megIm postestimation — Postestimation tools for megIm

Postestimation commands	predict	margins	Remarks and examples
Methods and formulas	References	Also see	

Postestimation commands

The following postestimation command is of special interest after meglm:

Command	Description
estat group	summarize the composition of the nested groups
estat icc	estimate intraclass correlations
estat sd	display variance components as standard deviations and correlations

The following standard postestimation commands are also available:

Command	Description
contrast	contrasts and ANOVA-style joint tests of parameters
estat ic	Akaike's, consistent Akaike's, corrected Akaike's, and Schwarz's Bayesian in- formation criteria (AIC, CAIC, AICc, and BIC, respectively)
estat summarize	summary statistics for the estimation sample
estat vce	variance-covariance matrix of the estimators (VCE)
estat (svy)	postestimation statistics for survey data
estimates	cataloging estimation results
etable	table of estimation results
* hausman	Hausman's specification test
lincom	point estimates, standard errors, testing, and inference for linear combinations of parameters
* lrtest	likelihood-ratio test
margins	marginal means, predictive margins, marginal effects, and average marginal effects
marginsplot	graph the results from margins (profile plots, interaction plots, etc.)
nlcom	point estimates, standard errors, testing, and inference for nonlinear combina- tions of parameters
predict	means, probabilities, densities, REs, residuals, etc.
predictnl	point estimates, standard errors, testing, and inference for generalized predic- tions
pwcompare	pairwise comparisons of parameters
test	Wald tests of simple and composite linear hypotheses
testnl	Wald tests of nonlinear hypotheses

*hausman and lrtest are not appropriate with svy estimation results.

predict

Description for predict

predict creates a new variable containing predictions such as mean responses; linear predictions; density and distribution functions; standard errors; and raw, Pearson, deviance, and Anscombe residuals.

Menu for predict

Statistics > Postestimation

Syntax for predict

Syntax for obtaining predictions of the outcome and other statistics

```
predict [type] { stub* | newvarlist } [if ] [in ] [, statistic options ]
```

Syntax for obtaining estimated random effects and their standard errors

predict [type] { stub* | newvarlist } [if] [in], reffects [re_options]

Syntax for obtaining ML scores

predict [type] { stub* | newvarlist } [if] [in], scores

statistic	Description
Main	
mu	mean response; the default
pr	synonym for mu for ordinal and binary response models
eta	fitted linear predictor
xb	linear predictor for the fixed portion of the model only
stdp	standard error of the fixed-portion linear prediction
density	predicted density function
distribution	predicted distribution function
residuals	raw residuals; available only with the Gaussian family
pearson	Pearson residuals
deviance	deviance residuals
anscombe	Anscombe residuals

These statistics are available both in and out of sample; type predict ... if e(sample) ... if wanted only for the estimation sample.

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Description
<pre>compute statistic conditional on estimated random effects; default is conditional(ebmeans)</pre>
compute statistic marginally with respect to the random effects
make calculation ignoring offset or exposure
outcome category for predicted probabilities for ordinal models
integration options

pearson, deviance, anscombe may not be combined with marginal.

For ordinal outcomes, you specify one or k new variables in *newvarlist* with mu and pr, where k is the number of outcomes. If you do not specify outcome(), these options assume outcome(#1).

ctype	Description
ebmeans	empirical Bayes means of random effects; the default
<u>ebmode</u> s	empirical Bayes modes of random effects
<u>fixed</u> only	prediction for the fixed portion of the model only
re_options	Description
Main	
<u>ebmean</u> s	use empirical Bayes means of random effects; the default
<u>ebmode</u> s	use empirical Bayes modes of random effects
reses(<i>stub</i> * <i>newvarlist</i>)	calculate standard errors of empirical Bayes estimates
Integration	
int_options	integration options
int_options	Description
<pre>intpoints(#)</pre>	use # quadrature points to compute marginal predictions and empirical Bayes means
<u>iter</u> ate(#)	set maximum number of iterations in computing statistics involving empirical Bayes estimators
<pre>tolerance(#)</pre>	set convergence tolerance for computing statistics involving empirical Bayes estimators

Options for predict

Main

mu, the default, calculates the expected value of the outcome.

pr calculates predicted probabilities and is a synonym for mu. This option is available only for ordinal and binary response models.

eta calculates the fitted linear prediction.

xb calculates the linear prediction $\mathbf{x}\beta$ using the estimated fixed effects (coefficients) in the model. This is equivalent to fixing all random effects in the model to their theoretical (prior) mean value of 0.

stdp calculates the standard error of the fixed-effects linear predictor $\mathbf{x}\beta$.

- density calculates the density function. This prediction is computed using the current values of the observed variables, including the dependent variable.
- distribution calculates the distribution function. This prediction is computed using the current values of the observed variables, including the dependent variable.
- residuals calculates raw residuals, that is, responses minus the fitted values. This option is available only for the Gaussian family.
- pearson calculates Pearson residuals. Pearson residuals that are large in absolute value may indicate a lack of fit.
- deviance calculates deviance residuals. Deviance residuals are recommended by McCullagh and Nelder (1989) as having the best properties for examining the goodness of fit of a GLM. They are approximately normally distributed if the model is correctly specified. They can be plotted against the fitted values or against a covariate to inspect the model fit.
- anscombe calculates Anscombe residuals, which are designed to closely follow a normal distribution.
- conditional (ctype) and marginal specify how random effects are handled in computing statistic.
 - conditional() specifies that *statistic* will be computed conditional on specified or estimated random effects.
 - conditional (ebmeans), the default, specifies that empirical Bayes means be used as the estimates of the random effects. These estimates are also known as posterior mean estimates of the random effects.
 - conditional(ebmodes) specifies that empirical Bayes modes be used as the estimates of the random effects. These estimates are also known as posterior mode estimates of the random effects.
 - conditional(fixedonly) specifies that all random effects be set to zero, equivalent to using only the fixed portion of the model.
 - marginal specifies that the predicted *statistic* be computed marginally with respect to the random effects, which means that *statistic* is calculated by integrating the prediction function with respect to all the random effects over their entire support.

Although this is not the default, marginal predictions are often very useful in applied analysis. They produce what are commonly called population-averaged estimates. They are also required by margins.

- nooffset is relevant only if you specified offset(*varname_o*) or exposure(*varname_e*) with meglm. It modifies the calculations made by predict so that they ignore the offset or the exposure variable; the linear prediction is treated as $X\beta + Zu$ rather than $X\beta + Zu + \text{offset}$, or $X\beta + Zu + \ln(\text{exposure})$, whichever is relevant.
- outcome (*outcome*) specifies the outcome for which the predicted probabilities are to be calculated. outcome() should contain either one value of the dependent variable or one of #1, #2, ..., with #1 meaning the first category of the dependent variable, #2 meaning the second category, etc.

reffects calculates estimates of the random effects using empirical Bayes predictions. By default, or if the ebmeans option is specified, empirical Bayes means are computed. With the ebmodes option, empirical Bayes modes are computed. You must specify q new variables, where q is the number of random-effects terms in the model. However, it is much easier to just specify stub* and let Stata name the variables stub1, stub2, ..., stubq for you.

ebmeans specifies that empirical Bayes means be used to predict the random effects.

ebmodes specifies that empirical Bayes modes be used to predict the random effects.

reses (*stub** | *newvarlist*) calculates standard errors of the empirical Bayes estimators and stores the result in *newvarlist*. This option requires the reffects option. You must specify q new variables, where q is the number of random-effects terms in the model. However, it is much easier to just specify *stub** and let Stata name the variables *stub*1, *stub*2, ..., *stubq* for you. The new variables will have the same storage type as the corresponding random-effects variables.

The reffects and reses() options often generate multiple new variables at once. When this occurs, the random effects (and standard errors) contained in the generated variables correspond to the order in which the variance components are listed in the output of meglm. The generated variables are also labeled to identify their associated random effect.

scores calculates the scores for each coefficient in e(b). This option requires a new variable list of length equal to the number of columns in e(b). Otherwise, use the *stub** syntax to have predict generate enumerated variables with prefix *stub*.

Integration

- intpoints(#) specifies the number of quadrature points used to compute marginal predictions and the empirical Bayes means; the default is the value from estimation.
- iterate(#) specifies the maximum number of iterations when computing statistics involving empirical Bayes estimators; the default is the value from estimation.
- tolerance(#) specifies convergence tolerance when computing statistics involving empirical Bayes estimators; the default is the value from estimation.

margins

Description for margins

margins estimates margins of response for mean responses and linear predictions.

Menu for margins

Statistics > Postestimation

Syntax for margins

margins [marginlist] [, options]					
margins [marginlist]	<pre>margins [marginlist], predict(statistic) [predict(statistic)] [options]</pre>				
statistic	Description				
mu	mean response; the default				
pr	synonym for mu for ordinal and binary response models				
eta	fitted linear predictor				
xb	linear predictor for the fixed portion of the model only				
stdp	not allowed with margins				
<u>den</u> sity	not allowed with margins				
<u>dist</u> ribution	not allowed with margins				
<u>res</u> iduals	not allowed with margins				
pearson	not allowed with margins				
deviance	not allowed with margins				
<u>ans</u> combe	not allowed with margins				
reffects	not allowed with margins				
scores	not allowed with margins				

Options conditional (ebmeans) and conditional (ebmodes) are not allowed with margins.

Option marginal is assumed where applicable if conditional(fixedonly) is not specified.

Statistics not allowed with margins are functions of stochastic quantities other than e(b).

For the full syntax, see [R] margins.

Remarks and examples

Various predictions, statistics, and diagnostic measures are available after fitting a mixed-effects model using meglm. For the most part, calculation centers around obtaining predictions of the random effects. Random effects are not estimated when the model is fit but instead need to be predicted after estimation.

Example 1: Obtaining estimates of random effects

In example 2 of [ME] **meglm**, we modeled the probability of contraceptive use among Bangladeshi women by fitting a mixed-effects logistic regression model. To facilitate a more direct comparison between urban and rural women, we specify no base level for the urban factor variable and eliminate the constant from both the fixed-effects part and the random-effects part.

. use https://www.stata-press.com/data/r19/bangladesh (Bangladesh Fertility Survey, 1989) . meglm c use ibn.urban age i.children, nocons nolog > || district: ibn.urban, nocons family(bernoulli) link(logit) nofvlabel Mixed-effects GLM Number of obs 1,934 = Family: Bernoulli Link: Logit Group variable: district Number of groups = 60 Obs per group: 2 min = avg = 32.2 max = 118 Integration pts. 7 Integration method: mvaghermite = Wald chi2(6) = 120.59 Log likelihood = -1199.3268 Prob > chi2 _ 0.0000 (1) $[c_use]_cons = 0$ Coefficient Std. err. P>|z| [95% conf. interval] c_use z urban .1603689 -10.68 0 -1.7125490.000 -2.026866-1.3982321 -.9004495 .1674683 -5.38 0.000 -1.228681-.5722176-.0264472 .0080196 -3.30 0.001 -.0421652 -.0107291 age children 1.132291 .1603052 7.06 0.000 .8180983 1.446483 1 2 1.358692 .1769369 7.68 0.000 1.011902 1.705482 1.354788 .1827459 7.41 0.000 .9966122 1.712963 3 _cons 0 (omitted) district var(0.urban) .3882825 .1284858 .2029918 .7427064 var(1.urban) .239777 .1403374 .0761401 .7550947 LR test vs. logistic model: chi2(2) = 58.40 Prob > chi2 = 0.0000

Note: LR test is conservative and provided only for reference.

This particular model allows for district random effects that are specific to the rural and urban areas of that district and that can be interpreted as such. We can obtain predictions of posterior means of the random effects and their standard errors by typing

```
. predict re_rural re_urban, reffects reses(se_rural se_urban)
(calculating posterior means of random effects)
(using 7 quadrature points)
```

The order in which we specified the variables to be generated corresponds to the order in which the variance components are listed in meglm output. If in doubt, a simple describe will show how these newly generated variables are labeled just to be sure.

Having generated estimated random effects and standard errors, we can now list them for the first 10 districts:

```
. by district, sort: generate tag = (_n==1)
. list district re_rural se_rural re_urban se_urban if district <= 10 & tag,
> sep(0)
```

	district	re_rural	se_rural	re_urban	se_urban
1.	1	9523374	.316291	5619418	.2329456
118.	2	0425217	.3819309	1.01e-17	.4896702
138.	3	4.29e-18	.6231232	.2229486	.4658747
140.	4	2703357	.3980832	.574464	.3962131
170.	5	.0691029	.3101591	.0074569	.4650451
209.	6	3939819	.2759802	.2622263	.4177785
274.	7	1904756	.4043461	-7.77e-18	.4896702
292.	8	.0382993	.3177392	.2250237	.4654329
329.	9	3715211	.3919996	.0628076	.453568
352.	10	5624707	.4763545	1.00e-18	.4896702

The estimated standard errors are conditional on the values of the estimated model parameters: β and the components of Σ . Their interpretation is therefore not one of standard sample-to-sample variability but instead one that does not incorporate uncertainty in the estimated model parameters; see *Methods and formulas*. That stated, conditional standard errors can still be used as a measure of relative precision, provided that you keep this caveat in mind.

You can also obtain predictions of posterior modes and compare them with the posterior means:

```
. predict mod_rural mod_urban, reffects ebmodes
(calculating posterior modes of random effects)
. list district re_rural mod_rural re_urban mod_urban if district <= 10 & tag,
> sep(0)
```

	district	re_rural	mod_rural	re_urban	mod_urban
1. 118.	1	9523374 0425217	9295366 0306312	5619418 1.01e-17	5584528 0
138.	3	4.29e-18	0300312	.2229486	. 2223551
140.	4	2703357	2529507	.574464	.5644512
170.	5	.0691029	.0789803	.0074569	.0077525
209.	6	3939819	3803784	.2622263	.2595116
274. 292.	7	1904756 .0382993	1737696 .0488528	-7.77e-18 .2250237	0 .2244676
329.	9	3715211	3540084	.0628076	.0605462
352.	10	5624707	535444	1.00e-18	0

The two sets of predictions are fairly close.

Because not all districts contain both urban and rural areas, some of the posterior modes are 0 and some of the posterior means are practically 0. A closer examination of the data reveals that district 3 has no rural areas, and districts 2, 7, and 10 have no urban areas.

Had we imposed an unstructured covariance structure in our model, the estimated posterior modes and posterior means in the cases in question would not be exactly 0 because of the correlation between urban and rural effects. For instance, if a district has no urban areas, it can still yield a nonzero (albeit small) random-effects estimate for a nonexistent urban area because of the correlation with its rural counterpart; see example 2 of [ME] melogit postestimation for details.

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Example 2: Calculating predicted probabilities

Continuing with the model from example 1, we can obtain predicted probabilities, and unless we specify the fixedonly option, these predictions will incorporate the estimated subject-specific random effects $\tilde{\mathbf{u}}_{i}$.

```
. predict pr, pr
(predictions based on fixed effects and posterior means of random effects)
(using 7 quadrature points)
```

The predicted probabilities for observation i in cluster j are obtained by applying the inverse link function to the linear predictor, $\hat{p}_{ij} = g^{-1}(\mathbf{x}_{ij}\hat{\boldsymbol{\beta}} + \mathbf{z}_{ij}\tilde{\mathbf{u}}_j)$; see Methods and formulas for details. By default or with the conditional (ebmeans) option, the calculation uses posterior means for $\tilde{\mathbf{u}}_j$. You

can use the conditional (ebmodes) option to obtain predictions based on the posterior modes for $\tilde{\tilde{u}}_{i}$.

```
. predict prm, pr conditional(ebmodes)
(predictions based on fixed effects and posterior modes of random effects)
```

We can list the two sets of predicted probabilities together with the actual outcome for some district, let's say district 38:

	c_use	pr	prm
1228.	Yes	.5783408	.5780864
1229.	No	.5326623	.5324027
1230.	Yes	.6411679	.6409279
1231.	Yes	.5326623	.5324027
1232.	Yes	.5718783	.5716228
1233.	No	.3447686	.344533
1234.	No	.4507973	.4505391
1235.	No	.1940524	.1976133
1236.	No	.2846738	.2893007
1237.	No	.1264883	.1290078
1238.	No	.206763	.2104961
1239.	No	.202459	.2061346
1240.	No	.206763	.2104961
1241.	No	.1179788	.1203522

. list c use pr prm if district == 38

The two sets of predicted probabilities are fairly close.

For mixed-effects models with many levels or many random effects, the calculation of the posterior means of random effects or any quantities that are based on the posterior means of random effects may take a long time. This is because we must resort to numerical integration to obtain the posterior means. In contrast, the calculation of the posterior modes of random effects is usually orders of magnitude faster because there is no numerical integration involved. For this reason, empirical modes are often used in practice as an approximation to empirical means. Note that for linear mixed-effects models, the two predictors are the same.

We can compare the observed values with the predicted values by constructing a classification table. Defining success as $\hat{y}_{ij} = 1$ if $\hat{p}_{ij} > 0.5$ and defining $\hat{y}_{ij} = 0$ otherwise, we obtain the following table.

- . generate p_use = pr > .5
- . label var p_use "Predicted outcome"
- . tab2 c_use p_use, row
- -> tabulation of c_use by p_use

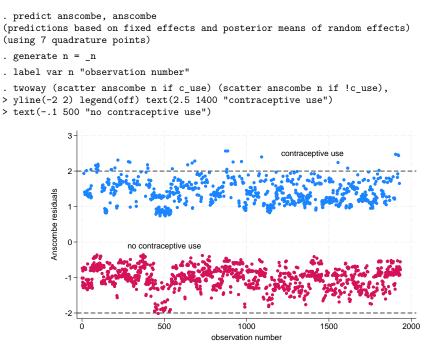
Кеу
frequency
row percentage

Use contracept ion	Predicte	d outcome 1	Total
No	991	184	1,175
	84.34	15.66	100.00
Yes	423	336	759
	55.73	44.27	100.00
Total	1,414	520	1,934
	73.11	26.89	100.00

The model correctly classified 84% of women who did not use contraceptives but only 44% of women who did. In the next example, we will look at some residual diagnostics.

Example 3: A look at residual diagnostics

Continuing our discussion from example 2, here we look at residual diagnostics. meglm offers three kinds of predicted residuals for nonlinear responses—Pearson, Anscombe, and deviance. Of the three, Anscombe residuals are designed to be approximately normally distributed; thus we can check for outliers by plotting Anscombe residuals against observation numbers and seeing which residuals are greater than 2 in absolute value.



There seem to be some outliers among residuals that identify women who use contraceptives. We could examine the observations corresponding to the outliers, or we could try fitting a model with perhaps a different covariance structure, which we leave as an exercise.

Example 4: Using predicted random effects for ranking purposes

In example 3 of [ME] **meglm**, we estimated the effects of two treatments on the tobacco and health knowledge (THK) scale score of students in 28 schools. The dependent variable was collapsed into four ordered categories, and we fit a three-level ordinal logistic regression.

```
. use https://www.stata-press.com/data/r19/tvsfpors, clear
(Television, School, and Family Project)
. meologit thk prethk i.cc##i.tv || school: || class:
Fitting fixed-effects model:
Iteration 0: Log likelihood = -2212.775
Iteration 1: Log likelihood = -2125.509
Iteration 2: Log likelihood = -2125.1034
Iteration 3: Log likelihood = -2125.1032
Refining starting values:
Grid node 0: Log likelihood = -2152.1514
Fitting full model:
(content project)
```

(output omitted)

Mixed-effects ologit regression

```
Number of obs = 1,600
```

Grouping information

		No. of	Obse	rvations	per gr		
Group variable		groups	Minimum		1 0	Jayimum	
	school	28	18	5	7.1	137	
	class	135	1	1	1.9	28	
Integration me	ethod: mvagher	rmite		Integra	tion pt:	s. =	7
				Wald ch	i2(4)	=	124.39
Log likelihood	d = -2114.5881			Prob >	chi2	=	0.0000
thk	Coefficient	Std. err.	Z	P> z	[95%	conf.	interval]
prethk	.4085273	.039616	10.31	0.000	. 3308	3814	.4861731
1.cc	.8844369	.2099124	4.21	0.000	.4730	0161	1.295858
1.tv	.236448	.2049065	1.15	0.249	1651	L614	.6380575
cc#tv							
1 1	3717699	.2958887	-1.26	0.209	951	L701	.2081612
/cut1	0959459	.1688988			4269	9815	.2350896
/cut2	1.177478	.1704946			.8433	3151	1.511642
/cut3	2.383672	.1786736			2.033	3478	2.733865
school							
<pre>var(_cons)</pre>	.0448735	.0425387			.0069	9997	.2876749
school>class							
<pre>var(_cons)</pre>	.1482157	.0637521			.063	3792	.3443674
LR test vs. of	logit model: d	chi2(2) = 21	.03		Prob	> chi2	= 0.0000

Note: LR test is conservative and provided only for reference.

Not surprisingly, the level of knowledge before the intervention is a good predictor of the level of knowledge after the intervention. The social resistance classroom curriculum is effective in raising the knowledge score, but the TV intervention and the interaction term are not.

We can rank schools by their institutional effectiveness by plotting the random effects at the school level.

```
. predict re_school re_class, reffects reses(se_school se class)
(calculating posterior means of random effects)
(using 7 quadrature points)
. generate lower = re_school - 1.96*se_school
. generate upper = re_school + 1.96*se_school
. egen tag = tag(school)
. gsort +re_school -tag
. generate rank = sum(tag)
. generate labpos = re_school + 1.96*se_school + .1
. twoway (rcap lower upper rank) (scatter re school rank)
> (scatter labpos rank, mlabel(school) msymbol(none) mlabpos(0)),
> xtitle(rank) ytitle(Predicted posterior mean) legend(off)
> xscale(range(0 28)) xlabel(1/28) ysize(2)
            1
         Predicted posterior mean
            5
                                                    414
                                        405 412
            0
           -.5
                       4
                          5
                            6
                               ż
                                 8
                                   9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28
```

Although there is some variability in the predicted posterior means, we cannot see significant differences among the schools in this example.

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Methods and formulas

Continuing the discussion in Methods and formulas of [ME] meglm and using the definitions and formulas defined there, we begin by considering the prediction of the random effects \mathbf{u}_i for the *j*th cluster in a two-level model. Prediction of random effects in multilevel generalized linear models involves assigning values to random effects, and there are many methods for doing so; see Skrondal and Rabe-Hesketh (2009) and Skrondal and Rabe-Hesketh (2004, chap. 7) for a comprehensive review. Stata offers two methods of predicting random effects: empirical Bayes means (also known as posterior means) and empirical Bayes modes (also known as posterior modes). Below we provide more details about the two methods.

Let $\hat{\theta}$ denote the estimated model parameters comprising $\hat{\beta}$ and the unique elements of $\hat{\Sigma}$. Empirical Bayes (EB) predictors of the random effects are the means or modes of the empirical posterior distribution with the parameter estimates θ replaced with their estimates θ . The method is called "empirical" because $\hat{\theta}$ is treated as known. EB combines the prior information about the random effects with the likelihood to obtain the conditional posterior distribution of random effects. Using Bayes's theorem, the empirical conditional posterior distribution of random effects for cluster j is

$$\begin{split} \omega(\mathbf{u}_j | \mathbf{y}_j, \mathbf{X}_j, \mathbf{Z}_j; \widehat{\boldsymbol{\theta}}) &= \frac{\Pr(\mathbf{y}_j, \mathbf{u}_j | \mathbf{X}_j, \mathbf{Z}_j; \widehat{\boldsymbol{\theta}})}{\Pr(\mathbf{y}_j | \mathbf{X}_j, \mathbf{Z}_j; \widehat{\boldsymbol{\theta}})} \\ &= \frac{f(\mathbf{y}_j | \mathbf{u}_j, \mathbf{X}_j, \mathbf{Z}_j; \widehat{\boldsymbol{\beta}}) \, \phi(\mathbf{u}_j; \widehat{\boldsymbol{\Sigma}})}{\int f(\mathbf{y}_j | \mathbf{u}_j) \, \phi(\mathbf{u}_j) \, d\mathbf{u}_j} \\ &= \frac{f(\mathbf{y}_j | \mathbf{u}_j, \mathbf{X}_j, \mathbf{Z}_j; \widehat{\boldsymbol{\beta}}) \, \phi(\mathbf{u}_j; \widehat{\boldsymbol{\Sigma}})}{\mathcal{L}_j(\widehat{\boldsymbol{\theta}})} \end{split}$$

The denominator is just the likelihood contribution of the *j*th cluster.

EB mean predictions of random effects, \tilde{u} , also known as posterior means, are calculated as

$$\begin{split} \widetilde{\mathbf{u}} &= \int_{\Re^q} \mathbf{u}_j \, \omega(\mathbf{u}_j | \mathbf{y}_j, \mathbf{X}_j, \mathbf{Z}_j; \widehat{\boldsymbol{\theta}}) \, d\mathbf{u}_j \\ &= \frac{\int_{\Re^q} \mathbf{u}_j \, f(\mathbf{y}_j | \mathbf{u}_j, \mathbf{X}_j, \mathbf{Z}_j; \widehat{\boldsymbol{\beta}}) \, \phi(\mathbf{u}_j; \widehat{\boldsymbol{\Sigma}}) \, d\mathbf{u}_j}{\int_{\Re^q} f(\mathbf{y}_j | \mathbf{u}_j) \, \phi(\mathbf{u}_j) \, d\mathbf{u}_j} \end{split}$$

where we use the notation $\tilde{\mathbf{u}}$ rather than $\hat{\mathbf{u}}$ to distinguish predicted values from estimates. This multivariate integral is approximated by the mean-variance adaptive Gaussian quadrature; see *Methods and formulas* of [ME] **meglm** for details about the quadrature. If you have multiple random effects within a level or random effects across levels, the calculation involves orthogonalizing transformations using the Cholesky transformation because the random effects are no longer independent under the posterior distribution.

In a linear mixed-effects model, the posterior density is multivariate normal, and EB means are also best linear unbiased predictors (BLUPs); see Skrondal and Rabe-Hesketh (2004, 227). In generalized mixed-effects models, the posterior density tends to multivariate normal as cluster size increases.

EB modal predictions can be approximated by solving for the mode $\tilde{\tilde{u}}_i$ in

$$rac{\partial}{\partial \mathbf{u}_j} \log \omega(\widetilde{\widetilde{\mathbf{u}}}_j | \mathbf{y}_j, \mathbf{X}_j, \mathbf{Z}_j; \widehat{oldsymbol{ heta}}) = \mathbf{0}$$

Because the denominator in $\omega(\cdot)$ does not depend on **u**, we can omit it from the calculation to obtain

$$\begin{split} & \frac{\partial}{\partial \mathbf{u}_{j}}\log\left\{f(\mathbf{y}_{j}|\mathbf{u}_{j},\mathbf{X}_{j},\mathbf{Z}_{j};\widehat{\boldsymbol{\beta}})\,\phi(\mathbf{u}_{j};\widehat{\boldsymbol{\Sigma}})\right\}\\ &=\frac{\partial}{\partial \mathbf{u}_{j}}\log f\left(\mathbf{y}_{j}|\mathbf{u}_{j},\mathbf{X}_{j},\mathbf{Z}_{j};\widehat{\boldsymbol{\beta}}\right)+\frac{\partial}{\partial \mathbf{u}_{j}}\log \phi\left(\mathbf{u}_{j};\widehat{\boldsymbol{\Sigma}}\right)=0 \end{split}$$

The calculation of EB modes does not require numerical integration, and for that reason they are often used in place of EB means. As the posterior density gets closer to being multivariate normal, EB modes get closer and closer to EB means.

Just like there are many methods of assigning values to the random effects, there exist many methods of calculating standard errors of the predicted random effects; see Skrondal and Rabe-Hesketh (2009) for a comprehensive review.

Stata uses the posterior standard deviation as the standard error of the posterior means predictor of random effects. The EB posterior covariance matrix of the random effects is given by

$$\operatorname{cov}(\tilde{\mathbf{u}}_j|\mathbf{y}_j,\mathbf{X}_j,\mathbf{Z}_j;\hat{\boldsymbol{\theta}}) = \int_{\Re^q} (\mathbf{u}_j - \tilde{\mathbf{u}}_j) (\mathbf{u}_j - \tilde{\mathbf{u}}_j)' \, \omega(\mathbf{u}_j|\mathbf{y}_j,\mathbf{X}_j,\mathbf{Z}_j;\hat{\boldsymbol{\theta}}) \, d\mathbf{u}_j$$

The posterior covariance matrix and the integrals are approximated by the mean-variance adaptive Gaussian quadrature; see *Methods and formulas* of [ME] **megIm** for details about the quadrature.

Conditional standard errors for the estimated posterior modes are derived from standard theory of maximum likelihood, which dictates that the asymptotic variance matrix of $\tilde{\tilde{u}}_j$ is the negative inverse of the Hessian, $g''(\beta, \Sigma, \tilde{\tilde{u}}_j)$.

In what follows, we show formulas using the posterior means estimates of random effects $\tilde{\mathbf{u}}_j$, which are used by default or if the means option is specified. If the modes option is specified, $\tilde{\mathbf{u}}_j$ are simply replaced with the posterior modes $\tilde{\mathbf{u}}_j$ in these formulas.

For any *i*th observation in the *j*th cluster in a two-level model, define the linear predictor as

$$\widehat{\eta}_{ij} = \mathbf{x}_{ij}\widehat{\boldsymbol{\beta}} + \mathbf{z}_{ij}\widetilde{\mathbf{u}}_j$$

The linear predictor includes the offset or exposure variable if one was specified during estimation, unless the nooffset option is specified. If the fixedonly option is specified, $\hat{\eta}$ contains the linear predictor for only the fixed portion of the model, $\hat{\eta}_{ij} = \mathbf{x}_{ij}\hat{\boldsymbol{\beta}}$.

The predicted mean, conditional on the random effects $\tilde{\mathbf{u}}_{i}$, is

$$\hat{\mu}_{ij} = g^{-1}(\hat{\eta}_{ij})$$

where $g^{-1}(\cdot)$ is the inverse link function for $\mu_{ij} = g^{-1}(\eta_{ij})$ defined as follows for the available links in link (*link*):

link	Inverse link
identity	η_{ij}
logit	$1/\{1+\exp(-\eta_{ij})\}$
probit	$\Phi(\eta_{ij})$
log	$\exp(\eta_{ij})$
cloglog	$1-\exp\{-\exp(\eta_{ij})\}$

By default, random effects and any statistic based on them—mu, fitted, pearson, deviance, anscombe—are calculated using posterior means of random effects unless option modes is specified, in which case the calculations are based on posterior modes of random effects.

Raw residuals are calculated as the difference between the observed and fitted outcomes,

$$\nu_{ij} = y_{ij} - \hat{\mu}_{ij}$$

and are only defined for the Gaussian family.

Let r_{ij} be the number of Bernoulli trials in a binomial model, α be the conditional overdispersion parameter under the mean parameterization of the negative binomial model, and δ be the conditional overdispersion parameter under the constant parameterization of the negative binomial model. Pearson residuals are raw residuals divided by the square root of the variance function

$$\nu_{ij}^P = \frac{\nu_{ij}}{\{V(\hat{\mu}_{ij})\}^{1/2}}$$

where $V(\hat{\mu}_{ij})$ is the family-specific variance function defined as follows for the available families in family (*family*):

family	Variance function $V(\hat{\mu}_{ij})$
bernoulli	$\hat{\mu}_{ij}(1-\hat{\mu}_{ij})$
binomial	$\hat{\mu}_{ij}(1-\hat{\mu}_{ij}/r_{ij})$
gamma	$\hat{\mu}_{ij}^2$
gaussian	1
nbinomial mean	$\hat{\mu}_{ij}(1+\alpha\hat{\mu}_{ij})$
nbinomial constant	$\hat{\mu}_{ij}(1+\delta)$
ordinal	not defined
poisson	$\hat{\mu}_{ij}$

Deviance residuals are calculated as

$$\nu^D_{ij} = \mathrm{sign}(\nu_{ij}) \sqrt{\hat{d}^2_{ij}}$$

where the squared deviance residual $\hat{d}_{ij}^{\,2}$ is defined as follows:

family	Squared deviance \hat{d}_{ij}^2
bernoulli	$-2\log(1-\hat{\mu}_{ij}) \text{ if } y_{ij}=0$
	$-2\log(\hat{\mu}_{ij}) \qquad \text{if} \ y_{ij} = 1$
binomial	$2r_{ij}\log\left(\frac{r_{ij}}{r_{ij}-\hat{\mu}_{ij}}\right) \text{if} \ y_{ij}=0$
	$2y_{ij} \log \left(\frac{y_{ij}}{\hat{\mu}_{ij}}\right) + 2(r_{ij} - y_{ij}) \log \left(\frac{r_{ij} - y_{ij}}{r_{ij} - \hat{\mu}_{ij}}\right) \text{if } 0 < y_{ij} < r_{ij}$
	$2r_{ij}\log\left(rac{r_{ij}}{\hat{\mu}_{ij}} ight) ext{if } y_{ij} = r_{ij}$
gamma	$-2\left\{\log\left(\frac{y_{ij}}{\widehat{\mu}_{ij}}\right)-\frac{\widehat{\nu}_{ij}}{\widehat{\mu}_{ij}}\right\}$
gaussian	$\hat{ u}_{ij}^2$
nbinomial mean	$2\log\left(1+\alpha\hat{\mu}_{ij}\right)\alpha \text{ if } y_{ij}=0$
	$2y_{ij}\log\left(\frac{y_{ij}}{\hat{\mu}_{ij}}\right) - \tfrac{2}{\alpha}(1 + \alpha y_{ij})\log\left(\frac{1 + \alpha y_{ij}}{1 + \alpha \hat{\mu}_{ij}}\right) \text{otherwise}$
nbinomial constant	not defined
ordinal	not defined
poisson	$2\hat{\mu}_{ij}$ if $y_{ij}=0$
	$2y_{ij}\log\left(rac{y_{ij}}{\widehat{\mu}_{ij}} ight)-2\widehat{ u}_{ij}$ otherwise

Anscombe residuals, denoted ν_{ij}^A , are calculated as follows:

family	Anscombe residual $ u^A_{ij}$
bernoulli	$\frac{3\left\{y_{ij}^{2/3}\mathcal{H}(y_{ij}) - \hat{\mu}_{ij}^{2/3}\mathcal{H}(\hat{\mu}_{ij})\right\}}{2\left(\hat{\mu}_{ij} - \hat{\mu}_{ij}^2\right)^{1/6}}$
binomial	$\frac{3\left\{y_{ij}^{2/3}\mathcal{H}(y_{ij}/r_{ij}) - \hat{\mu}_{ij}^{2/3}\mathcal{H}(\hat{\mu}_{ij}/r_{ij})\right\}}{2\left(\hat{\mu}_{ij} - \hat{\mu}_{ij}^2/r_{ij}\right)^{1/6}}$
gamma	$\frac{3(y_{ij}^{1/3}-\hat{\mu}_{ij}^{1/3})}{\hat{\mu}_{ij}^{1/3}}$
gaussian	$ u_{ij}$
nbinomial mean	$\frac{\mathcal{H}(-\alpha y_{ij})-\mathcal{H}(-\alpha \hat{\mu}_{ij})+1.5(y_{ij}^{2/3}-\hat{\mu}_{ij}^{2/3})}{(\hat{\mu}_{ij}+\alpha \hat{\mu}_{ij}^2)^{1/6}}$
nbinomial constant	not defined
ordinal	not defined
poisson	$\frac{3(y_{ij}^{2/3}-\hat{\mu}_{ij}^{2/3})}{2\hat{\mu}_{ij}^{1/6}}$

where $\mathcal{H}(t)$ is a specific univariate case of the Hypergeometric2F1 function (Wolfram 2003, 780), defined here as $\mathcal{H}(t) = {}_2F_1(2/3, 1/3, 5/3, t)$.

For a discussion of the general properties of the various residuals, see Hardin and Hilbe (2018, chap. 4).

References

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Also see

[ME] meglm — Multilevel mixed-effects generalized linear models

[U] 20 Estimation and postestimation commands

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