

xtintreg — Random-effects interval-data regression models

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Syntax

```
xtintreg depvarlower depvarupper [indepvars] [if] [in] [weight] [, options]
```

<i>options</i>	Description
Model	
<u>noconstant</u>	suppress constant term
<u>offset</u>(<i>varname</i>)	include <i>varname</i> in model with coefficient constrained to 1
<u>constraints</u>(<i>constraints</i>)	apply specified linear constraints
<u>collinear</u>	keep collinear variables
SE	
<u>vce</u>(<i>vcetype</i>)	<i>vcetype</i> may be oim , bootstrap , or jackknife
Reporting	
<u>level</u>(#)	set confidence level; default is level(95)
<u>noskip</u>	perform overall model test as a likelihood-ratio test
<u>intreg</u>	perform likelihood-ratio test against pooled model
<u>nocnsreport</u>	do not display constraints
<u>display_options</u>	control column formats, row spacing, line width, display of omitted variables and base and empty cells, and factor-variable labeling
Integration	
<u>intmethod</u>(<i>intmethod</i>)	integration method; <i>intmethod</i> may be mvaghermite (the default) or ghermite
<u>intpoints</u>(#)	use # quadrature points; default is intpoints(12)
Maximization	
<u>maximize_options</u>	control the maximization process; see [R] maximize
<u>coeflegend</u>	display legend instead of statistics

A panel variable must be specified; use [xtset](#); see [\[XT\] xtset](#).

indepvars may contain factor variables; see [\[U\] 11.4.3 Factor variables](#).

*depvar*_{lower}, *depvar*_{upper}, and *indepvars* may contain time-series operators; see [\[U\] 11.4.4 Time-series varlists](#).

by and *statsby* are allowed; see [\[U\] 11.1.10 Prefix commands](#).

weights are allowed; see [\[U\] 11.1.6 weight](#). Weights must be constant within panel.

[coeflegend](#) does not appear in the dialog box.

See [\[U\] 20 Estimation and postestimation commands](#) for more capabilities of estimation commands.

Menu

Statistics > Longitudinal/panel data > Censored outcomes > Interval regression (RE)

Description

`xtintreg` fits a random-effects regression model whose dependent variable may be measured as point data, interval data, left-censored data, or right-censored data. $depvar_{\text{lower}}$ and $depvar_{\text{upper}}$ represent how the dependent variable was measured.

The values in $depvar_{\text{lower}}$ and $depvar_{\text{upper}}$ should have the following form:

Type of data		$depvar_{\text{lower}}$	$depvar_{\text{upper}}$
point data	$a = [a, a]$	a	a
interval data	$[a, b]$	a	b
left-censored data	$(-\infty, b]$.	b
right-censored data	$[a, +\infty)$	a	.

Options

Model

`noconstant`, `offset(varname)`, `constraints(constraints)`, `collinear`; see [R] [estimation options](#).

SE

`vce(vcetype)` specifies the type of standard error reported, which includes types that are derived from asymptotic theory (`oim`) and that use bootstrap or jackknife methods (`bootstrap`, `jackknife`); see [XT] [vce_options](#).

Reporting

`level(#)`, `noskip`; see [R] [estimation options](#).

`intreg` specifies that a likelihood-ratio test comparing the random-effects model with the pooled (`intreg`) model be included in the output.

`nocnsreport`; see [R] [estimation options](#).

display_options: `noomitted`, `vsquish`, `noemptycells`, `baselevels`, `allbaselevels`, `novlabel`, `fvwrap(#)`, `fvwrapon(style)`, `cformat(%fmt)`, `pformat(%fmt)`, `sformat(%fmt)`, and `no!stretch`; see [R] [estimation options](#).

Integration

`intmethod(intmethod)`, `intpoints(#)`; see [R] [estimation options](#).

Maximization

maximize_options: `difficult`, `technique(algorithm_spec)`, `iterate(#)`, `[no]log`, `trace`, `gradient`, `showstep`, `hessian`, `showtolerance`, `tolerance(#)`, `!tolerance(#)`, `!rtolerance(#)`, `!nontolerance`, and `from(init_specs)`; see [R] [maximize](#). These options are seldom used.

The following option is available with `xtintreg` but is not shown in the dialog box: `coeflegend`; see [R] [estimation options](#).

Remarks and examples

[stata.com](http://www.stata.com)

Consider the linear regression model with panel-level random effects

$$y_{it} = \mathbf{x}_{it}\boldsymbol{\beta} + \nu_i + \epsilon_{it}$$

for $i = 1, \dots, n$ panels, where $t = 1, \dots, n_i$. The random effects, ν_i , are i.i.d., $N(0, \sigma_\nu^2)$, and ϵ_{it} are i.i.d., $N(0, \sigma_\epsilon^2)$ independently of ν_i . The observed data consist of the couples, (y_{1it}, y_{2it}) , such that all that is known is that $y_{1it} \leq y_{it} \leq y_{2it}$, where y_{1it} is possibly $-\infty$ and y_{2it} is possibly $+\infty$.

► Example 1

We begin with the `nlswork` dataset described in [XT] `xt` and create two fictional dependent variables, where the wages are instead reported sometimes as ranges. The wages have been adjusted to 1988 dollars and have further been recoded such that some of the observations are known exactly, some are left-censored, some are right-censored, and some are known only in an interval.

We wish to fit a random-effects interval regression model of adjusted (log) wages:

```
. use http://www.stata-press.com/data/r13/nlswork5
(National Longitudinal Survey. Young Women 14-26 years of age in 1968)
. xtintreg ln_wage1 ln_wage2 union age grade south##c.year occ_code, intreg
(output omitted)
Random-effects interval regression      Number of obs      =      19151
Group variable: idcode                 Number of groups   =      4140
Random effects u_i ~ Gaussian          Obs per group: min =           1
                                       avg   =          4.6
                                       max   =           12
Integration method: mvaghermite        Integration points =           12
Wald chi2(7)                           =      2523.84
Prob > chi2                             =           0.0000
Log likelihood = -23174.355
```

	Coef.	Std. Err.	z	P> z	[95% Conf. Interval]	
union	.1441844	.0094245	15.30	0.000	.1257128	.162656
age	.0104083	.0018804	5.54	0.000	.0067228	.0140939
grade	.0794958	.0023469	33.87	0.000	.074896	.0840955
1.south	-.3778103	.0979415	-3.86	0.000	-.5697722	-.1858485
year	.0013528	.0020176	0.67	0.503	-.0026016	.0053071
south#c.year						
1	.0034385	.0012105	2.84	0.005	.0010659	.005811
occ_code	-.0197912	.0014094	-14.04	0.000	-.0225535	-.0170289
_cons	.3791078	.1136641	3.34	0.001	.1563303	.6018853
/sigma_u	.2987074	.0052697	56.68	0.000	.2883789	.309036
/sigma_e	.3528109	.0030935	114.05	0.000	.3467478	.358874
rho	.4175266	.0102529			.3975474	.4377211

Likelihood-ratio test of `sigma_u=0`: `chibar2(01)= 2516.85 Prob>=chibar2 = 0.000`

```
Observation summary:    4757 left-censored observations
                        4792 uncensored observations
                        4830 right-censored observations
                        4772 interval observations
```

The output includes the overall and panel-level variance components (labeled `sigma_e` and `sigma_u`, respectively) together with ρ (labeled `rho`),

$$\rho = \frac{\sigma_u^2}{\sigma_\epsilon^2 + \sigma_u^2}$$

which is the proportion of the total variance contributed by the panel-level variance component.

When `rho` is zero, the panel-level variance component is unimportant, and the panel estimator is not different from the pooled estimator. A likelihood-ratio test of this is included at the bottom of the output. This test formally compares the pooled estimator (`intreg`) with the panel estimator.

◀

□ Technical note

The random-effects model is calculated using quadrature, which is an approximation whose accuracy depends partially on the number of integration points used. We can use the `quadchk` command to see if changing the number of integration points affects the results. If the results change, the quadrature approximation is not accurate given the number of integration points. Try increasing the number of integration points using the `intpoints()` option and run `quadchk` again. Do not attempt to interpret the results of estimates when the coefficients reported by `quadchk` differ substantially. See [XT] [quadchk](#) for details and [XT] [xtprobit](#) for an [example](#).

Because the `xtintreg` likelihood function is calculated by Gauss–Hermite quadrature, on large problems the computations can be slow. Computation time is roughly proportional to the number of points used for the quadrature.

□

Stored results

xtintreg stores the following in `e()`:

Scalars

<code>e(N)</code>	number of observations
<code>e(N_g)</code>	number of groups
<code>e(N_unc)</code>	number of uncensored observations
<code>e(N_lc)</code>	number of left-censored observations
<code>e(N_rc)</code>	number of right-censored observations
<code>e(N_int)</code>	number of interval observations
<code>e(N_cd)</code>	number of completely determined observations
<code>e(k)</code>	number of parameters
<code>e(k_aux)</code>	number of auxiliary parameters
<code>e(k_eq)</code>	number of equations in <code>e(b)</code>
<code>e(k_eq_model)</code>	number of equations in overall model test
<code>e(k_dv)</code>	number of dependent variables
<code>e(df_m)</code>	model degrees of freedom
<code>e(ll)</code>	log likelihood
<code>e(ll_0)</code>	log likelihood, constant-only model
<code>e(chi2)</code>	χ^2
<code>e(chi2_c)</code>	χ^2 for comparison test
<code>e(rho)</code>	ρ
<code>e(sigma_u)</code>	panel-level standard deviation
<code>e(sigma_e)</code>	standard deviation of ϵ_{it}
<code>e(n_quad)</code>	number of quadrature points
<code>e(g_min)</code>	smallest group size
<code>e(g_avg)</code>	average group size
<code>e(g_max)</code>	largest group size
<code>e(p)</code>	significance
<code>e(rank)</code>	rank of <code>e(V)</code>
<code>e(rank0)</code>	rank of <code>e(V)</code> for constant-only model
<code>e(ic)</code>	number of iterations
<code>e(rc)</code>	return code
<code>e(converged)</code>	1 if converged, 0 otherwise

Macros

<code>e(cmd)</code>	<code>xtintreg</code>
<code>e(cmdline)</code>	command as typed
<code>e(depvar)</code>	names of dependent variables
<code>e(ivar)</code>	variable denoting groups
<code>e(wtype)</code>	weight type
<code>e(wexp)</code>	weight expression
<code>e(title)</code>	title in estimation output
<code>e(offset1)</code>	offset
<code>e(chi2type)</code>	Wald or LR; type of model χ^2 test
<code>e(chi2_ct)</code>	Wald or LR; type of model χ^2 test corresponding to <code>e(chi2_ct)</code>
<code>e(vce)</code>	<code>vcetype</code> specified in <code>vce()</code>
<code>e(vcetype)</code>	title used to label Std. Err.
<code>e(intmethod)</code>	integration method
<code>e(distrib)</code>	Gaussian; the distribution of the random effect
<code>e(opt)</code>	type of optimization
<code>e(which)</code>	max or min; whether optimizer is to perform maximization or minimization
<code>e(ml_method)</code>	type of ml method
<code>e(user)</code>	name of likelihood-evaluator program
<code>e(technique)</code>	maximization technique
<code>e(properties)</code>	<code>b v</code>
<code>e(predict)</code>	program used to implement <code>predict</code>
<code>e(asbalanced)</code>	factor variables <code>fvset</code> as <code>asbalanced</code>
<code>e(asobserved)</code>	factor variables <code>fvset</code> as <code>asobserved</code>

Matrices

<code>e(b)</code>	coefficient vector
<code>e(Cns)</code>	constraints matrix
<code>e(ilog)</code>	iteration log
<code>e(gradient)</code>	gradient vector
<code>e(V)</code>	variance–covariance matrix of the estimators

Functions

<code>e(sample)</code>	marks estimation sample
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Methods and formulas

Assuming a normal distribution, $N(0, \sigma_\nu^2)$, for the random effects ν_i , we have the joint (unconditional of ν_i) density of the observed data for the i th panel

$$f \{ (y_{1i1}, y_{2i1}), \dots, (y_{1in_i}, y_{2in_i}) | \mathbf{x}_{1i}, \dots, \mathbf{x}_{in_i} \} = \int_{-\infty}^{\infty} \frac{e^{-\nu_i^2 / 2\sigma_\nu^2}}{\sqrt{2\pi\sigma_\nu}} \left\{ \prod_{t=1}^{n_i} F(y_{1it}, y_{2it}, \mathbf{x}_{it}\boldsymbol{\beta} + \nu_i) \right\} d\nu_i$$

where

$$F(y_{1it}, y_{2it}, \Delta_{it}) = \begin{cases} (\sqrt{2\pi}\sigma_\epsilon)^{-1} e^{-(y_{1it}-\Delta_{it})^2/(2\sigma_\epsilon^2)} & \text{if } (y_{1it}, y_{2it}) \in C \\ \Phi\left(\frac{y_{2it}-\Delta_{it}}{\sigma_\epsilon}\right) & \text{if } (y_{1it}, y_{2it}) \in L \\ 1 - \Phi\left(\frac{y_{1it}-\Delta_{it}}{\sigma_\epsilon}\right) & \text{if } (y_{1it}, y_{2it}) \in R \\ \Phi\left(\frac{y_{2it}-\Delta_{it}}{\sigma_\epsilon}\right) - \Phi\left(\frac{y_{1it}-\Delta_{it}}{\sigma_\epsilon}\right) & \text{if } (y_{1it}, y_{2it}) \in I \end{cases}$$

where C is the set of noncensored observations ($y_{1it} = y_{2it}$ and both nonmissing), L is the set of left-censored observations (y_{1it} missing and y_{2it} nonmissing), R is the set of right-censored observations (y_{1it} nonmissing and y_{2it} missing), I is the set of interval observations ($y_{1it} < y_{2it}$ and both nonmissing), and $\Phi(\cdot)$ is the cumulative normal distribution.

The panel-level likelihood l_i is given by

$$\begin{aligned} l_i &= \int_{-\infty}^{\infty} \frac{e^{-\nu_i^2/2\sigma_\nu^2}}{\sqrt{2\pi}\sigma_\nu} \left\{ \prod_{t=1}^{n_i} F(y_{1it}, y_{2it}, \mathbf{x}_{it}\boldsymbol{\beta} + \nu_i) \right\} d\nu_i \\ &\equiv \int_{-\infty}^{\infty} g(y_{1it}, y_{2it}, x_{it}, \nu_i) d\nu_i \end{aligned}$$

This integral can be approximated with M -point Gauss–Hermite quadrature

$$\int_{-\infty}^{\infty} e^{-x^2} h(x) dx \approx \sum_{m=1}^M w_m^* h(a_m^*)$$

This is equivalent to

$$\int_{-\infty}^{\infty} f(x) dx \approx \sum_{m=1}^M w_m^* \exp\{(a_m^*)^2\} f(a_m^*)$$

where the w_m^* denote the quadrature weights and the a_m^* denote the quadrature abscissas. The log likelihood, L , is the sum of the logs of the panel-level likelihoods l_i .

The default approximation of the log likelihood is by adaptive Gauss–Hermite quadrature, which approximates the panel-level likelihood with

$$l_i \approx \sqrt{2\hat{\sigma}_i} \sum_{m=1}^M w_m^* \exp\{(a_m^*)^2\} g(y_{1it}, y_{2it}, x_{it}, \sqrt{2\hat{\sigma}_i} a_m^* + \hat{\mu}_i)$$

where $\hat{\sigma}_i$ and $\hat{\mu}_i$ are the adaptive parameters for panel i . Therefore, using the definition of $g(y_{1it}, y_{2it}, x_{it}, \nu_i)$, the total log likelihood is approximated by

$$L \approx \sum_{i=1}^n w_i \log \left[\sqrt{2\hat{\sigma}_i} \sum_{m=1}^M w_m^* \exp\{(a_m^*)^2\} \frac{\exp\{-(\sqrt{2\hat{\sigma}_i}a_m^* + \hat{\mu}_i)^2/2\sigma_\nu^2\}}{\sqrt{2\pi}\sigma_\nu} \prod_{t=1}^{n_i} F(y_{1it}, y_{2it}, x_{it}\beta + \sqrt{2\hat{\sigma}_i}a_m^* + \hat{\mu}_i) \right]$$

where w_i is the user-specified weight for panel i ; if no weights are specified, $w_i = 1$.

The default method of adaptive Gauss–Hermite quadrature is to calculate the posterior mean and variance and use those parameters for $\hat{\mu}_i$ and $\hat{\sigma}_i$ by following the method of [Naylor and Smith \(1982\)](#), further discussed in [Skrondal and Rabe-Hesketh \(2004\)](#). We start with $\hat{\sigma}_{i,0} = 1$ and $\hat{\mu}_{i,0} = 0$, and the posterior means and variances are updated in the k th iteration. That is, at the k th iteration of the optimization for l_i we use

$$l_{i,k} \approx \sum_{m=1}^M \sqrt{2\hat{\sigma}_{i,k-1}} w_m^* \exp\{(a_m^*)^2\} g(y_{1it}, y_{2it}, x_{it}, \sqrt{2\hat{\sigma}_{i,k-1}}a_m^* + \hat{\mu}_{i,k-1})$$

Letting

$$\tau_{i,m,k-1} = \sqrt{2\hat{\sigma}_{i,k-1}}a_m^* + \hat{\mu}_{i,k-1}$$

$$\hat{\mu}_{i,k} = \sum_{m=1}^M (\tau_{i,m,k-1}) \frac{\sqrt{2\hat{\sigma}_{i,k-1}} w_m^* \exp\{(a_m^*)^2\} g(y_{1it}, y_{2it}, x_{it}, \tau_{i,m,k-1})}{l_{i,k}}$$

and

$$\hat{\sigma}_{i,k} = \sum_{m=1}^M (\tau_{i,m,k-1})^2 \frac{\sqrt{2\hat{\sigma}_{i,k-1}} w_m^* \exp\{(a_m^*)^2\} g(y_{1it}, y_{2it}, x_{it}, \tau_{i,m,k-1})}{l_{i,k}} - (\hat{\mu}_{i,k})^2$$

and this is repeated until $\hat{\mu}_{i,k}$ and $\hat{\sigma}_{i,k}$ have converged for this iteration of the maximization algorithm. This adaptation is applied on every iteration until the log-likelihood change from the preceding iteration is less than a relative difference of $1e-6$; after this, the quadrature parameters are fixed.

The log likelihood can also be calculated by nonadaptive Gauss–Hermite quadrature, the `int-method(ghermite)` option:

$$\begin{aligned} L &= \sum_{i=1}^n w_i \log f \{(y_{1i1}, y_{2i1}), \dots, (y_{1in_i}, y_{2in_i}) | \mathbf{x}_{1i}, \dots, \mathbf{x}_{in_i}\} \\ &\approx \sum_{i=1}^n w_i \log \left\{ \frac{1}{\sqrt{\pi}} \sum_{m=1}^M w_m^* \prod_{t=1}^{n_i} F(y_{1it}, y_{2it}, \mathbf{x}_{it}\beta + \sqrt{2}\sigma_\nu a_m^*) \right\} \end{aligned}$$

Both quadrature formulas require that the integrated function be well approximated by a polynomial of degree equal to the number of quadrature points. The number of periods (panel size) can affect whether

$$\prod_{t=1}^{n_i} F(y_{1it}, y_{2it}, \mathbf{x}_{it}\beta + \nu_i)$$

is well approximated by a polynomial. As panel size and ρ increase, the quadrature approximation can become less accurate. For large ρ , the random-effects model can also become unidentified. Adaptive quadrature gives better results for correlated data and large panels than nonadaptive quadrature; however, we recommend that you use the `quadchk` command (see [XT] [quadchk](#)) to verify the quadrature approximation used in this command, whichever approximation you choose.

References

- Naylor, J. C., and A. F. M. Smith. 1982. Applications of a method for the efficient computation of posterior distributions. *Journal of the Royal Statistical Society, Series C* 31: 214–225.
- Neuhaus, J. M. 1992. Statistical methods for longitudinal and clustered designs with binary responses. *Statistical Methods in Medical Research* 1: 249–273.
- Pendergast, J. F., S. J. Gange, M. A. Newton, M. J. Lindstrom, M. Palta, and M. R. Fisher. 1996. A survey of methods for analyzing clustered binary response data. *International Statistical Review* 64: 89–118.
- Skrondal, A., and S. Rabe-Hesketh. 2004. *Generalized Latent Variable Modeling: Multilevel, Longitudinal, and Structural Equation Models*. Boca Raton, FL: Chapman & Hall/CRC.

Also see

- [XT] [xtintreg postestimation](#) — Postestimation tools for `xtintreg`
- [XT] [quadchk](#) — Check sensitivity of quadrature approximation
- [XT] [xtreg](#) — Fixed-, between-, and random-effects and population-averaged linear models
- [XT] [xtset](#) — Declare data to be panel data
- [XT] [xttobit](#) — Random-effects tobit models
- [R] [intreg](#) — Interval regression
- [R] [tobit](#) — Tobit regression
- [U] [20 Estimation and postestimation commands](#)