xthtaylor — Hausman–Taylor estimator for error-components model

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Description

xthtaylor fits a random-effects model for panel data in which some of the covariates are correlated with the unobserved individual-level random effects. The command implements the Hausman–Taylor estimator by default, but the Amemiya–MaCurdy estimator is available for balanced panels.

Quick start

Hausman–Taylor model of y as a function of time-varying exogenous variable x1, time-invariant binary variable a, and time-varying endogenous variable x2 using xtset data

xthtaylor y x1 x2 a, endog(x2)

Same as above, and verify that a is the only time-invariant variable in the model

xthtaylor y x1 x2 a, endog(x2) constant(a)

Add time-invariant x3 as an endogenous covariate, but do not verify that a and x3 are the only time-invariant variables

xthtaylor y x1 x2 a x3, endog(x2 x3)

Same as above, but use Amemiya-MaCurdy estimator for balanced panels xthtaylor y x1 x2 a x3, endog(x2 x3) am

Menu

Statistics > Longitudinal/panel data > Endogenous covariates > Hausman–Taylor regression (RE)

Syntax

xthtaylor depvar indepvars [if] [in] [weight], endog(varlist) [options]

options	Description
Model	
<u>nocons</u> tant	suppress constant term
* endog(varlist)	explanatory variables in <i>indepvars</i> to be treated as endogenous
$\underline{cons} tant(varlist_{ti})$	independent variables that are constant within panel
<u>v</u> arying(<i>varlist</i> _{tv})	independent variables that are time varying within panel
amacurdy	fit model based on Amemiya and MaCurdy estimator
SE/Robust	
vce(<i>vcetype</i>)	<i>vcetype</i> may be conventional, <u>r</u> obust, <u>cl</u> uster <i>clustvar</i> , <u>boot</u> strap, or <u>jack</u> knife
Reporting	
<u>l</u> evel(#)	set confidence level; default is level(95)
small	report small-sample statistics

*endog(varlist) is required.

A panel variable must be specified. For xthtaylor, amacurdy, a time variable must also be specified. Use xtset; see [XT] xtset.

depvar, indepvars, and all varlists may contain time-series operators; see [U] 11.4.4 Time-series varlists.

by, collect, statsby, and xi are allowed; see [U] 11.1.10 Prefix commands.

iweights and fweights are allowed unless the amacurdy option is specified. Weights must be constant within panel; see [U] 11.1.6 weight.

See [U] 20 Estimation and postestimation commands for more capabilities of estimation commands.

Options

Model

noconstant; see [R] Estimation options.

- endog(*varlist*) specifies that a subset of explanatory variables in *indepvars* be treated as endogenous variables, that is, the explanatory variables that are assumed to be correlated with the unobserved random effect. endog() is required.
- constant (*varlist*_{ti}) specifies the subset of variables in *indepvars* that are time invariant, that is, constant within panel. By using this option, you assert not only that the variables specified in *varlist*_{ti} are time invariant but also that all other variables in *indepvars* are time varying. If this assertion is false, xthtaylor does not perform the estimation and will issue an error message. xthtaylor automatically detects which variables are time invariant and which are not. However, users may want to check their understanding of the data and specify which variables are time invariant and which are not.
- varying (*varlist*_{tv}) specifies the subset of variables in *indepvars* that are time varying. By using this option, you assert not only that the variables specified in *varlist*_{tv} are time varying but also that all other variables in *indepvars* are time invariant. If this assertion is false, xthtaylor does not perform the estimation and will issue an error message. xthtaylor automatically detects which variables are time varying and which are not. However, users may want to check their understanding of the data and specify which variables are time varying and which are not.

amacurdy specifies that the Amemiya-MaCurdy estimator be used. This estimator uses extra instruments to gain efficiency at the cost of additional assumptions on the data-generating process. This option may be specified only for samples containing balanced panels, and weights may not be specified. The panels must also have a common initial period.

SE/Robust

vce(vcetype) specifies the type of standard error reported, which includes types that are derived from asymptotic theory (conventional), that are robust to some kinds of misspecification (robust), that allow for intragroup correlation (cluster *clustvar*), and that use bootstrap or jackknife methods (bootstrap, jackknife); see [XT] vce_options.

vce(conventional), the default, uses the conventionally derived variance estimator for this Hausman-Taylor model.

Specifying vce(robust) is equivalent to specifying vce(cluster *panelvar*); see *xtpoisson*, re and the robust VCE estimator in Methods and formulas of [XT] **xtpoisson**.

Reporting

level(#); see [R] Estimation options.

small specifies that the *p*-values from the Wald tests in the output and all subsequent Wald tests obtained via test use *t* and *F* distributions instead of the large-sample normal and χ^2 distributions. By default, the *p*-values are obtained using the normal and χ^2 distributions.

Remarks and examples

If you have not read [XT] **xt**, please do so.

Consider a random-effects model of the form

 $y_{it} = \mathbf{X}_{1it} \boldsymbol{\beta}_1 + \mathbf{X}_{2it} \boldsymbol{\beta}_2 + \mathbf{Z}_{1i} \boldsymbol{\delta}_1 + \mathbf{Z}_{2i} \boldsymbol{\delta}_2 + \mu_i + \epsilon_{it}$

where

 \mathbf{X}_{1it} is a $1 \times k_1$ vector of observations on exogenous, time-varying variables assumed to be uncorrelated with μ_i and ϵ_{it} ;

 \mathbf{X}_{2it} is a $1 \times k_2$ vector of observations on endogenous, time-varying variables assumed to be (possibly) correlated with μ_i but orthogonal to ϵ_{it} ;

 \mathbf{Z}_{1i} is a $1 \times g_1$ vector of observations on exogenous, time-invariant variables assumed to be uncorrelated with μ_i and ϵ_{it} ;

 \mathbf{Z}_{2i} is a $1 \times g_2$ vector of observations on endogenous, time-invariant variables assumed to be (possibly) correlated μ_i but orthogonal to ϵ_{ii} ;

 μ_i is the unobserved, panel-level random effect that is assumed to have zero mean and finite variance σ_{μ}^2 and to be independent and identically distributed (i.i.d.) over the panels;

 ϵ_{it} is the idiosyncratic error that is assumed to have zero mean and finite variance σ_{ϵ}^2 and to be i.i.d. over all the observations in the data;

 $\beta_1, \beta_2, \delta_1$, and δ_2 are $k_1 \times 1, k_2 \times 1, g_1 \times 1$, and $g_2 \times 1$ coefficient vectors, respectively; and $i = 1, \ldots, n$, where n is the number of panels in the sample and, for each $i, t = 1, \ldots, T_i$.

Because \mathbf{X}_{2it} and \mathbf{Z}_{2i} may be correlated with μ_i , the simple random-effects estimators—xtreg, re and xtreg, mle—are generally not consistent for the parameters in this model. Because the within estimator, xtreg, fe, removes the μ_i by mean-differencing the data before estimating β_1 and β_2 , it is consistent for these parameters. However, in the process of removing the μ_i , the within estimator also eliminates the \mathbf{Z}_{1i} and the \mathbf{Z}_{2i} . Thus it cannot estimate δ_1 nor δ_2 . The Hausman–Taylor and Amemiya–MaCurdy estimators implemented in xthtaylor are designed to resolve this problem.

The within estimator consistently estimates β_1 and β_2 . Using these estimates, we can obtain the within residuals, called \hat{d}_i . Intermediate, albeit consistent, estimates of δ_1 and δ_2 —called $\hat{\delta}_{1IV}$ and $\hat{\delta}_{2IV}$, respectively—are obtained by regressing the within residuals on \mathbf{Z}_{1i} and \mathbf{Z}_{2i} , using \mathbf{X}_{1it} and \mathbf{Z}_{1i} as instruments. The order condition for identification requires that the number of variables in \mathbf{X}_{1it} , k_1 , be at least as large as the number of elements in \mathbf{Z}_{2i} , g_2 and that there be sufficient correlation between the instruments and \mathbf{Z}_{2i} to avoid a weak-instrument problem.

The within estimates of β_1 and β_2 and the intermediate estimates $\hat{\delta}_{11V}$ and $\hat{\delta}_{21V}$ can be used to obtain sets of within and overall residuals. These two sets of residuals can be used to estimate the variance components (see *Methods and formulas* for details).

The estimated variance components can then be used to perform a GLS transform on each of the variables. For what follows, define the general notation \breve{w}_{it} to represent the GLS transform of the variable w_{it}, \overline{w}_i to represent the within-panel mean of w_{it} , and \widetilde{w}_{it} to represent the within transform of w_{it} . With this notational convention, the Hausman–Taylor (1981) estimator of the coefficients of interest can be obtained by the instrumental-variables regression

$$\breve{y}_{it} = \breve{\mathbf{X}}_{1it}\boldsymbol{\beta}_1 + \breve{\mathbf{X}}_{2it}\boldsymbol{\beta}_2 + \breve{\mathbf{Z}}_{1i}\boldsymbol{\delta}_1 + \breve{\mathbf{Z}}_{2i}\boldsymbol{\delta}_2 + \breve{\mu}_i + \breve{\epsilon}_{it}$$
(1)

using $\widetilde{\mathbf{X}}_{1it}, \widetilde{\mathbf{X}}_{2it}, \overline{\mathbf{X}}_{1i}, \overline{\mathbf{X}}_{2i}$, and \mathbf{Z}_{1i} as instruments.

For the instruments to be valid, this estimator requires that $\overline{\mathbf{X}}_{1i}$ and \mathbf{Z}_{1i} be uncorrelated with the random-effect μ_i . More precisely, the instruments are valid when

$$\mathsf{plim}_{n\to\infty}\frac{1}{n}\sum_{i=1}^n\overline{\mathbf{X}}_{1i.}\mu_i=0$$

and

$$\operatorname{plim}_{n\to\infty}\frac{1}{n}\sum_{i=1}^n \mathbf{Z}_{1i}\mu_i = 0$$

Amemiya and MaCurdy (1986) place stricter requirements on the instruments that vary within panels to obtain a more efficient estimator. Specifically, Amemiya and MaCurdy (1986) assume that \mathbf{X}_{1it} is orthogonal to μ_i in every period; that is, $\lim_{n\to\infty} 1/n \sum_{i=1}^n \mathbf{X}_{1it} \mu_i = 0$ for $t = 1, \ldots, T$. With this restriction, they derive the Amemiya-MaCurdy estimator as the instrumental-variables regression of (1) using instruments $\widetilde{\mathbf{X}}_{1it}, \widetilde{\mathbf{X}}_{2it}, \mathbf{X}^*_{1it}$, and \mathbf{Z}_{1i} . The order condition for the Amemiya-MaCurdy estimator is now $Tk_1 > g_2$. xthtaylor uses the Amemiya-MaCurdy estimator when the amacurdy option is specified.

Although the estimators implemented in xthtaylor and xtivreg (see [XT] xtivreg) use the method of instrumental variables, each command is designed for different problems. The estimators implemented in xtivreg assume that a subset of the explanatory variables in the model are correlated with the idiosyncratic error ϵ_{it} . In contrast, the Hausman–Taylor and Amemiya–MaCurdy estimators that are implemented in xthtaylor assume that some of the explanatory variables are correlated with the individual-level random effects, u_i , but that none of the explanatory variables are correlated with the idiosyncratic error, ϵ_{it} .

Example 1

This example replicates the results of Baltagi and Khanti-Akom (1990, table II, column HT) using 595 observations on individuals over 1976–1982 that were extracted from the Panel Study of Income Dynamics (PSID). In the model, the log-transformed wage lwage is assumed to be a function of how long the person has worked for a firm, wks; binary variables indicating whether a person lives in a large metropolitan area or in the south, smsa and south; marital status is ms; years of education, ed; a quadratic of work experience, exp and exp2; occupation, occ; a binary variable indicating employment in a manufacture industry, ind; a binary variable indicating that wages are set by a union contract, union; a binary variable indicating gender, fem; and a binary variable indicating whether the individual is African American, blk.

We suspect that the time-varying variables exp, exp2, wks, ms, and union are all correlated with the unobserved individual random effect. We can inspect these variables to see if they exhibit sufficient within-panel variation to serve as their own instruments.

. xtsum	i exp expz i	wks ms union					
Variabl	e	Mean	Std. dev.	Min	Max	Observation	
exp	overall	19.85378	10.96637	1	51	N =	4165
-	between		10.79018	4	48	n =	595
	within		2.00024	16.85378	22.85378	T =	7
exp2	overall	514.405	496.9962	1	2601	N =	4165
-	between		489.0495	20	2308	n =	595
	within		90.44581	231.405	807.405	T =	7
wks	overall	46.81152	5.129098	5	52	N =	4165
	between		3.284016	31.57143	51.57143	n =	595
	within		3.941881	12.2401	63.66867	T =	7
ms	overall	.8144058	.3888256	0	1	N =	4165
	between		.3686109	0	1	n =	595
	within		.1245274	0427371	1.671549	T =	7
union	overall	.3639856	.4812023	0	1	N =	4165
	between		.4543848	0	1	n =	595
	within		.1593351	4931573	1.221128	T =	7

. use https://www.stata-press.com/data/r19/psidextract

xtsum exp exp2 wks ms union

We are also going to assume that the exogenous variables occ, south, smsa, ind, fem, and blk are instruments for the endogenous, time-invariant variable ed. The output below indicates that although fem appears to be a weak instrument, the remaining instruments are probably sufficiently correlated to identify the coefficient on ed. (See Baltagi and Khanti-Akom [1990] for more discussion.)

. correlate fe (obs=4,165)	em blk occ						
	fem	blk	occ	south	smsa	ind	ed
fem	1.0000						
blk	0.2086	1.0000					
occ	-0.0847	0.0837	1.0000				
south	0.0516	0.1218	0.0413	1.0000			
smsa	0.1044	0.1154	-0.2018	-0.1350	1.0000		
ind	-0.1778	-0.0475	0.2260	-0.0769	-0.0689	1.0000	
ed	-0.0012	-0.1196	-0.6194	-0.1216	0.1843	-0.2365	1.0000

We will assume that the correlations are strong enough and proceed with the estimation. The output below gives the Hausman-Taylor estimates for this model.

<pre>. xthtaylor lwage occ south smsa ind exp exp2 wks ms union fem blk ed, > endog(exp exp2 wks ms union ed)</pre>							
Hausman-Taylo	- r estimation			Number	of obs	=	4,165
Group variable	e: id			Number	of groups	=	595
-				Obs ner	group.		
				opp bor	min	=	7
					ave	- =	7
					max	; =	7
Dandan affaat				17-1-1 -h	+0(10)	_	6001 07
Random effects	s u_1 ~ 1.1.a.			Dreb >	(12(12))	_	0.0000
				Prob >	chiz		0.0000
lwage	Coefficient	Std. err.	z	P> z	[95% cc	onf.	interval]
TVexogenous							
occ	0207047	.0137809	-1.50	0.133	047714	9	.0063055
south	.0074398	.031955	0.23	0.816	055190	8	.0700705
smsa	0418334	.0189581	-2.21	0.027	078990	6	0046761
ind	.0136039	.0152374	0.89	0.372	016260	8	.0434686
TVendogenous							
exp	.1131328	.002471	45.79	0.000	.108289	8	.1179758
exp2	0004189	.0000546	-7.67	0.000	000525	9	0003119
wks	.0008374	.0005997	1.40	0.163	000338	31	.0020129
ms	0298508	.01898	-1.57	0.116	067050	8	.0073493
union	.0327714	.0149084	2.20	0.028	.003551	.4	.0619914
TIexogenous							
fem	1309236	.126659	-1.03	0.301	379170)7	.1173234
blk	2857479	.1557019	-1.84	0.066	590917	'9	.0194221
TIendogenous							
ed	.137944	.0212485	6.49	0.000	.096297	7	.1795902
_cons	2.912726	.2836522	10.27	0.000	2.35677	8	3.468674
sigma_u	.94180304						
sigma_e	.15180273						
rho	.97467788	(fraction	of varia	nce due t	o u_i)		

Note: TV refers to time varying; TI refers to time invariant.

The estimated σ_{μ} and σ_{ϵ} are 0.9418 and 0.1518, respectively, indicating that a large fraction of the total error variance is attributed to μ_i . The z statistics indicate that several the coefficients may not be significantly different from zero. Whereas the coefficients on the time-invariant variables fem and blk have relatively large standard errors, the standard error for the coefficient on ed is relatively small.

Baltagi and Khanti-Akom (1990) also present evidence that the efficiency gains of the Amemiya–MaCurdy estimator over the Hausman–Taylor estimator are small for these data. This point is especially important given the additional restrictions that the estimator places on the data-generating process. The output below replicates the Baltagi and Khanti-Akom (1990) results from column AM of table II.

. xthtaylor lu > endog(exp ez	wage occ south kp2 wks ms uni	. smsa ind e on ed) amac	xp exp2 w urdy	wks ms un	ion fem blk e	ed,
Amemiya-MaCuro Group variable	dy estimation e: id			Number Number	of obs = of groups =	4,165 595
Time variable	• +			Obs ner	group.	
TIME Variable				opp ber	min =	7
					avg =	7
					max =	7
Dondom offort				Wold ab	+0(10) =	6970 00
Random effects	s u_1 ~ 1.1.u.			Drob >	(12(12)) =	0019.20
				FIOD >		0.0000
lwage	Coefficient	Std. err.	Z	P> z	[95% conf	. interval]
TVexogenous						
000	0208498	.0137653	-1.51	0.130	0478292	.0061297
south	.0072818	.0319365	0.23	0.820	0553126	.0698761
smsa	0419507	.0189471	-2.21	0.027	0790864	0048149
ind	.0136289	.015229	0.89	0.371	0162194	.0434771
TVendogenous						
exp	.1129704	.0024688	45.76	0.000	.1081316	.1178093
exp2	0004214	.0000546	-7.72	0.000	0005283	0003145
wks	.0008381	.0005995	1.40	0.162	0003368	.002013
ms	0300894	.0189674	-1.59	0.113	0672649	.0070861
union	.0324752	.0148939	2.18	0.029	.0032837	.0616667
TIexogenous						
fem	132008	.1266039	-1.04	0.297	380147	.1161311
blk	2859004	.1554857	-1.84	0.066	5906468	.0188459
TIendogenous						
ed	.1372049	.0205695	6.67	0.000	.0968894	.1775205
_cons	2.927338	.2751274	10.64	0.000	2.388098	3.466578
sigma u	.94180304					
sigma e	.15180273					
rho	.97467788	(fraction	of varia	nce due t	o u_i)	

Note: TV refers to time varying; TI refers to time invariant.

Technical note

We mentioned earlier that insufficient correlation between an endogenous variable and the instruments can give rise to a weak-instrument problem. Suppose that we simulate data for a model of the form

$$y = 3 + 3x_{1a} + 3x_{1b} + 3x_2 + 3z_1 + 3z_2 + u_i + e_{it}$$

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and purposely construct the instruments so that they exhibit little correlation with the endogenous variable z_2 .

. use https://	/www.stata-	press.com	/data/r19	/xthtaylo	r1		
. correlate u: (obs=10,000)	i z1 z2 x1a	x1b x2 e	it				
	ui	z1	z2	x1a	x1b	x2	eit
ui	1.0000						
z1	0.0268	1.0000					
z2	0.8777	0.0286	1.0000				
x1a	-0.0145	0.0065	-0.0034	1.0000			
x1b	0.0026	0.0079	0.0038	-0.0030	1.0000		
x2	0.8765	0.0191	0.7671	-0.0192	0.0037	1.0000	
eit	0.0060	-0.0198	0.0123	-0.0100	-0.0138	0.0092	1.0000

In the output below, weak instruments have serious consequences on the estimates produced by xthtaylor. The estimate of the coefficient on z2 is three times larger than its true value, and its standard error is rather large. Without sufficient correlation between the endogenous variable and its instruments in a given sample, there is insufficient information for identifying the parameter. Also, given the results of Stock, Wright, and Yogo (2002), weak instruments will cause serious size distortions in any tests performed.

. xthtaylor y:	it x1a x1b x2	z1 z2, endo	og(x2 z2)				
Hausman-Taylo	r estimation		Number o	of obs	=	10,000	
Group variable	e: id			Number o	of groups	=	1,000
				Obs per	group:		
				-	mi	n =	10
					av	g =	10
					ma	x =	10
Random effects	s u i ~ i.i.d.			Wald chi	L2(5)	=	24172.91
	-			Prob > o	chi2	=	0.0000
yit	Coefficient	Std. err.	z	P> z	[95% c	onf.	interval]
TVexogenous							
x1a	2.959736	.0330233	89.63	0.000	2.8950	11	3.02446
x1b	2.953891	.0333051	88.69	0.000	2.8886	14	3.019168
TVendogenous							
x2	3.022685	.033085	91.36	0.000	2.9578	39	3.08753
TIexogenous							
z1	2.709179	.587031	4.62	0.000	1.558	62	3.859739
TIendogenous							
z2	9.525973	8.572966	1.11	0.266	-7.2767	32	26.32868
_cons	2.837072	.4276595	6.63	0.000	1.9988	75	3.675269
sigma u	8,729479						
sigma e	3.1657492						
rho	.88377062	(fraction	of varia	nce due to	o u_i)		

Note: TV refers to time varying; TI refers to time invariant.

Example 2

Now let's consider why we might want to specify the $constant(varlist_{ti})$ option. For this example, we will use simulated data. In the output below, we fit a model over the full sample. Note the placement in the output of the coefficient on the exogenous variable x1c.

. use https://www.stata-press.com/data/r19/xthtaylor2

. xthtaylor yit x1a x1b x1c x2 z1 z2, endog(x2 z2)

Hausman-Taylor Group variable	Number Number	of obs of group	= s =	10,000 1,000			
				Obs per	group:		
				- · · · 1 ·	m	in =	10
					а	vg =	10
					m	ax =	10
Random effects	sui~i.i.d.			Wald ch	i2(6)	=	10341.63
Nandom 011000	, a_1 1111a			Prob >	chi2	=	0.0000
yit	Coefficient	Std. err.	z	P> z	[95%	conf.	interval]
TVexogenous							
x1a	3.023647	.0570274	53.02	0.000	2.911	875	3.135418
x1b	2.966666	.0572659	51.81	0.000	2.854	427	3.078905
x1c	.2355318	.123502	1.91	0.057	0065	276	.4775912
TVendogenous							
x2	14.17476	3.128385	4.53	0.000	8.043	234	20.30628
TIexogenous							
z1	1.741709	.4280022	4.07	0.000	.9028	398	2.580578
TIendogenous							
z2	7.983849	.6970903	11.45	0.000	6.617	577	9.350121
_cons	2.146038	.3794179	5.66	0.000	1.402	393	2.889684
sigma_u	5.6787791						
sigma_e	3.1806188						
rho	.76120931	(fraction	of varia	nce due t	o u_i)		

Note: TV refers to time varying; TI refers to time invariant.

Now suppose that we want to fit the model using only the first eight periods. Below, x1c now appears under the TIexogenous heading rather than the TVexogenous heading because x1c is time invariant in the subsample defined by t<9.

. xthtaylor y	it x1a x1b x1c	x2 z1 z2 i	f t<9, e	ndog(x2 z2)		
Hausman-Taylor Group variable	r estimation e: id			Number of Number of	obs = groups =	8,000 1,000
				Obs per gr	oup:	
				F 8-	min =	8
					avg =	8
					max =	8
Random effects	s u i ~ i.i.d.			Wald chi2((6) =	15354.87
	-			Prob > chi	.2 =	0.0000
yit	Coefficient	Std. err.	z	P> z	[95% conf.	interval]
TVexogenous						
x1a	3.051966	.0367026	83.15	0.000	2.98003	3.123901
x1b	2.967822	.0368144	80.62	0.000	2.895667	3.039977
TVendogenous						
x2	.7361217	3.199764	0.23	0.818	-5.5353	7.007543
TIexogenous						
x1c	3.215907	.5657191	5.68	0.000	2.107118	4.324696
z1	3.347644	.5819756	5.75	0.000	2.206992	4.488295
TIendogenous						
z2	2.010578	1.143982	1.76	0.079	231586	4.252742
_cons	3.257004	.5295828	6.15	0.000	2.219041	4.294967
sigma_u	15.445594					
sigma_e	3.175083					
rho	.95945606	(fraction	of varia	nce due to u	ı_i)	

Note: TV refers to time varying; TI refers to time invariant.

To prevent a variable from becoming time invariant, you can use either $constant(varlist_{ti})$ or $varying(varlist_{tv})$. $constant(varlist_{ti})$ specifies the subset of variables in varlist that are time invariant and requires the remaining variables in varlist to be time varying. If you specify $constant(varlist_{ti})$ and any of the variables contained in varlist_{ti} are time varying, or if any of the variables not contained in varlist_{ti} are time invariant, $varlist_{ti}$ are time invariant, $varlist_{ti}$ are time invariant, $varlist_{ti}$ are time varying. If you specify $constant(varlist_{ti})$ and any of the variables contained in $varlist_{ti}$ are time varying, or if any of the variables not contained in $varlist_{ti}$ are time invariant, $varlist_{ti}$ are time invariant.

```
. xthtaylor yit x1a x1b x1c x2 z1 z2 if t<9, endog(x2 z2) constant(z1 z2)
x1c not included in constant().
r(198);</pre>
```

The same thing happens when you use the varying $(varlist_{tv})$ option.

4

Stored results

xthtaylor stores the following in e():

~ .	
Scal	lars

	e(N)	number of observations
	e(N_g)	number of groups
	e(df_m)	model degrees of freedom
	e(df_r)	residual degrees of freedom (small only)
	e(g_min)	smallest group size
	e(g_avg)	average group size
	e(g_max)	largest group size
	e(Tcon)	1 if panels balanced, 0 otherwise
	e(N_clust)	number of clusters
	e(sigma_u)	panel-level standard deviation
	e(sigma_e)	standard deviation of ϵ_{it}
	e(chi2)	χ^2
	e(rho)	ho
	e(F)	model $F(\text{small only})$
	e(Tbar)	harmonic mean of group sizes
	e(rank)	rank of e(V)
Mac	ros	
	e(cmd)	xthtaylor
	e(cmdline)	command as typed
	e(depvar)	name of dependent variable
	e(ivar)	variable denoting groups
	e(tvar)	variable denoting time within groups, amacurdy only
	e(TVexogenous)	exogenous time-varying variables
	e(TIexogenous)	exogenous time-invariant variables
	e(TVendogenous)	endogenous time-varying variables
	e(TIendogenous)	endogenous time-invariant variables
	e(wtype)	weight type
	e(wexp)	weight expression
	e(title)	Hausman-Taylor or Amemiya-MaCurdy
	e(clustvar)	name of cluster variable
	e(chi2type)	Wald; type of model χ^2 test
	e(vce)	vcetype specified in vce()
	e(vcetype)	title used to label Std. err.
	e(properties)	b V
	e(predict)	program used to implement predict
Mat	rices	
	e(b)	coefficient vector
	e(V)	variance-covariance matrix of the estimators
	e(V_modelbased)	model-based variance
Fund	ctions	
	e(sample)	marks estimation sample
		······

Methods and formulas

Consider an error-components model of the form

$$y_{it} = \mathbf{X}_{1it}\boldsymbol{\beta}_1 + \mathbf{X}_{2it}\boldsymbol{\beta}_2 + \mathbf{Z}_{1i}\boldsymbol{\delta}_1 + \mathbf{Z}_{2i}\boldsymbol{\delta}_2 + \mu_i + \epsilon_{it}$$
(2)

for i = 1, ..., n and, for each $i, t = 1, ..., T_i$, of which T_i periods are observed; n is the number of panels in the sample. The covariates in **X** are time varying, and the covariates in **Z** are time invariant. Both **X** and **Z** are decomposed into two parts. The covariates in **X**₁ and **Z**₁ are assumed to be uncorrelated with μ_i and e_{it} , whereas the covariates in **X**₂ and **Z**₂ are allowed to be correlated with μ_i but not with ϵ_{it} . Hausman and Taylor (1981) suggest an instrumental-variable estimator for this model.

For some variable w, the within transformation of w is defined as

$$\widetilde{w}_{it} = w_{it} - \overline{w}_{i.} \qquad \overline{w}_{i.} = \frac{1}{T_i} \sum_{t=1}^{T_i} w_{it}$$

Because the within estimator removes \mathbf{Z} , the within transformation reduces the model to

$$\tilde{y}_{it} = \widetilde{\mathbf{X}}_{1it} \boldsymbol{\beta}_1 + \tilde{\mathbf{X}}_{2it} \boldsymbol{\beta}_2 + \tilde{\epsilon}_{it}$$

The within estimators $\hat{\beta}_{1w}$ and $\hat{\beta}_{2w}$ are consistent for β_1 and β_2 , but they may not be efficient. Also, note that the within estimator cannot estimate δ_1 and δ_2 .

From the within estimator, we can obtain an estimate of the idiosyncratic error component, σ_{ϵ}^2 , as

$$\hat{\sigma}_{\epsilon}^2 = \frac{\mathrm{RSS}}{N-n}$$

where RSS is the residual sum of squares from the within regression and N is the total number of observations in the sample.

Using the results of the within estimation, we can define

$$\overline{d}_{it} = \overline{y}_{it} - \overline{X}_{1it}\hat{\beta}_{1w} - \overline{X}_{2it}\hat{\beta}_{2w}$$

where $\overline{y}_{it}, \overline{X}_{1it}$, and \overline{X}_{2it} contain the panel level means of these variables in all observations.

Regressing \overline{d}_{it} on \mathbf{Z}_1 and \mathbf{Z}_2 , using \mathbf{X}_1 and \mathbf{Z}_1 as instruments, provides intermediate, consistent estimates of $\boldsymbol{\delta}_1$ and $\boldsymbol{\delta}_2$, which we will call $\hat{\boldsymbol{\delta}}_{1IV}$ and $\hat{\boldsymbol{\delta}}_{2IV}$.

Using the within estimates, $\hat{\delta}_{1IV}$, and $\hat{\delta}_{2IV}$, we can obtain an estimate of the variance of the random effect, σ_{μ}^2 . First, let

$$\hat{e}_{it} = \left(y_{it} - \mathbf{X}_{1it}\widehat{\boldsymbol{\beta}}_{1w} - \mathbf{X}_{2it}\widehat{\boldsymbol{\beta}}_{2w} - \mathbf{Z}_{1it}\widehat{\boldsymbol{\delta}}_{1\mathrm{IV}} - \mathbf{Z}_{2it}\widehat{\boldsymbol{\delta}}_{2\mathrm{IV}}\right)$$

Then define

$$s^{2} = \frac{1}{N} \sum_{i=1}^{n} \sum_{t=1}^{T_{i}} \left(\frac{1}{T_{i}} \sum_{t=1}^{T_{i}} \hat{e}_{it} \right)^{2}$$

Hausman and Taylor (1981) showed that, for balanced panels,

$${\rm plim}_{n\to\infty}s^2=T\sigma_{\mu}^2+\sigma_{\epsilon}^2$$

For unbalanced panels,

$$\mathsf{plim}_{n\to\infty}s^2 = \overline{T}\sigma_\mu^2 + \sigma_\epsilon^2$$

where

$$\overline{T} = \frac{n}{\sum_{i=1}^{n} \frac{1}{T_i}}$$

After we plug in $\hat{\sigma}_{\epsilon}^2$, our consistent estimate for σ_{ϵ}^2 , a little algebra suggests the estimate

$$\hat{\sigma}_{\mu}^2 = (s^2 - \hat{\sigma}_{\epsilon}^2)(\overline{T})^{-1}$$

Define $\hat{\theta}_i$ as

$$\hat{\theta}_i = 1 - \left(\frac{\hat{\sigma}_{\epsilon}^2}{\hat{\sigma}_{\epsilon}^2 + T_i \hat{\sigma}_{\mu}^2}\right)^{\frac{1}{2}}$$

With $\hat{\theta}_i$ in hand, we can perform the standard random-effects GLS transform on each of the variables. The transform is given by

$$w_{it}^* = w_{it} - \widehat{\theta_i} \overline{w}_{i.}$$

where \overline{w}_i is the within-panel mean.

We can then obtain the Hausman–Taylor estimates of the coefficients in (2) and the conventional VCE by fitting an instrumental-variables regression of the GLS-transformed y_{it}^* on \mathbf{X}_{it}^* and \mathbf{Z}_{it}^* , with instruments $\widetilde{\mathbf{X}}_{it}, \overline{\mathbf{X}}_{1i}$, and \mathbf{Z}_{1i} .

We can obtain Amemiya–MaCurdy estimates of the coefficients in (2) and the conventional VCE by fitting an instrumental-variables regression of the GLS-transformed y_{it}^* on \mathbf{X}_{it}^* and \mathbf{Z}_{it}^* , using $\widetilde{\mathbf{X}}_{it}$, \mathbf{X}_{1it} , and \mathbf{Z}_{1i} as instruments, where $\mathbf{X}_{1it} = \mathbf{X}_{1i1}, \mathbf{X}_{1i2}, \ldots, \mathbf{X}_{1iT_i}$. The order condition for the Amemiya–MaCurdy estimator is $Tk_1 > g_2$, and this estimator is available only for balanced panels.

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Also see

- [XT] xthtaylor postestimation Postestimation tools for xthtaylor
- [XT] xtivreg Instrumental variables and two-stage least squares for panel-data models
- [XT] **xtreg** Linear models for panel data
- [XT] **xtset** Declare data to be panel data

[U] 20 Estimation and postestimation commands

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