fullsvd()	— Full singular value decomposition
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Description

fullsvd(A, U, s, Vt) calculates the singular value decomposition of $m \times n$ matrix A, returning the result in U, s, and Vt. Singular values in s are sorted from largest to smallest.

fullsdiag(s, k) converts column vector s returned by fullsvd() into matrix S. In all cases, the appropriate call for this function is

S = fullsdiag(s, rows(A)-cols(A))

_fullsvd(A, U, s, Vt) does the same as fullsvd(), except that, in the process, it destroys A. Use of _fullsvd() in place of fullsvd() conserves memory.

_svd_la() is the interface to the LAPACK SVD routines and is used in the implementation of the previous functions. There is no reason you should want to use it. _svd_la() is similar to _fullsvd(). It differs in that it returns a real scalar equal to 1 if the numerical routines fail to converge, and it returns 0 otherwise. The previous SVD routines set *s* to contain missing values in this unlikely case.

Syntax

void	<pre>fullsvd(numeric matrix A, U, s, Vt)</pre>
numeric matrix	<pre>fullsdiag(numeric colvector s, real scalar k)</pre>
void	_fullsvd(numeric matrix A, U, s, Vt)
real scalar	_svd_la(numeric matrix A, U, s, Vt)

Remarks and examples

Remarks are presented under the following headings:

Introduction Relationship between the full and thin SVDs The contents of s Possibility of convergence problems

Documented here is the full SVD, appropriate in all cases, but of interest mainly when $A: m \times n, m < n$. There is a thin SVD that conserves memory when $m \ge n$; see [M-5] svd(). The relationship between the two is discussed in *Relationship between the full and thin SVDs* below.

Introduction

The SVD is used to compute accurate solutions to linear systems and least-squares problems, to compute the 2-norm, and to determine the numerical rank of a matrix.

The singular value decomposition (SVD) of $A: m \times n$ is given by

A = USV'

where

U: $m \times m$ and orthogonal (unitary)S: $m \times n$ and diagonalV: $n \times n$ and orthogonal (unitary)

When A is complex, the transpose operator ' is understood to mean the conjugate transpose operator.

Diagonal matrix S contains the singular values and those singular values are real even when A is complex. It is usual (but not required) that S is arranged so that the largest singular value appears first, then the next largest, and so on. The SVD routines documented here do this.

The full SVD routines return U and Vt = V'. S is returned as a column vector s, and S can be obtained by

S = fullsdiag(s, rows(A)-cols(A))

so we will write the SVD as

A = U * fullsdiag(s, rows(A)-cols(A)) * Vt

Function fullsvd(A, U, s, Vt) returns the U, s, and Vt corresponding to A.

Relationship between the full and thin SVDs

A popular variant of the SVD is known as the thin SVD and is suitable for use when $m \ge n$. Both SVDs have the same formula,

$$A = USV'$$

but U and S have reduced dimensions in the thin version:

Matrix	Full SVD	Thin SVD
U:	$m \times m$	$m \times n$
<i>S</i> :	$m \times n$	$n \times n$
V:	$n \times n$	$n \times n$

When m = n, the two variants are identical.

The thin SVD is of use when m > n, because then only the first *n* diagonal elements of *S* are nonzero, and therefore only the first *n* columns of *U* are relevant in A = USV'. There are considerable memory savings to be had in calculating the thin SVD when $m \gg n$.

As a result, many people call the thin SVD the SVD and ignore the full SVD altogether. If the matrices you deal with have $m \ge n$, you will want to do the same. To obtain the thin SVD, see [M-5] svd().

Regardless of the dimension of your matrix, you may wish to obtain only the singular values. In this case, see svdsv() documented in [M-5] svd(). That function is appropriate in all cases.

The contents of s

Given A: $m \times n$, the singular values are returned in s: $\min(m, n) \times 1$.

Let's consider the m = n case first. A is $m \times m$ and the m singular values are returned in s, an $m \times 1$ column vector. If A were 3×3 , perhaps we would get back

: s 1 1 13.47 2 5.8 3 2.63

If we needed it, we could obtain S from s simply by creating a diagonal matrix from s

: S =	= diag(s)		
: S			
[symmetric]			
	1	2	3
1	13.47		
1 2 3	0	5.8	
3	0	0	2.63

although the official way we are supposed to do this is

: S = fullsdiag(s, rows(A)-cols(A))

and that will return the same result.

Now let's consider m < n. Let's pretend that A is 3×4 . The singular values will be returned in 3×1 vector s. For instance, s might still contain

: s	1
1	13.47
2	5.8
3	2.63

The *S* matrix here needs to be 3×4 , and fullsdiag() will form it:

: fullsdiag(s, rows(A)-cols(A))				
	1	2	3	4
1	13.47	0	0	0
2	0	5.8	0	0
3	0	0	2.63	0

The final case is m > n. We will pretend that A is 4×3 . The s vector we get back will look the same

 $\begin{array}{c} : \ s \\ & 1 \\ 1 \\ 2 \\ 3 \\ 2.63 \end{array}$

but this time, we need a 4 \times 3 rather than a 3 \times 4 matrix formed from it.

<pre>fullsdiag(s, rows(A)-cols(A))</pre>			
	1	2	3
	[
1	13.47	0	0
2	0	5.8	0
3	0	0	2.63
4	0	0	0

Possibility of convergence problems

See Possibility of convergence problems in [M-5] svd(); what is said there applies equally here.

Conformability

:

```
fullsvd(A, U, s, Vt):
     input:
                      A:
                               m \times n
     output:
                      U:
                               m \times m
                      s:
                               \min(m, n) \times 1
                     Vt:
                               n \times n
                 result:
                               void
fullsdiag(s, k):
     input:
                      s:
                               r \times 1
                               1 \times 1
                      k:
     output:
                 result:
                               r + k \times r, if k \ge 0
                               r \times r - k, otherwise
_fullsvd(A, U, s, Vt):
     input:
                      A:
                               m \times n
     output:
                      A:
                               0 \times 0
                      U:
                               m \times m
                      s:
                               \min(m, n) \times 1
                     Vt:
                               n \times n
                 result:
                               void
```

```
_svd_la(A, U, s, Vt):

input:

A: m \times n

output:

A: m \times n, but contents changed

U: m \times m

s: \min(m, n) \times 1

Vt: n \times n

result: 1 \times 1
```

Diagnostics

fullsvd(A, U, s, Vt) and _fullsvd(A, s, Vt) return missing results if A contains missing. In all other cases, the routines should work, but there is the unlikely possibility of convergence problems, in which case missing results will also be returned; see *Possibility of convergence problems* in [M-5] svd().

_fullsvd() aborts with error if A is a view.

Direct use of _svd_la() is not recommended.

Also see

- [M-5] **norm()** Matrix and vector norms
- [M-5] **pinv()** Moore–Penrose pseudoinverse
- [M-5] rank() Rank of matrix
- [M-5] svd() Singular value decomposition
- [M-5] svsolve() Solve AX=B for X using singular value decomposition
- [M-4] Matrix Matrix functions

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