Title

psdensity — Parametric spectral density estimation after arima, arfima, and ucm

Syntax	Menu	Description	Options
Remarks and examples	Methods and formulas	References	Also see

## Syntax

psdensity [type] newvar<sub>sd</sub> newvar<sub>f</sub> [if] [in] [, options]

where  $newvar_{sd}$  is the name of the new variable that will contain the estimated spectral density and  $newvar_f$  is the name of the new variable that will contain the frequencies at which the spectral density estimate is computed.

options	Description
pspectrum	estimate the power spectrum rather than the spectral density
range(a b)	limit the frequency range to $[a, b)$
<pre>cycle(#)</pre>	estimate the spectral density from the specified stochastic cycle; only allowed after ucm
<u>smem</u> ory	estimate the spectral density of the short-memory component of the ARFIMA process; only allowed after arfima

## Menu

Statistics > Time series > Postestimation > Parametric spectral density

## Description

psdensity estimates the spectral density of a stationary process using the parameters of a previously estimated parametric model.

psdensity works after arfima, arima, and ucm.

# Options

- pspectrum causes psdensity to estimate the power spectrum rather than the spectral density. The power spectrum is equal to the spectral density times the variance of the process.
- range(a b) limits the frequency range. By default, the spectral density is computed over  $[0, \pi)$ . Specifying range(a b) causes the spectral density to be computed over [a, b). We require that  $0 \le a < b < \pi$ .
- cycle(#) causes psdensity to estimate the spectral density from the specified stochastic cycle after ucm. By default, the spectral density from the first stochastic cycle is estimated. cycle(#) must specify an integer that corresponds to a cycle in the model fit by ucm.
- smemory causes psdensity to ignore the ARFIMA fractional integration parameter. The spectral density computed is for the short-memory ARMA component of the model.

## **Remarks and examples**

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Remarks are presented under the following headings:

The frequency-domain approach to time series Some ARMA examples

### The frequency-domain approach to time series

A stationary process can be decomposed into random components that occur at the frequencies  $\omega \in [0, \pi]$ . The spectral density of a stationary process describes the relative importance of these random components. psdensity uses the estimated parameters of a parametric model to estimate the spectral density of a stationary process.

We need some concepts from the frequency-domain approach to time-series analysis to interpret estimated spectral densities. Here we provide a simple, intuitive explanation. More technical presentations can be found in Priestley (1981), Harvey (1989, 1993), Hamilton (1994), Fuller (1996), and Wei (2006).

In the time domain, the dependent variable evolves over time because of random shocks. The autocovariances  $\gamma_j$ ,  $j \in \{0, 1, ..., \infty\}$ , of a covariance-stationary process  $y_t$  specify its variance and dependence structure, and the autocorrelations  $\rho_j$ ,  $j \in \{1, 2, ..., \infty\}$ , provide a scale-free measure of its dependence structure. The autocorrelation at lag j specifies whether realizations at time t and realizations at time t - j are positively related, unrelated, or negatively related.

In the frequency domain, the dependent variable is generated by an infinite number of random components that occur at the frequencies  $\omega \in [0, \pi]$ . The spectral density specifies the relative importance of these random components. The area under the spectral density in the interval  $(\omega, \omega + d\omega)$  is the fraction of the variance of the process than can be attributed to the random components that occur at the frequencies in the interval  $(\omega, \omega + d\omega)$ .

The spectral density and the autocorrelations provide the same information about the dependence structure, albeit in different domains. The spectral density can be written as a weighted average of the autocorrelations of  $y_t$ , and it can be inverted to retrieve the autocorrelations as a function of the spectral density.

Like autocorrelations, the spectral density is normalized by  $\gamma_0$ , the variance of  $y_t$ . Multiplying the spectral density by  $\gamma_0$  yields the power spectrum of  $y_t$ , which changes with the units of  $y_t$ .

A peak in the spectral density around frequency  $\omega$  implies that the random components around  $\omega$  make an important contribution to the variance of  $y_t$ .

A random variable primarily generated by low-frequency components will tend to have more runs above or below its mean than an independent and identically distributed (i.i.d.) random variable, and its plot may look smoother than the plot of the i.i.d. variable. A random variable primarily generated by high-frequency components will tend to have fewer runs above or below its mean than an i.i.d. random variable, and its plot may look more jagged than the plot of the i.i.d. variable.

#### Technical note

A more formal specification of the spectral density allows us to be more specific about how the spectral density specifies the relative importance of the random components.

If  $y_t$  is a covariance-stationary process with absolutely summable autocovariances, its spectrum is given by

$$g_y(\omega) = \frac{1}{2\pi}\gamma_0 + \frac{1}{\pi}\sum_{k=1}^{\infty}\gamma_k\cos(\omega k)$$
(1)

where  $g_y(\omega)$  is the spectrum of  $y_t$  at frequency  $\omega$  and  $\gamma_k$  is the kth autocovariance of  $y_t$ . Taking the inverse Fourier transform of each side of (1) yields

$$\gamma_k = \int_{-\pi}^{\pi} g_y(\omega) e^{i\omega k} d\omega \tag{2}$$

where *i* is the imaginary number  $i = \sqrt{-1}$ .

Evaluating (2) at k = 0 yields

$$\gamma_0 = \int_{-\pi}^{\pi} g_y(\omega) d\omega$$

which means that the variance of  $y_t$  can be decomposed in terms of the spectrum  $g_y(\omega)$ . In particular,  $g_y(\omega)d\omega$  is the contribution to the variance of  $y_t$  attributable to the random components in the interval  $(\omega, \omega + d\omega)$ .

The spectrum depends on the units in which  $y_t$  is measured, because it depends on the  $\gamma_0$ . Dividing both sides of (1) by  $\gamma_0$  gives us the scale-free spectral density of  $y_t$ :

$$f_y(\omega) = \frac{1}{2\pi} + \frac{1}{\pi} \sum_{k=1}^{\infty} \rho_k \cos(\omega k)$$

By construction,

$$\int_{-\pi}^{\pi} f_y(\omega) d\omega = 1$$

so  $f_y(\omega)d\omega$  is the fraction of the variance of  $y_t$  attributable to the random components in the interval  $(\omega, \omega + d\omega)$ .

#### Some ARMA examples

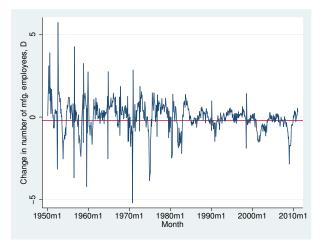
In this section, we estimate and interpret the spectral densities implied by the estimated ARMA parameters. The examples illustrate some of the essential relationships between covariance-stationary processes, the parameters of ARMA models, and the spectral densities implied by the ARMA-model parameters.

See [TS] ucm for a discussion of unobserved-components models and the stochastic-cycle model derived by Harvey (1989) for stationary processes. The stochastic-cycle model has a different parameterization of the spectral density, and it tends to produce spectral densities that look more like probability densities than ARMA models. See *Remarks and examples* in [TS] ucm for an introduction to these models, some examples, and some comparisons between the stochastic-cycle model and ARMA models.

#### Example 1

Let's consider the changes in the number of manufacturing employees in the United States, which we plot below.

```
. use http://www.stata-press.com/data/r13/manemp2
(FRED data: Number of manufacturing employees in U.S.)
. tsline D.manemp, yline(-0.206)
```



We added a horizontal line at the sample mean of -0.0206 to highlight that there appear to be more runs above or below the mean than we would expect in data generated by an i.i.d. process.

As a first pass at modeling this dependence, we use arima to estimate the parameters of a first-order autoregressive (AR(1)) model. Formally, the AR(1) model is given by

$$y_t = \alpha y_{t-1} + \epsilon_t$$

where  $y_t$  is the dependent variable,  $\alpha$  is the autoregressive coefficient, and  $\epsilon_t$  is an i.i.d. error term. See [TS] **arima** for an introduction to ARMA modeling and the **arima** command.

. arima D.manemp, ar(1) noconstant								
(setting optimization to BHHH)								
Iteration 0:	0	pod = -870.6						
Iteration 1:								
Iteration 2:								
	log likeliho							
Iteration 4:								
(switching opt								
Iteration 5: log likelihood = -870.64786								
Iteration 6: log likelihood = -870.64786								
ARIMA regression								
Sample: 1950r	n2 - 2011m2			Number	of obs	= 733		
•			Wald ch	i2(1)	= 730.51			
Log likelihood	d = -870.6479			Prob >	chi2	= 0.0000		
		OPG						
D.manemp	Coef.	Std. Err.	z	P> z	[95% Conf	. Interval]		
ARMA								
ar								
L1.	.5179561	.0191638	27.03	0.000	.4803959	.5555164		
/sigma	.7934554	.0080636	98.40	0.000	.777651	.8092598		
	*							

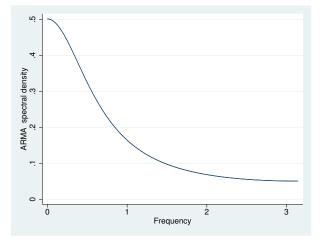
Note: The test of the variance against zero is one sided, and the two-sided confidence interval is truncated at zero.

The statistically significant estimate of 0.518 for the autoregressive coefficient indicates that there is an important amount of positive autocorrelation in this series.

The spectral density of a covariance-stationary process is symmetric around 0. Following convention, psdensity estimates the spectral density over the interval  $[0, \pi)$  at the points given in *Methods and formulas*.

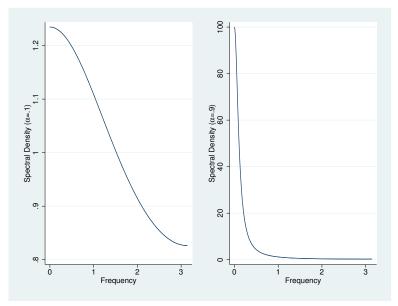
Now we use psdensity to estimate the spectral density of the process implied by the estimated ARMA parameters. We specify the names of two new variables in the call to psdensity. The first new variable will contain the estimated spectral density. The second new variable will contain the frequencies at which the spectral density is estimated.

- . psdensity psden1 omega
- . line psden1 omega



The above graph is typical of a spectral density of an AR(1) process with a positive coefficient. The curve is highest at frequency 0, and it tapers off toward zero or a positive asymptote. The estimated spectral density is telling us that the low-frequency random components are the most important random components of an AR(1) process with a positive autoregressive coefficient.

The closer the  $\alpha$  is to 1, the more important are the low-frequency components relative to the high-frequency components. To illustrate this point, we plot the spectral densities implied by AR(1) models with  $\alpha = 0.1$  and  $\alpha = 0.9$ .



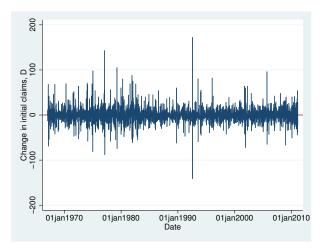
As  $\alpha$  gets closer to 1, the plot of the spectral density gets closer to being a spike at frequency 0, implying that only the lowest-frequency components are important.

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## Example 2

Now let's consider a dataset for which the estimated coefficient from an AR(1) model is negative. Below we plot the changes in initial claims for unemployment insurance in the United States.

- . use http://www.stata-press.com/data/r13/icsa1, clear
- . tsline D.icsa, yline(0.08)



The plot looks a little more jagged than we would expect from an i.i.d. process, but it is hard to tell. Below we estimate the AR(1) coefficient.

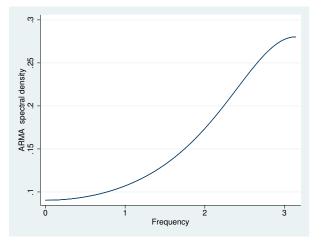
2302
666.06
0.0000
interval]
.2546722
18.34048
•

Note: The test of the variance against zero is one sided, and the two-sided confidence interval is truncated at zero.

The estimated coefficient is negative and statistically significant.

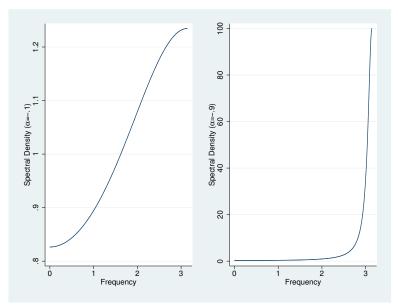
The spectral density implied by the estimated parameters is

- . psdensity psden2 omega2
- . line psden2 omega2



The above graph is typical of a spectral density of an AR(1) process with a negative coefficient. The curve is lowest at frequency 0, and it monotonically increases to its highest point, which occurs when the frequency is  $\pi$ .

When the coefficient of an AR(1) model is negative, the high-frequency random components are the most important random components of the process. The closer the  $\alpha$  is to -1, the more important are the high-frequency components relative to the low-frequency components. To illustrate this point, we plot the spectral densities implied by AR(1) models with  $\alpha = -0.1$ , and  $\alpha = -0.9$ .



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As  $\alpha$  gets closer to -1, the plot of the spectral density shifts toward becoming a spike at frequency  $\pi$ , implying that only the highest-frequency components are important.

For examples of psdensity after arfima and ucm, see [TS] arfima and [TS] ucm.

## Methods and formulas

Methods and formulas are presented under the following headings:

Introduction Spectral density after arima or arfima Spectral density after ucm

### Introduction

The spectral density  $f(\omega)$  is estimated at the values  $\omega \in \{\omega_1, \omega_2, \ldots, \omega_N\}$  using one of the formulas given below. Given a sample of size N, after accounting for any if or in restrictions, the N values of  $\omega$  are given by  $\omega_i = \pi(i-1)/(N-1)$  for  $i \in \{1, 2, \ldots, N\}$ .

In the rare case in which the dataset in memory has insufficient observations for the desired resolution of the estimated spectral density, you may use tsappend or set obs (see [TS] tsappend or [D] obs) to increase the number of observations in the current dataset.

You may use an if restriction or an in restriction to restrict the observations to handle panel data or to compute the estimates for a subset of the observations.

#### Spectral density after arima or arfima

Let  $\phi_k$  and  $\theta_k$  denote the *p* autoregressive and *q* moving-average parameters of an ARMA model, respectively. Box, Jenkins, and Reinsel (2008) show that the spectral density implied by the ARMA parameters is

$$f_{\text{ARMA}}(\omega; \boldsymbol{\phi}, \boldsymbol{\theta}, \sigma_{\epsilon}^{2}, \gamma_{0}) = \frac{\sigma_{\epsilon}^{2}}{2\pi\gamma_{0}} \frac{\left|1 + \theta_{1}e^{-i\omega} + \theta_{2}e^{-i2\omega} + \dots + \theta_{q}e^{-iq\omega}\right|^{2}}{\left|1 - \phi_{1}e^{-i\omega} - \phi_{2}e^{-i2\omega} - \dots - \phi_{p}e^{-ip\omega}\right|^{2}}$$

where  $\omega \in [0, \pi]$  and  $\sigma_{\epsilon}^2$  is the variance of the idiosyncratic error and  $\gamma_0$  is the variance of the dependent variable. We estimate  $\gamma_0$  using the arima parameter estimates.

The spectral density for the ARFIMA model is

$$f_{\text{ARFIMA}}(\omega; \boldsymbol{\phi}, \boldsymbol{\theta}, d, \sigma_{\epsilon}^2, \gamma_0) = |1 - e^{i\omega}|^{-2d} f_{\text{ARMA}}(\omega; \boldsymbol{\phi}, \boldsymbol{\theta}, \sigma_{\epsilon}^2)$$

where d, -1/2 < d < 1/2, is the fractional integration parameter. The spectral density goes to infinity as the frequency approaches 0 for 0 < d < 1/2, and it is zero at frequency 0 for -1/2 < d < 0.

The smemory option causes psdensity to perform the estimation with d = 0, which is equivalent to estimating the spectral density of the fractionally differenced series.

The power spectrum omits scaling by  $\gamma_0$ .

#### Spectral density after ucm

The spectral density of an order-k stochastic cycle with frequency  $\lambda$  and damping  $\rho$  is (Trimbur 2006)

$$\begin{split} f(\omega;\rho,\lambda,\sigma_{\kappa}^2) = & \left\{ \frac{(1-\rho^2)^{2k-1}}{\sigma_{\kappa}^2 \sum_{i=0}^{k-1} {\binom{k-1}{i}}^2 \rho^{2i}} \right\} \quad \times \\ & \frac{\sum_{j=0}^k \sum_{i=0}^k (-1)^{j+i} {\binom{k}{j}} {\binom{k}{i}} \rho^{j+i} \cos \lambda (j-i) \cos \omega (j-i)}{2\pi \left\{ 1+4\rho^2 \cos^2 \lambda + \rho^4 - 4\rho (1+\rho^2) \cos \lambda \cos \omega + 2\rho^2 \cos 2\omega \right\}^k} \end{split}$$

where  $\sigma_{\kappa}^2$  is the variance of the cycle error term.

The variance of the cycle is

$$\sigma_{\omega}^{2} = \sigma_{\kappa}^{2} \frac{\sum_{i=0}^{k-1} {\binom{k-1}{i}}^{2} \rho^{2i}}{(1-\rho^{2})^{2k-1}}$$

and the power spectrum omits scaling by  $\sigma_{\omega}^2$ .

## References

- Box, G. E. P., G. M. Jenkins, and G. C. Reinsel. 2008. Time Series Analysis: Forecasting and Control. 4th ed. Hoboken, NJ: Wiley.
- Fuller, W. A. 1996. Introduction to Statistical Time Series. 2nd ed. New York: Wiley.

Hamilton, J. D. 1994. Time Series Analysis. Princeton: Princeton University Press.

- Harvey, A. C. 1989. Forecasting, Structural Time Series Models and the Kalman Filter. Cambridge: Cambridge University Press.
- -----. 1993. Time Series Models. 2nd ed. Cambridge, MA: MIT Press.

Priestley, M. B. 1981. Spectral Analysis and Time Series. London: Academic Press.

Trimbur, T. M. 2006. Properties of higher order stochastic cycles. Journal of Time Series Analysis 27: 1-17.

Wei, W. W. S. 2006. Time Series Analysis: Univariate and Multivariate Methods. 2nd ed. Boston: Pearson.

### Also see

- [TS] arfima Autoregressive fractionally integrated moving-average models
- [TS] arima ARIMA, ARMAX, and other dynamic regression models
- [TS] ucm Unobserved-components model