Title

> **varlmar** — LM test for residual autocorrelation after var or svar

Description

varlmar implements a Lagrange multiplier (LM) test for autocorrelation in the residuals of VAR models, which was presented in Johansen (1995).

Quick start

Test the null hypothesis of no autocorrelation for the first two lags of the residuals after var or svar

    varlmar

As above, but test the first 5 lags

    varlmar, mlag(5)

Perform test for the first two lags of the residuals of a vector autoregression using estimation results stored in myest

    varlmar, estimates(myest)

Menu

Statistics > Multivariate time series > VAR diagnostics and tests > LM test for residual autocorrelation

Syntax

> varlmar [, *options*]

options	Description
<u>ml</u>ag(*#*)	use *#* for the maximum order of autocorrelation; default is mlag(2)
estimates(*estname*)	use previously stored results *estname*; default is to use active results
<u>sep</u>arator(*#*)	draw separator line after every *#* rows

varlmar can be used only after var or svar; see [TS] **var** and [TS] **var svar**.

You must tsset your data before using varlmar; see [TS] **tsset**.

collect is allowed; see [U] **11.1.10 Prefix commands**.

Options

mlag(*#*) specifies the maximum order of autocorrelation to be tested. The integer specified in mlag() must be greater than 0; the default is 2.

estimates(*estname*) requests that varlmar use the previously obtained set of var or svar estimates stored as *estname*. By default, varlmar uses the active results. See [R] **estimates** for information on manipulating estimation results.

separator(*#*) specifies how often separator lines should be drawn between rows. By default, separator lines do not appear. For example, separator(1) would draw a line between each row, separator(2) between every other row, and so on.

Remarks and examples

[stata.com]

Most postestimation analyses of VAR models and SVAR models assume that the disturbances are not autocorrelated. varlmar implements the LM test for autocorrelation in the residuals of a VAR model discussed in Johansen (1995, 21–22). The test is performed at lags $j = 1, \ldots, \text{mlag}()$. For each j, the null hypothesis of the test is that there is no autocorrelation at lag j.

varlmar uses the estimation results stored by var or svar. By default, varlmar uses the active estimation results. However, varlmar can use any previously stored var or svar estimation results specified in the estimates() option.

▷ Example 1: After var

Here we refit the model with German data described in [TS] **var** and then call `varlmar`.

```
. use https://www.stata-press.com/data/r17/lutkepohl2
(Quarterly SA West German macro data, Bil DM, from Lutkepohl 1993 Table E.1)
. var dln_inv dln_inc dln_consump if qtr<=tq(1978q4), dfk
  (output omitted )
. varlmar, mlag(5)
```

   Lagrange-multiplier test

lag	chi2	df	Prob > chi2
1	5.5871	9	0.78043
2	6.3189	9	0.70763
3	8.4022	9	0.49418
4	11.8742	9	0.22049
5	5.2914	9	0.80821

   H0: no autocorrelation at lag order

Because we cannot reject the null hypothesis that there is no autocorrelation in the residuals for any of the five orders tested, this test gives no hint of model misspecification. Although we fit the VAR with the `dfk` option to be consistent with the example in [TS] **var**, `varlmar` always uses the ML estimator of Σ. The results obtained from `varlmar` are the same whether or not `dfk` is specified.

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▷ Example 2: After svar

When `varlmar` is applied to estimation results produced by `svar`, the sequence of LM tests is applied to the underlying VAR. See [TS] **var svar** for a description of how an SVAR model builds on a VAR. In this example, we fit an SVAR that has an underlying VAR with two lags that is identical to the one fit in the previous example.

```
. matrix A = (.,.,0\0,.,0\.,.,.)
. matrix B = I(3)
. svar dln_inv dln_inc dln_consump if qtr<=tq(1978q4), dfk aeq(A) beq(B)
  (output omitted )
. varlmar, mlag(5)
```

   Lagrange-multiplier test

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   H0: no autocorrelation at lag order

Because the underlying VAR(2) is the same as the previous example (we assure you that this is true), the output from `varlmar` is also the same.

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Stored results

varlmar stores the following in r():

Matrices
    r(lm) χ^2, df, and p-values

Methods and formulas

The formula for the LM test statistic at lag j is

$$\text{LM}_s = (T - d - 0.5)\ln\left(\frac{|\widehat{\Sigma}|}{|\widetilde{\Sigma}_s|}\right)$$

where T is the number of observations in the VAR; d is explained below; $\widehat{\Sigma}$ is the maximum likelihood estimate of Σ, the variance–covariance matrix of the disturbances from the VAR; and $\widetilde{\Sigma}_s$ is the maximum likelihood estimate of Σ from the following augmented VAR.

If there are K equations in the VAR, we can define $\mathbf{e}_t$ to be a $K \times 1$ vector of residuals. After we create the K new variables e1, e2, ..., eK containing the residuals from the K equations, we can augment the original VAR with lags of these K new variables. For each lag s, we form an augmented regression in which the new residual variables are lagged s times. Per the method of Davidson and MacKinnon (1993, 358), the missing values from these s lags are replaced with zeros. $\widetilde{\Sigma}_s$ is the maximum likelihood estimate of Σ from this augmented VAR, and d is the number of coefficients estimated in the augmented VAR. See [TS] **var** for a discussion of the maximum likelihood estimate of Σ in a VAR.

The asymptotic distribution of LM$_s$ is χ^2 with K^2 degrees of freedom.

References

Davidson, R., and J. G. MacKinnon. 1993. *Estimation and Inference in Econometrics*. New York: Oxford University Press.

Johansen, S. 1995. *Likelihood-Based Inference in Cointegrated Vector Autoregressive Models*. Oxford: Oxford University Press.

Also see

[TS] **var** — Vector autoregressive models

[TS] **var intro** — Introduction to vector autoregressive models

[TS] **var svar** — Structural vector autoregressive models

[TS] **varbasic** — Fit a simple VAR and graph IRFs or FEVDs