

Estimating the Price Elasticity of Gasoline Demand in Correlated Random Coefficient Models with Endogeneity

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- ▶ Estimation is difficult due to:
 - ▶ Endogeneity: Simultaneous supply and demand forces
 - ▶ Seasonal prices and quantities trend over time
 - ▶ Heterogeneity: locations differ in taxes, regulation, infrastructure, macroeconomic climate (Wadud et al., 2010; Frondel et al., 2012; Blundell et al., 2012; Hausman and Newey, 2016)

Existing strategies for endogeneity

- ▶ We have an instrument! We follow the literature in instrumenting prices with state fuel taxes (Davis and Kilian, 2011; Blundell et al., 2012; Hausman and Newey, 2016; Coglianesi et al., 2017; Hoderlein and Vanhems, 2018)

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- ▶ Given panel structure, use P2SLS or FEIV with two-way fixed effects to get a LATE?
- ▶ Even with exogenous regressors, recent work explores issues from heterogeneous effects in two-way fixed effects models
—[De Chaisemartin and d'Haultfoeuille (2020); Sun and Abraham (2021); Wooldridge (2021); Goldsmith-Pinkham et al. (2022); #metricstothe face]

Complications from heterogeneity

Simple model (Murtazashvili and Wooldridge, 2008):

- ▶ $y_{ij} = \alpha_i + x_{ij}(\beta + d_i) + e_{ij}$
- ▶ $i = 1, \dots, N$ indexes cluster, $j = 1, \dots, T$ indexes observations within cluster, have instrument z_{ij}

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Violations:

- ▶ A LATE different from the ATE exists
- ▶ Even in a population of compliers, correlations between the strength of IV and heterogeneous responsiveness leads to inconsistency

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- ▶ Fernández-Val and Lee (2013) adopt a natural approach of estimating cluster-specific coefficients using GMM per cluster and averages over them
- ▶ The Fernández-Val and Lee (2013) estimator does not, however, handle two-way fixed effects models (and may have difficulty with other exogenous regressors)

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- ▶ Monte-Carlo finite sample simulations
- ▶ Apply the estimators to estimate the price elasticity of demand for gasoline finding meaning for differences in point estimates

Pros and Cons

Advantages of using PCIV:

- ▶ Estimate PAEs (& LATEs for an identified group of compliers) under less restrictive assumptions
- ▶ Estimate the distribution of effect heterogeneity
- ▶ Root mean squared error declines with more observations per-cluster
- ▶ PC first-stage provides insight regarding key assumptions underpinning IV estimation with grouped data

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Model Identification Constraint:

- ▶ Need variation in each cluster for each cluster to be represented in the PAE without further assumptions

General Model

Consider a correlated random effects model as follows:

$$\begin{aligned}y_{ij} &= \mathbf{x}_{1ij}\mathbf{b}_i + \mathbf{x}_{2ij}\boldsymbol{\delta} + e_{ij}, \\ \mathbf{x}_{1ij} &= \mathbf{z}_{ij}\boldsymbol{\Gamma}_i + \mathbf{x}_{2ij}\boldsymbol{\eta} + u_{ij}, \quad i = 1, \dots, N; j = 1, \dots, T,\end{aligned}\tag{1}$$

- ▶ y_{ij} is a dependent variable
- ▶ \mathbf{x}_{1ij} is a $1 \times K$ vector of plausibly endogenous covariates
 - ▶ Plausibly heterogeneous second-stage slopes $\mathbf{b}_i = \boldsymbol{\beta} + \mathbf{d}_i$ such that $E(\mathbf{d}_i) = 0$
- ▶ \mathbf{z}_{ij} , a $1 \times L$ ($L \geq K$) vector of instrumental variables
 - ▶ Plausibly heterogeneous first-stage slopes $\boldsymbol{\Gamma}_i = \boldsymbol{\gamma} + \mathbf{g}_i$ such that $E(\mathbf{g}_i) = 0$
- ▶ We allow for a $1 \times H$ vector of exogenous covariates, \mathbf{x}_{2ij} , with $\boldsymbol{\delta}$ and $\boldsymbol{\eta}$, $H \times 1$ vectors of homogeneous slopes
 - ▶ May include a $1 \times T$ vector of time indicators s.t. $T < H$
- ▶ e_{ij} is an idiosyncratic error

General estimator: first stage (unbiased in finite samples)

1. Pre-treat the data to account for Γ_i : Per-cluster, regress \mathbf{x}_{1ij} and \mathbf{x}_{2ij} on \mathbf{z}_{ij} , saving the residuals
 2. To consistently estimate η , regress the residuals $\tilde{\mathbf{x}}_{1ij}$ on $\tilde{\mathbf{x}}_{2ij}$ pooling over clusters to estimate $\hat{\eta}$
 3. Estimate Γ_i per-cluster by regressing $(\mathbf{x}_{1ij} - \mathbf{x}_{2ij}\hat{\eta})$ on \mathbf{z}_{ij} to obtain $\hat{\mathbf{X}}_{1i}$
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 2. Use cross-sectional variation to estimate homogeneous parameters
 3. Use within variation (net of homogeneous parameters) to get the first stage by cluster (Wooldridge, 2010)

General estimator: second stage (rinse wash repeat)

1. For the second stage, we regress y_{ij} and \mathbf{x}_{2ij} on $\hat{\mathbf{x}}_{1ij}$ per-cluster, obtaining the residuals $\dot{\mathbf{y}}_i$ and $\dot{\mathbf{x}}_{2i}$
2. Regressing the residuals \dot{y}_{ij} on $\dot{\mathbf{x}}_{2ij}$ pooling over clusters allows us to eliminate \mathbf{b}_i when we obtain $\hat{\delta}$
3. The heterogeneous slopes $\hat{\mathbf{b}}_i = (\hat{\mathbf{X}}'_{1i}\hat{\mathbf{X}}_{1i})^{-1}\hat{\mathbf{X}}'_{1i}(\mathbf{y}_i - \mathbf{X}_{2i}\hat{\delta})$ can be consistently estimated by regressing $(y_{ij} - \mathbf{x}_{2ij}\delta)$ on $\hat{\mathbf{x}}_{1ij}$ per cluster

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pciv.ado Stata package coming...

Consistency of $\hat{\beta}_{PCIV}$

With $T \rightarrow \infty$ and $N \rightarrow \infty$,

$$\text{plim}_{T, N \rightarrow \infty} (\hat{\beta}_{PCIV} - \beta) = E(\mathbf{d}_i) + E[[E_i(\mathbf{x}'_{ij} \mathbf{H}_{z_i} \mathbf{x}_{ij})]^{-1} E_i(\mathbf{x}'_{ij} \mathbf{H}_{z_i} e_{ij})] \quad (2)$$

Thus, consistency of $\hat{\beta}_{PCIV}$ follows from the assumptions enumerated below:

(A1) *i.i.d.* across i

(A2) $E[e_{ij} \mid \mathbf{x}_{2i}, \mathbf{z}_i, \mathbf{d}_i] = 0$, $E[u_{ij} \mid \mathbf{x}_{2i}, \mathbf{z}_i, \mathbf{g}_i] = 0$

(A3) $\text{rank}[E_i(\mathbf{z}'_{ij} \mathbf{x}_{ij})] = K$, $\text{rank}[E_i(\mathbf{z}'_{ij} \mathbf{z}_{ij})] = L$, and $E[\mathbf{z}'_{ij} \mathbf{z}_{ij} e_{ij}^2]$ is positive definite

(A4) $E[\|\mathbf{x}_{2ij}\|^2] < \infty$, $E[\|\mathbf{z}_{ij}\|^2] < \infty$; $E[\|\mathbf{z}_{ij}\|^4] < \infty$, and $E[\|\mathbf{x}_{2ij}\|^4] < \infty$

(A5) $w_i = O_p(n^\epsilon)$ where $\sum_{i=1}^N w_i = 1$ and $\epsilon \leq -1$; $N^{3+2\epsilon}/T \rightarrow c$, where $0 < c < \infty$

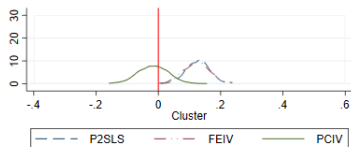
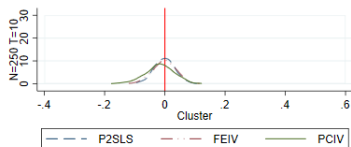
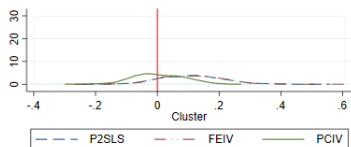
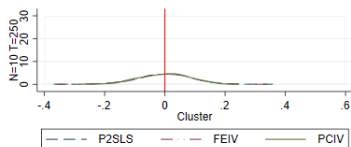
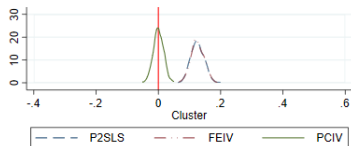
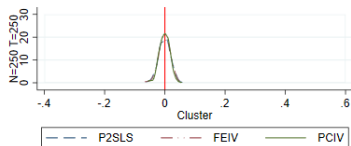
Inference

$$\begin{aligned} & \hat{V}(\hat{\beta}_{PCIV} - \beta) \tag{3} \\ &= V \left(\sum_{i=1}^N w_i \left[\hat{\mathbf{d}}_i + (\mathbf{X}'_{1i} \mathbf{P}_i \mathbf{X}_{1i})^{-1} \mathbf{X}'_{1i} \mathbf{P}_i \hat{\mathbf{e}}_i \right] \right) \\ &= \sum_{i=1}^N w_i^2 \hat{\mathbf{d}}_i \hat{\mathbf{d}}_i' + \sum_{i=1}^N w_i^2 (\mathbf{X}'_{1i} \mathbf{P}_i \mathbf{X}_{1i})^{-1} \mathbf{X}'_{1i} \mathbf{P}_i \hat{\Omega} \mathbf{P}_i' \mathbf{X}_{1i} (\mathbf{X}'_{1i} \mathbf{P}_i \mathbf{X}_{1i})^{-1} \end{aligned}$$

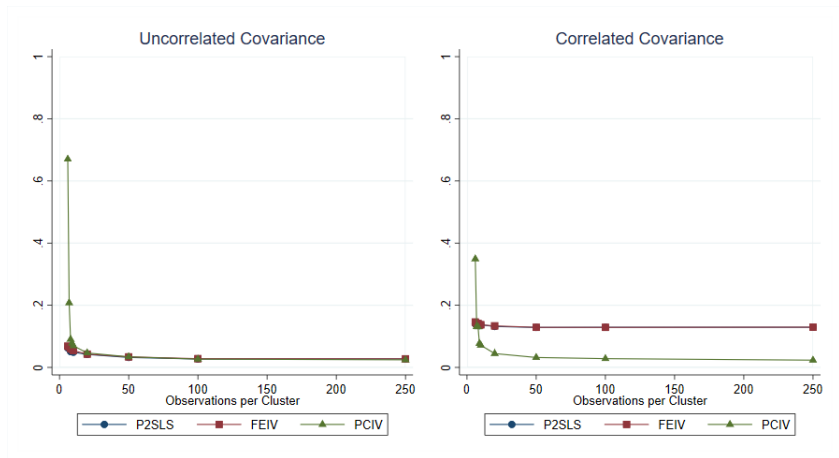
where $\hat{\mathbf{d}}_i = \hat{\mathbf{b}}_i - \hat{\beta}_{PCIV}$ and $\hat{\mathbf{e}}_i = y_i - \mathbf{X}_{1i} \hat{\mathbf{b}}_i - \mathbf{X}_{2ij} \hat{\boldsymbol{\delta}}$. The standard errors from this estimator are robust to heteroskedasticity and arbitrary correlation in the error term within cluster

Simplified model: kernel density plots of estimation errors, $\hat{\beta}_1 - \beta_1$

Uncorrelated Covariance vs. Correlated Covariance

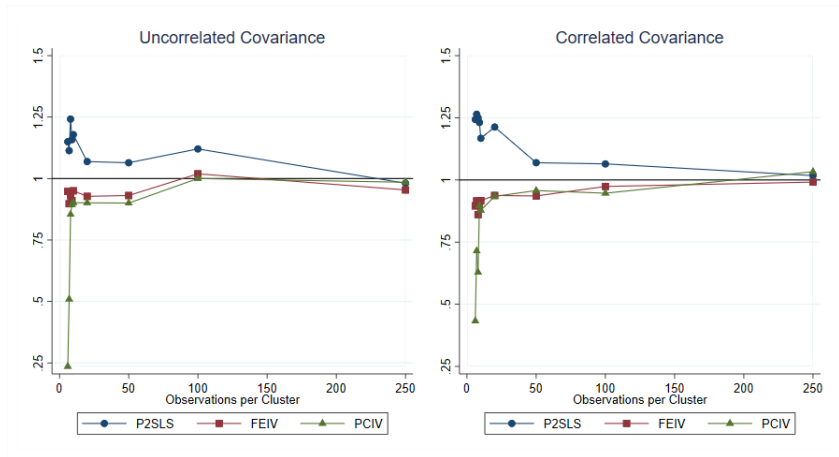


Root Mean Squared Errors across cluster size



DPG

Ratio of Mean SE by SD across cluster size

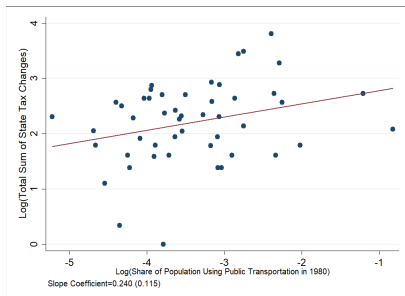


Note: Ratio of mean standard errors (SEs) divided by standard deviations (SDs) of the estimates

PCIV in practice: Elasticity of demand for gasoline

- ▶ First-stage heterogeneity: sales and per-unit taxes vary by state
- ▶ Second-stage heterogeneity: infrastructure, population density, and local economies vary by state
- ▶ Correlation: States with more infrastructure raise taxes more

Figure: Relationship between tax changes and public transportation



Estimating equation

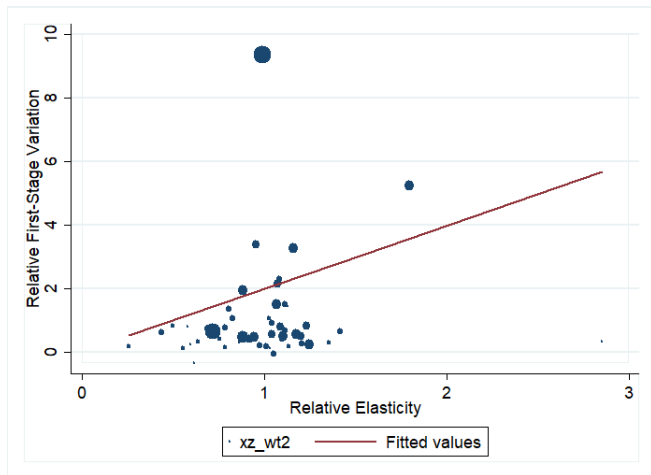
$$\begin{aligned} \log sales_{ij} &= \alpha_{1i} + \log price_{ij} b_i + \mathbf{x}_{ij} \boldsymbol{\delta} + \tau_{1t} + \epsilon_{ij}, \\ \log price_{ij} &= \alpha_{2i} + \log taxes_{ij} \Gamma_i + \mathbf{x}_{ij} \boldsymbol{\eta}_2 + \tau_{2t} + u_{ij}. \end{aligned} \quad (4)$$

- ▶ Includes state and month-by-year fixed effects
- ▶ Includes population, income, unemployment, temperature, and rainfall exogenous covariates

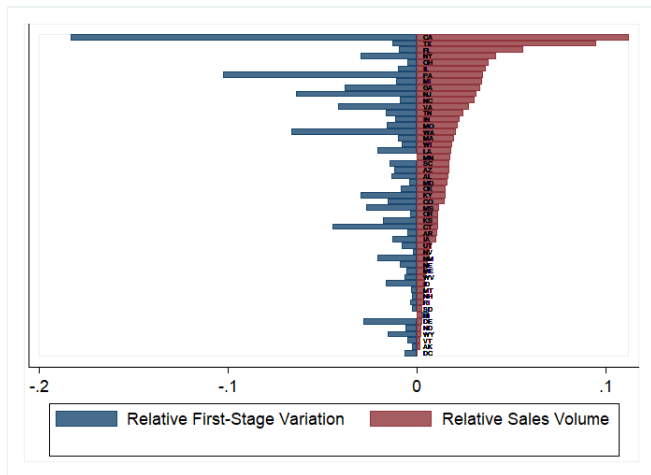
Summary of Results Using Three Estimation Methods

	Without volume weights			Volume weighted		
	P2SLS	FEIV	PCIV	P2SLS	FEIV	PCIV
Log price	-0.724 (0.193)	-0.929 (0.415)	-0.551 (0.227)	-0.463 (0.154)	-0.873 (0.394)	-0.555 (0.240)
First-stage F-statistic	36.66	79.71	58.35	47.47	63.70	61.16
Controls	N	N	N	N	N	N
Log price	-0.736 (0.189)	-0.828 (0.327)	-0.543 (0.278)	-0.512 (0.138)	-0.760 (0.271)	-0.561 (0.294)
First-stage F-statistic	36.58	80.92	58.71	46.83	60.26	59.93
Controls	Y	Y	Y	Y	Y	Y

Violation: correlated elasticities and first-stage variation



FEIV implicit weighting vs volume weights



LATE

Table: Estimated elasticities among states in which the instrument is strong (LATE)

	Without volume weights			Volume weighted		
	P2SLS	FEIV	PCIV	P2SLS	FEIV	PCIV
Log price	-0.659 (0.208)	-1.153 (0.389)	-0.521 (0.216)	-0.430 (0.170)	-0.945 (0.399)	-0.541 (0.210)
First-stage F-statistic	43.24	80.92	55.91	98.21	64.51	58.35

Notes: Sample composed of all states with first-stage F-statistics above 10, excluding Hawaii, Indiana, Georgia, Michigan, and the District of Columbia. Regressions condition on time-by-month fixed effects. State-clustered standard errors appear in parentheses.

Conclusion

- ▶ This paper suggests Per-Cluster Instrumental Variable Approach to identify PAEs
- ▶ When the strength of the instrument is related to the heterogeneous effects, PCIV can consistently estimate Population Average Effects
- ▶ With access to large T data sets, PCIV strictly dominates FEIV
- ▶ Even without a large T it may be useful, and we advocate considering PC first stage
- ▶ It seems that gasoline consumption is more elastic than typically thought, though the confidence interval is wide

Consistency for Fixed Effects Estimators

- ▶ Wooldridge (2005) shows the conditions under which standard fixed effects estimators are consistent in estimating PAEs

$$\widehat{\beta}_{FE} = \beta + \left(\sum_{i=1}^N \sum_{t=1}^T \ddot{\mathbf{x}}_{ij}' \ddot{\mathbf{x}}_{ij} \right)^{-1} \left[\sum_{i=1}^N \sum_{t=1}^T \ddot{\mathbf{x}}_{ij}' \ddot{\mathbf{x}}_{ij} \mathbf{d}_i + \sum_{i=1}^N \sum_{t=1}^T \ddot{\mathbf{x}}_{ij}' \ddot{\mathbf{e}}_{ij} \right] \quad (5)$$

- ▶ Assumptions for consistency for the simple case model is as follows.

$$E(\mathbf{e}_{ij} | \mathbf{x}_{i1}, \dots, \mathbf{x}_{ij}, \mathbf{b}_i) = 0, \quad t = 1, \dots, T, \quad (6)$$

$$\text{rank} E \left(\sum_{t=1}^T \ddot{\mathbf{x}}_{ij}' \ddot{\mathbf{x}}_{ij} \right) = K, \quad (7)$$

$$E[\ddot{\mathbf{x}}_{ij}' \ddot{\mathbf{x}}_{ij} \mathbf{d}_i] = 0, \quad (8)$$

where $\ddot{\mathbf{x}}_{ij} = \mathbf{x}_{ij} - T^{-1} \sum_{t=1}^T \mathbf{x}_{ij}$.

Per-Cluster Estimation with Exogenous Regressors

- ▶ However, equation 8 may not hold in important cases.
- ▶ Per-cluster estimation in this simple model needs only two steps (Bates et al. (2014))
 - ▶ First, estimate $\hat{\mathbf{b}}_i$ for each cluster using OLS on only the within-cluster observations, such that

$$\hat{\mathbf{b}}_i = \beta + \mathbf{d}_i + \left(\sum_{t=1}^T \mathbf{x}'_{ij} \mathbf{x}_{ij} \right)^{-1} \left(\sum_{t=1}^T \mathbf{x}'_{ij} e_{ij} \right) \quad (9)$$

- ▶ Second, average $\hat{\mathbf{b}}_i$ over clusters.

$$\widehat{\beta}_{PC} = \beta + N^{-1} \sum_{i=1}^N \mathbf{d}_i + N^{-1} \sum_{i=1}^N \left[\left(\sum_{t=1}^T \mathbf{x}'_{ij} \mathbf{x}_{ij} \right)^{-1} \left(\sum_{t=1}^T \mathbf{x}'_{ij} e_{ij} \right) \right] \quad (10)$$

- ▶ From the rank conditions, $E(\mathbf{d}_i) = 0$ by definition, and the strict exogeneity assumption from equation (2), per-cluster estimator is **unbiased**

Asymptotic unbiasedness with fixed N

With $T \rightarrow \infty$ and N fixed,

$$\begin{aligned} & \underset{T \rightarrow \infty}{\text{plim}} \widehat{\beta}_{PCIV} \\ &= \beta + N^{-1} \sum_{i=1}^N \mathbf{d}_i + N^{-1} \sum_{i=1}^N [(E(\mathbf{z}'_{ij} \mathbf{x}_{ij}))^{-1} E(\mathbf{z}'_{ij} e_{ij})]. \end{aligned} \quad (11)$$

$$E(\underset{T \rightarrow \infty}{\text{plim}} \widehat{\beta}_{PCIV}) = \beta + E(\mathbf{d}_i) + E[[E_i(\mathbf{z}'_{ij} \mathbf{x}_{ij})]^{-1} E_i(\mathbf{z}'_{ij} e_{ij})]. \quad (12)$$

$\therefore \widehat{\beta}_{PCIV}$ is asymptotically unbiased.

Unlike FEIV, the PCIV estimator may provide an asymptotically unbiased estimate of β even when $E[(\ddot{\mathbf{z}}'_{ij} \ddot{\mathbf{x}}_{ij})^{-1} \ddot{\mathbf{z}}'_{ij} \ddot{\mathbf{x}}_{ij} \mathbf{d}_i] \neq 0$

Assumption needed for consistency with T fixed

With fixed T,

$$\underset{N \rightarrow \infty}{plim} \widehat{\beta}_{PCIV} = \beta + \underset{N \rightarrow \infty}{plim} N^{-1} \sum_{i=1}^N \mathbf{d}_i + \underset{N \rightarrow \infty}{plim} N^{-1} \sum_{i=1}^N [(\sum_{t=1}^T \mathbf{z}'_{ij} \mathbf{x}_{ij})^{-1} \sum_{t=1}^T \mathbf{z}'_{ij} e_{ij}]. \quad (13)$$

$$\underset{N \rightarrow \infty}{plim} \widehat{\beta}_{PCIV} = \beta + E[\mathbf{d}_i] + E[(\sum_{t=1}^T \mathbf{z}'_{ij} \mathbf{x}_{ij})^{-1} \sum_{t=1}^T \mathbf{z}'_{ij} e_{ij}]. \quad (14)$$

In this case, in order for $\widehat{\beta}_{PCIV}$ to consistently estimate the PAE (β), we must assume

$$E[(\sum_{t=1}^T \mathbf{z}'_{ij} \mathbf{x}_{ij})^{-1} \sum_{t=1}^T \mathbf{z}'_{ij} e_{ij}] = 0$$

- ▶ Each estimated b_i is bound to manifest some degree of finite sample bias (Bound et al. (1995))

Simulation: Data Generating Process

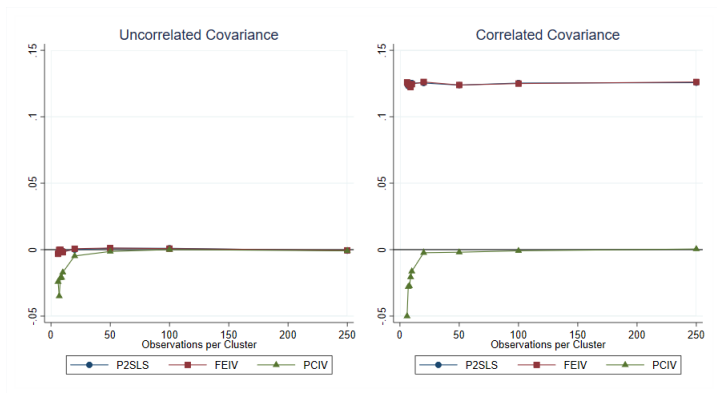
- ▶ We generate the data based on Equation 18 with 500 observations for each cluster
 - ▶ We generate two types of y_{ij} with $\beta_1 = 1$
 - ▶ Uncorrelated covariance assumption is violated with $y_{1,ij}$
 - ▶ Uncorrelated covariance assumption with $y_{2,ij}$

$$y_{1ij} = d_{0i} + (\beta_1 + d_{1i})x_{1ij} + o_{ij} + v_{ij}, \quad v_{1ij} \sim N(0, \sigma_v). \quad (15)$$

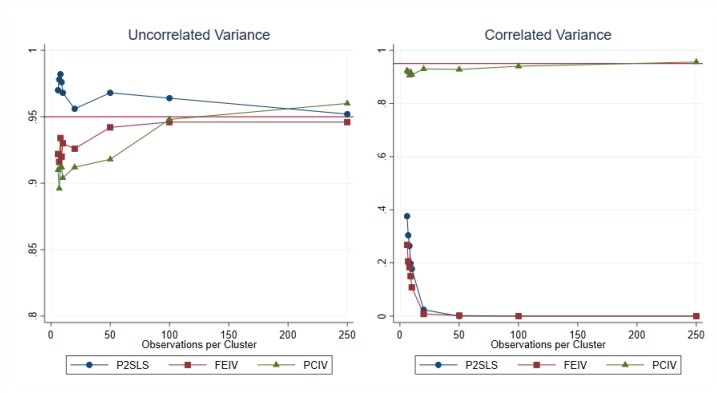
$$y_{2ij} = d_{0i} + (\beta_1 + d_{2i})x_{2ij} + o_{ij} + v_{2ij}, \quad v_{2ij} \sim N(0, \sigma_v). \quad (16)$$

- ▶ x_{ij} is “observed” in the data and is a function $x_{2,it}$, z_{ij} , d_0 , and d_2
- ▶ o_{ij} is exogenous but is “unobserved” in the data creating omitted variables bias
- ▶ $z_{ij} \sim N(0, \sigma_z)$. In order to violate the uncorrelated covariance assumption $\sigma_z = \exp(d_1)$
- ▶ d_0 and d_2 are each drawn from bivariate normal distribution and are allowed to be correlated with each other

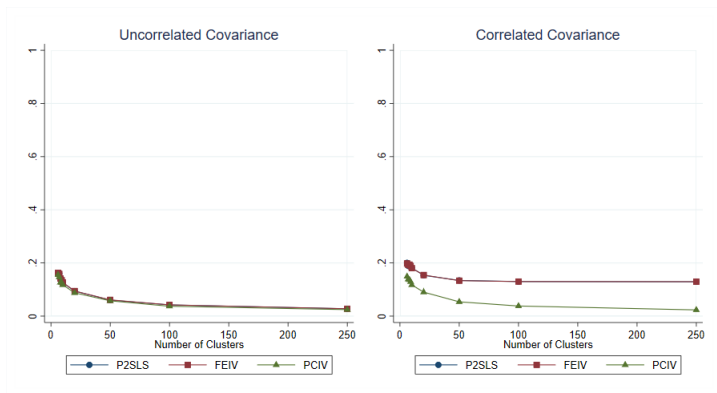
Simulation Results: Bias



Simulation Results: Coverage rate



Simulation Results: RMSE varying N of clusters



PC First Stage

- ▶ PC provides an unbiased estimate of the first stage.

$$\widehat{\gamma}_{PC} = \gamma + N^{-1} \sum_{i=1}^N \mathbf{d}_i + N^{-1} \sum_{i=1}^N [(\sum_{t=1}^T \mathbf{z}'_{ij} \mathbf{z}_{ij})^{-1} (\sum_{t=1}^T \mathbf{z}'_{ij} u_{ij})] \quad (17)$$

- ▶ Allows identification of compliers
- ▶ Tests monotonicity
- ▶ Provides sample analogue to the key assumption behind FEIV

Weighting

Who is the population of interest?

- ▶ Panel data settings: Population from which the sample is drawn
 - ▶ However, panels are rarely random samples: NLSY and PSID both over-sample low income individuals and households
 - ▶ We can still recover PAEs using a weighted average in the last stage
- ▶ Grouped cross-sectional settings: Is the population individuals or groups?
 - ▶ If each groups comprise the population of interest with random sampling simple averaging is fine.
 - ▶ If we are interested in the individuals within groups, population weighted average in the last stage is needed to recover PAEs

Potential applications

Exogenous covariates

Consider the slightly richer model presented below:

$$y_{ij} = \mathbf{x}_{1it}\mathbf{b}_i + \mathbf{x}_{2it}\boldsymbol{\delta} + e_{ij}, \quad t = 1, \dots, T, \quad (18)$$

- ▶ Year fixed effects provide one common and reasonable example of x_{2it}
- ▶ Including these in each regression could lead to the incidental parameters problem, and more generally cut into our degrees of freedom in the per-cluster regressions
- ▶ What to do?
 - ▶ Apply Frisch-Waugh-Lowell to residualize the data
 - ▶ Use residualized data for PCIV estimation

Potential applications

Mechanisms

Consider the following “multi-level model”:

$$\begin{aligned}y_{ij} &= \mathbf{x}_{ij}\mathbf{b}_i + e_{ij}, \\ \mathbf{b}_i &= \boldsymbol{\beta} + \mathbf{w}_i\boldsymbol{\gamma} + \mathbf{d}_i,\end{aligned}\tag{19}$$

where $\mathbf{w}_i = (w_{1i}, \dots, w_{Ji})$ is a vector of observable cluster-level components or mechanisms driving the heterogeneous effects

- ▶ If we assume $E[\mathbf{d}_i\mathbf{w}_i] = 0$ and $E[\mathbf{w}_ie_{ij}] = 0$, we can estimate these mechanisms using PCIV, allowing $E[\mathbf{x}_{ij}\mathbf{w}_i] \neq 0$.
- ▶ To estimate mechanisms:
 - ▶ Estimate cluster specific slopes $\widehat{\mathbf{b}_{i\text{PCIV}}}$ as before ignoring \mathbf{w}_i
 - ▶ In the second stage regress $\widehat{\mathbf{b}_{i\text{PCIV}}}$ on \mathbf{w}_i

Potential applications

Simulation Results Summary

- ▶ Under uncorrelated covariance, PCIV is noisier and seems to manifest additional finite sample bias with very small clusters. Still, with a cluster size of 20 all three estimators perform equally well
- ▶ In contrast, both FEIV and P2SLS are biased when the uncorrelated covariance assumption is violated. PCIV manifests less bias than the other two estimators across cluster sizes
- ▶ The ratio of mean SEs/SDs for PCIV is closest to 1, in both cases of uncorrelated and correlated covariance.

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