} \right)^{1/2} \right) \right] & \text{if } \varphi_\alpha = 0. \end{cases}$$

where c_α is defined as in I & M.

Proposition 2

Suppose we have i.i.d. data, (1)-(2) and A1 hold and $\min(\Sigma_{11}, \Sigma_{22}) > 0$. Then $\liminf_n \inf_{\Delta \in [\underline{\Delta}, \bar{\Delta}]} P(\Delta \in CI_{1-\alpha}^1) \geq 1 - \alpha$, with equality when $\beta_{0k} \neq 0$.

Inference using outer bounds

- The outer bounds take the form $[\tilde{\Delta} \pm \bar{b}]$, with

$$\tilde{\Delta} = E \left[\sum_{t=0}^T Z_t (\lambda_t(X, \beta_0) + b_{t,T}^* \lambda_{T+1}(X, \beta_0)) \right],$$

$$\bar{b} = \frac{1}{2 \times 4^T} E [Z_0 | \lambda_{T+1}(X, \beta_0)|].$$

- We can estimate these simply by plug-in $\Rightarrow \hat{\tilde{\Delta}}$ and $\hat{\bar{b}}$.
- We then consider the confidence interval

$$CI_{1-\alpha}^2 = \left[\hat{\tilde{\Delta}} \pm q_\alpha \left(\frac{n^{1/2} \hat{\bar{b}}}{\hat{\sigma}} \right) \frac{\hat{\sigma}}{n^{1/2}} \right],$$

where $q_\alpha(b) = \text{quantile of order } 1 - \alpha \text{ of a } |\mathcal{N}(b, 1)|$ and $\hat{\sigma}$ is an estimator of the asymptotic variance of $\hat{\tilde{\Delta}}$.

Construction of confidence intervals on Δ

Theorem 3

Suppose (1)-(2) hold, X is bounded and either $|\tilde{\Delta} - \Delta| < \bar{b}$ or $\beta_{0k} = 0$. Then:

$$\liminf_{n \rightarrow \infty} P(\Delta \in CI_{1-\alpha}^2) \geq 1 - \alpha.$$

- $|\tilde{\Delta} - \Delta| < \bar{b}$ or $\beta_{0k} = 0$ holds except if

$$P(\text{Supp}(\Lambda(X_T' \beta_0 + \alpha)|X) \subset \mathcal{R}_X | \lambda_{T+1}(X, \beta_0) \neq 0) = 1, \quad (5)$$

where \mathcal{R}_X is the set of maxima (resp. minima) of the polynomial \mathbb{T}_{T+1} on $[0, 1]$ if $\lambda_{T+1}(x, \beta_0) > 0$ (resp. $\lambda_{T+1}(x, \beta_0) < 0$).

- Eq. (5) unlikely: it implies a very specific location for $\text{Supp}(\alpha)|X = x$, with discontinuous changes in this support at some x .
- But $CI_{1-\alpha}^2$ may not have a uniform coverage. See the paper for a slightly larger CI, uniform over a large class of DGP.

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Designs

- We assume X_1, \dots, X_T i.i.d., with $X_t \in \mathbb{R} \sim \mathcal{U}[-1/2, 1/2]$ and $\beta_0 = 1$.
- We let $T \in \{2, 3\}$ and $n \in \{250; 500; 1,000\}$.
- We then let $\alpha = -X_T' \beta_0 + \eta$, with either:
 1. $\eta|X \sim \mathcal{N}(0, 1)$;
 2. or $\eta|X$ such that $\tilde{\Delta} - \Delta = \bar{b}$.
- In the 2nd case, the DGP varies with T .

DGP1: estimators of the bounds

- $\Delta \simeq 0.2067$ is partially identified for all T .
- $(\underline{\Delta}, \overline{\Delta}) \simeq (0.2006, 0.2124)$ if $T = 2$ and $(\underline{\Delta}, \overline{\Delta}) \simeq (0.2059, 0.2069)$ if $T = 3$.

T	n	First method				Second method	
		$\sigma(\hat{\underline{\Delta}})$	Bias($\hat{\underline{\Delta}}$)	$\sigma(\hat{\overline{\Delta}})$	Bias($\hat{\overline{\Delta}}$)	$\sigma(\hat{\tilde{\Delta}})$	Bias($\hat{\tilde{\Delta}}$)
2	250	0.110	0.006	0.114	0.003	0.108	0.002
	500	0.077	0.013	0.081	0.01	0.074	0.005
	1000	0.054	0.013	0.057	0.011	0.052	0.004
3	250	0.072	-0.005	0.072	-0.005	0.074	-0.001
	500	0.049	-0.003	0.049	-0.004	0.051	0*
	1000	0.035	-0.004	0.036	-0.005	0.037	-0.001

Notes: *: absolute value < 0.0005. Results obtained with 3,000 sims.

DGP1: comparison between the two CI's

T	n	CI _{0.95} ¹		CI _{0.95} ²	
		coverage	av. length	coverage	av. length
2	250	0.96	0.453	0.96	0.419
	500	0.96	0.305	0.96	0.296
	1000	0.95	0.215	0.97	0.211
3	250	0.96	0.288	0.95	0.284
	500	0.96	0.201	0.95	0.201
	1000	0.95	0.141	0.94	0.142

Notes: results obtained with 3,000 sims.

DGP2_T: estimators of the bounds

- $\Delta = \underline{\Delta} = \overline{\Delta} \simeq 0.1875$ if $T = 2$
 $\Delta \simeq 0.1667$ and $(\underline{\Delta}, \overline{\Delta}) \simeq (0.1652, 0.1667)$ if $T = 3$.

T	n	First method				Second method	
		$\sigma(\hat{\underline{\Delta}})$	Bias($\hat{\underline{\Delta}}$)	$\sigma(\hat{\overline{\Delta}})$	Bias($\hat{\overline{\Delta}}$)	$\sigma(\hat{\hat{\Delta}})$	Bias($\hat{\hat{\Delta}}$)
2	250	0.146	0.049	0.151	0.058	0.105	-0.003
	500	0.104	0.032	0.108	0.041	0.076	-0.009
	1000	0.069	0.026	0.072	0.034	0.052	-0.01
3	250	0.075	0.01	0.075	0.009	0.063	0.001
	500	0.05	0.005	0.05	0.004	0.045	-0.001
	1000	0.034	0.005	0.034	0.004	0.031	0*

Notes: *: abs. value < 0.0005. Results obtained with 3,000 sims.

- The biases of $(\hat{\underline{\Delta}}, \hat{\overline{\Delta}})$ are not that small when $n = 1,000$ and $T = 2$.
- This could be b/c regularity conditions on $\gamma_s(\cdot)$ are actually violated here.

DGP2_T: comparison between the two CI's

T	n	CI _{0.95} ¹		CI _{0.95} ²	
		coverage	av. length	coverage	av. length
2	250	0.92	0.522	0.96	0.420
	500	0.91	0.353	0.95	0.295
	1000	0.91	0.243	0.95	0.209
3	250	0.96	0.276	0.96	0.249
	500	0.95	0.186	0.95	0.175
	1000	0.95	0.130	0.95	0.124

Notes: results obtained with 3,000 sims.

- $CI_{1-\alpha}^2$ has still very good coverage, though $\tilde{\Delta} - \Delta = \bar{b}$.
- $CI_{1-\alpha}^1$ undercovers for $T = 2$, probably b/c of the aforementioned bias.

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What it does & does not do yet

- Available on SSC (requires `estout` to be installed).
- First estimates β_0 , then computes estimated bounds or the “point estimate” $\hat{\Delta}$, and CI for the AME (if not binary) or the ATE (if binary).
- Handles unbalanced panels.
- Still in progress:
 - Does not handle factor variables yet;
 - Only estimates the sharp bounds & $CI_{1-\alpha}^1$ for continuous X ;
 - Does not handle, e.g. age and age^2 ;
 - Could probably be faster.

Simplified syntax

```
mfelogit depvar [indepvar] [if] [in] method(string) id(string)  
time(string) [, listT(string) listX(string) level(string)]
```

- `id` and `time`: individual and time identifiers.
- `method`: outer bounds if "quick" (default), sharp bounds if "sharp".
- `listT`: periods on which AME / ATE are computed. By default, last period for which all individuals are observed. If "all", computes AME / ATE for all periods, and their averages.
- `listX`: covariates for which the AME / ATE are computed. By default, all covariates.
- `level`: level of confidence intervals. "0.95" by default.

(Toy) example: determinants of unionization in the US

- Syntax:

```
use "https://www.stata-press.com/data/r17/union.dta", clear

tabulate year, generate(y_)
drop y_1

mfelogit union south y_* black, id("idcode") time("year")

xtset idcode year
xtreg union age y_* black south, fe
```

- `black` automatically omitted as constant for each indiv. over time.
- Results on the ATE for `south`, with the FE logit and FE linear regs.:

	FE Logit model	FE linear reg.
Point est.	-0.072	-0.071
95% CI	[-0.095, -0.048]	[-0.103, -0.040]

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Conclusion

- Simple characterization of the identified set for the AME.
- Based on this, estimators of the sharp bounds of the AME.
- Alternative method based on a “proxy” of the AME and an upper bound on its asymptotic bias.
- Though not optimal as $n \rightarrow \infty$, very simple and seems to work very well for usual n and T .
- Already a Stata command, `mfe1ogit`, available on SSC. Will be improved soon hopefully!

Intuition on the Markov moment problem for $T = 1$.

- If $T = 1$, we seek bounds on $\int_0^1 x^2 d\mu(x)$ given $\int_0^1 x d\mu(x) = m_1$.
- Using $x^2 \leq x$ on $[0, 1]$ and Jensen's ineq., we get $\underline{q}_1(m) = m_1^2$, $\bar{q}_1(m) = m_1$.

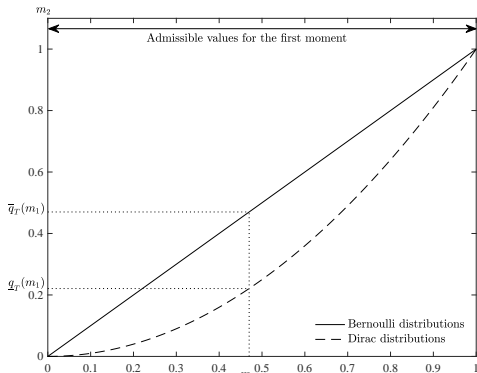


Figure: Moment space and bounds $\underline{q}_T(m)$, $\bar{q}_T(m)$ when $T = 1$.

Solving the moment problem for any T Back

- Such ideas generalize for any T : $\underline{q}_T(m)$ and $\bar{q}_T(m)$ rational functions of m .
- Let $T > 0$ and for any $m = (m_0, \dots, m_s)$, $s > T$, let

$$\begin{aligned} \underline{\mathbb{H}}_T(m) &= (m_{i+j-2})_{1 \leq i, j \leq T/2+1}, & \overline{\mathbb{H}}_T(m) &= (m_{i+j-1} - m_{i+j})_{1 \leq i, j \leq T/2} && \text{if } T \text{ even} \\ \underline{\mathbb{H}}_T(m) &= (m_{i+j-1})_{1 \leq i, j \leq (T+1)/2}, & \overline{\mathbb{H}}_T(m) &= (m_{i+j-2} - m_{i+j-1})_{1 \leq i, j \leq (T+1)/2} && \text{if } T \text{ odd.} \end{aligned}$$

- Then let $\underline{H}_T(c) = \det(\underline{\mathbb{H}}_T(c))$ and $\overline{H}_T(c) = \det(\overline{\mathbb{H}}_T(c))$.

Proposition 3 (Extremal moments & Hankel determinants)

1. $\mathcal{M}_T = \text{closure} \{ m \in \mathbb{R}^{T+1} : \underline{H}_t(m) > 0 \text{ and } \overline{H}_t(m) > 0, t = 1, \dots, T \}$.
2. If $m \in \mathcal{M}_T$ and $\underline{H}_T(m) \times \overline{H}_T(m) > 0$, $\underline{q}_T(m) < \bar{q}_T(m)$. Also, $q \mapsto \underline{H}_{T+1}(m, q)$ is strictly \uparrow , linear and

$$\underline{H}_{T+1}(m, \underline{q}_T(m)) = 0 \quad (\text{and similarly for } \bar{q}_T(m)).$$

- See the paper for the point identified case (when $\underline{H}_T(m) \times \overline{H}_T(m) = 0$).

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- Let $\gamma(\cdot) = (\gamma_0(\cdot), \dots, \gamma_T(\cdot))$ with $\gamma_t(x) = P(S = t | X = x)$.
- K be the kernel in the local polynomial (of degree $\ell \geq pT/2$) estimator of $\gamma_t(\cdot)$ and $h_n \in \mathbb{R}$ be the bandwidth.

Assumption 1

1. K has a compact support and is Lipschitz on \mathbb{R}^{pT} .
 2. $nh_n^{2(\ell+1)} \rightarrow 0$ and $n[h_n^{pT} / \ln n]^3 \rightarrow \infty$.
 3. The pdf of X , f_X , is C^1 and bounded away from 0 on its bounded support.
 4. γ_0 is $C^{\ell+2}$ on $\text{Supp}(X)$.
 5. Either $|\text{Supp}(\alpha | X = x)| > T/2$ for all $x \in \text{Supp}(X)$, or $x \mapsto |\text{Supp}(\alpha | X = x)|$ is constant.
- Point 5 needed b/c \underline{q}_t and \bar{q}_t not differentiable at all $m \in \partial\mathcal{M}_t$ if $t \geq 3$.