**mgarch dcc — Dynamic conditional correlation multivariate GARCH models**

### Syntax

```stata
mgarch dcc eq [eq ... eq] [if] [in] [, options]
```

where each `eq` has the form

```
(depvars = [indepvars] [, eqoptions])
```

<table>
<thead>
<tr>
<th><code>options</code></th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Model</strong></td>
<td></td>
</tr>
<tr>
<td><code>arch(numlist)</code></td>
<td>ARCH terms for all equations</td>
</tr>
<tr>
<td><code>garch(numlist)</code></td>
<td>GARCH terms for all equations</td>
</tr>
<tr>
<td><code>het(varlist)</code></td>
<td>include <code>varlist</code> in the specification of the conditional variance for all equations</td>
</tr>
<tr>
<td><code>distribution(dist [#])</code></td>
<td>use <code>dist</code> distribution for errors [may be <code>gaussian</code> (synonym <code>normal</code>) or <code>t</code>; default is <code>gaussian</code>]</td>
</tr>
<tr>
<td><code>constraints(numlist)</code></td>
<td>apply linear constraints</td>
</tr>
<tr>
<td><strong>SE/Robust</strong></td>
<td></td>
</tr>
<tr>
<td><code>vce(vcetype)</code></td>
<td><code>vcetype</code> may be <code>oim</code> or <code>robust</code></td>
</tr>
<tr>
<td><strong>Reporting</strong></td>
<td></td>
</tr>
<tr>
<td><code>level(#)</code></td>
<td>set confidence level; default is <code>level(95)</code></td>
</tr>
<tr>
<td><code>noconsreport</code></td>
<td>do not display constraints</td>
</tr>
<tr>
<td><code>display_options</code></td>
<td>control column formats, row spacing, line width, display of omitted variables and base and empty cells, and factor-variable labeling</td>
</tr>
<tr>
<td><strong>Maximization</strong></td>
<td></td>
</tr>
<tr>
<td><code>maximize_options</code></td>
<td>control the maximization process; seldom used</td>
</tr>
<tr>
<td><code>from(matname)</code></td>
<td>initial values for the coefficients; seldom used</td>
</tr>
<tr>
<td><code>coeflegend</code></td>
<td>display legend instead of statistics</td>
</tr>
</tbody>
</table>
**Description**

*mgarch dcc* estimates the parameters of dynamic conditional correlation (DCC) multivariate generalized autoregressive conditionally heteroskedastic (MGARCH) models in which the conditional variances are modeled as univariate generalized autoregressive conditionally heteroskedastic (GARCH) models and the conditional covariances are modeled as nonlinear functions of the conditional variances. The conditional quasicorrelation parameters that weight the nonlinear combinations of the conditional variances follow the GARCH-like process specified in Engle (2002).

The DCC MGARCH model is about as flexible as the closely related varying conditional correlation MGARCH model (see [TS] *mgarch vcc*), more flexible than the conditional correlation MGARCH model (see [TS] *mgarch ccc*), and more parsimonious than the diagonal vech MGARCH model (see [TS] *mgarch dvech*).

**Options**

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>noconstant</strong></td>
<td>suppress constant term in the mean equation</td>
</tr>
<tr>
<td><strong>arch(numlist)</strong></td>
<td>ARCH terms</td>
</tr>
<tr>
<td><strong>garch(numlist)</strong></td>
<td>GARCH terms</td>
</tr>
<tr>
<td><strong>het(varlist)</strong></td>
<td>include varlist in the specification of the conditional variance</td>
</tr>
</tbody>
</table>

You must *tsset* your data before using *mgarch dcc*; see [TS] *tsset*.  
*indepvars* and *varlist* may contain factor variables; see [U] 11.4.3 Factor variables.  
*depmvars*, *indepvars*, and *varlist* may contain time-series operators; see [U] 11.4.4 Time-series varlists.  
by, *fp*, rolling, and *statsby* are allowed; see [U] 11.1.10 Prefix commands.  
*coeflegend* does not appear in the dialog box.  
See [U] 20 Estimation and postestimation commands for more capabilities of estimation commands.

**Menu**

Statistics > Multivariate time series > Multivariate GARCH


t causes mgarch dcc to assume that the errors follow a multivariate Student t distribution, and the degree-of-freedom parameter is estimated along with the other parameters of the model. If distribution(t #) is specified, then mgarch dcc uses a multivariate Student t distribution with # degrees of freedom. # must be greater than 2.

constraints(numlist) specifies linear constraints to apply to the parameter estimates.

vce(vcetype) specifies the estimator for the variance–covariance matrix of the estimator.

vce(oim), the default, specifies to use the observed information matrix (OIM) estimator.

vce(robust) specifies to use the Huber/White/sandwich estimator.

level(#) specifies linear constraints to apply to the parameter estimates.

nocnsreport; see [R] estimation options.

display_options: noomitted, vsquish, noemptycells, baselevels, allbaselevels, nofvlabel, fvwrap(#), fvwrapon(style), cformat(%fmt), pformat(%fmt), sformat(%fmt), and nolstretch; see [R] estimation options.

maximize_options: difficult, technique(algorithm_spec), iterate(#), [no]log, trace, gradient, showstep, hessian, showtolerance, tolerance(#), ltolerance(#), nrtolerance(#), nonrtolerance, and from(matname); see [R] maximize for all options except from(), and see below for information on from(). These options are seldom used.

from(matname) specifies initial values for the coefficients. from(b0) causes mgarch dcc to begin the optimization algorithm with the values in b0. b0 must be a row vector, and the number of columns must equal the number of parameters in the model.

The following option is available with mgarch dcc but is not shown in the dialog box:

coeflegend; see [R] estimation options.

Eqoptions

noconstant suppresses the constant term in the mean equation.

arch(numlist) specifies the ARCH terms in the equation. By default, no ARCH terms are specified. This option may not be specified with model-level arch().

garch(numlist) specifies the GARCH terms in the equation. By default, no GARCH terms are specified. This option may not be specified with model-level garch().

het(varlist) specifies that varlist be included in the specification of the conditional variance. This varlist enters the variance specification collectively as multiplicative heteroskedasticity. This option may not be specified with model-level het().

Remarks and examples

We assume that you have already read [TS] mgarch, which provides an introduction to MGARCH models and the methods implemented in mgarch dcc.
MGARCH models are dynamic multivariate regression models in which the conditional variances and covariances of the errors follow an autoregressive-moving-average structure. The DCC MGARCH model uses a nonlinear combination of univariate GARCH models with time-varying cross-equation weights to model the conditional covariance matrix of the errors.

As discussed in [TS] mgarch, MGARCH models differ in the parsimony and flexibility of their specifications for a time-varying conditional covariance matrix of the disturbances, denoted by $H_t$. In the conditional correlation family of MGARCH models, the diagonal elements of $H_t$ are modeled as univariate GARCH models, whereas the off-diagonal elements are modeled as nonlinear functions of the diagonal terms. In the DCC MGARCH model,

$$h_{ij,t} = \rho_{ij,t} \sqrt{h_{ii,t} h_{jj,t}}$$

where the diagonal elements $h_{ii,t}$ and $h_{jj,t}$ follow univariate GARCH processes and $\rho_{ij,t}$ follows the dynamic process specified in Engle (2002) and discussed below.

Because the $\rho_{ij,t}$ varies with time, this model is known as the DCC GARCH model.

**Technical note**

The DCC GARCH model proposed by Engle (2002) can be written as

$$y_t = Cx_t + \epsilon_t$$

$$\epsilon_t = H_t^{1/2} \nu_t$$

$$H_t = D_t^{1/2} R_t D_t^{1/2}$$

$$R_t = \text{diag}(Q_t)^{-1/2} Q_t \text{diag}(Q_t)^{-1/2}$$

$$Q_t = (1 - \lambda_1 - \lambda_2)R + \lambda_1 \bar{\epsilon}_{t-1} \bar{\epsilon}_{t-1} + \lambda_2 Q_{t-1}$$

where

- $y_t$ is an $m \times 1$ vector of dependent variables;
- $C$ is an $m \times k$ matrix of parameters;
- $x_t$ is a $k \times 1$ vector of independent variables, which may contain lags of $y_t$;
- $H_t^{1/2}$ is the Cholesky factor of the time-varying conditional covariance matrix $H_t$;
- $\nu_t$ is an $m \times 1$ vector of normal, independent, and identically distributed innovations;
- $D_t$ is a diagonal matrix of conditional variances,

$$D_t = \begin{pmatrix}
\sigma_{1,t}^2 & 0 & \cdots & 0 \\
0 & \sigma_{2,t}^2 & \cdots & 0 \\
\vdots & \vdots & \ddots & \vdots \\
0 & 0 & \cdots & \sigma_{m,t}^2
\end{pmatrix}$$

in which each $\sigma_{i,t}^2$ evolves according to a univariate GARCH model of the form

$$\sigma_{i,t}^2 = s_i + \sum_{j=1}^{p_i} \alpha_j \epsilon_{i,t-j}^2 + \sum_{j=1}^{q_i} \beta_j \sigma_{i,t-j}^2$$

by default, or

$$\sigma_{i,t}^2 = \exp(\gamma_i z_{i,t}) + \sum_{j=1}^{p_i} \alpha_j \epsilon_{i,t-j}^2 + \sum_{j=1}^{q_i} \beta_j \sigma_{i,t-j}^2$$
when the het() option is specified, where $\gamma_t$ is a $1 \times p$ vector of parameters, $z_t$ is a $p \times 1$ vector of independent variables including a constant term, the $\alpha_j$’s are ARCH parameters, and the $\beta_j$’s are GARCH parameters;

$R_t$ is a matrix of conditional quasicorrelations,

$$
R_t = \begin{pmatrix}
1 & \rho_{12,t} & \cdots & \rho_{1m,t} \\
\rho_{12,t} & 1 & \cdots & \rho_{2m,t} \\
\vdots & \vdots & \ddots & \vdots \\
\rho_{1m,t} & \rho_{2m,t} & \cdots & 1
\end{pmatrix}
$$

$\tilde{\epsilon}_t$ is an $m \times 1$ vector of standardized residuals, $D_t^{-1/2}\epsilon_t$; and

$\lambda_1$ and $\lambda_2$ are parameters that govern the dynamics of conditional quasicorrelations. $\lambda_1$ and $\lambda_2$ are nonnegative and satisfy $0 \leq \lambda_1 + \lambda_2 < 1$.

When $Q_t$ is stationary, the $R$ matrix in (1) is a weighted average of the unconditional covariance matrix of the standardized residuals $\tilde{\epsilon}_t$, denoted by $\overline{R}$, and the unconditional mean of $Q_t$, denoted by $\overline{Q}$. Because $\overline{R} \neq \overline{Q}$, as shown by Aielli (2009), $R$ is neither the unconditional correlation matrix nor the unconditional mean of $Q_t$. For this reason, the parameters in $R$ are known as quasicorrelations; see Aielli (2009) and Engle (2009) for discussions.

Some examples

**Example 1: Model with common covariates**

We have daily data on the stock returns of three car manufacturers—Toyota, Nissan, and Honda, from January 2, 2003, to December 31, 2010—in the variables toyota, nissan and honda. We model the conditional means of the returns as a first-order vector autoregressive process and the conditional covariances as a DCC MGARCH process in which the variance of each disturbance term follows a GARCH(1,1) process.
. use http://www.stata-press.com/data/r13/stocks
(Data from Yahoo! Finance)
. mgarch dcc (toyota nissan honda = L.toyota L.nissan L.honda, noconstant),
> arch(1) garch(1)
Calculating starting values....
Optimizing log likelihood
(setting technique to bhhh)
Iteration 0:  log likelihood =  16902.44
Iteration 1:  log likelihood =  17005.45
Iteration 2:  log likelihood =  17157.96
Iteration 3:  log likelihood =  17267.36
Iteration 4:  log likelihood =  17318.29
Iteration 5:  log likelihood =  17353.03
Iteration 6:  log likelihood =  17369.12
Iteration 7:  log likelihood =  17388.07
Iteration 8:  log likelihood =  17401.28
Iteration 9:  log likelihood =  17435.60
(switching technique to nr)
Iteration 10: log likelihood = 17451.74
Iteration 11: log likelihood = 17474.65
Iteration 12: log likelihood = 17481.99
Iteration 13: log likelihood = 17484.83
Iteration 14: log likelihood = 17484.95
Iteration 15: log likelihood = 17484.95
Refining estimates
Iteration 0:  log likelihood =  17484.95
Iteration 1:  log likelihood =  17484.95
Dynamic conditional correlation MGARCH model
Sample: 1 - 2015    Number of obs  =  2014
Distribution: Gaussian  Wald chi2(9)  =  19.54
Log likelihood = 17484.95  Prob > chi2  =  0.0210

|                | Coef.     | Std. Err. |     z    |   P>|z|   | [95% Conf. Interval] |
|----------------|-----------|-----------|----------|--------|----------------------|
| toyota         |           |           |          |        |                      |
| toyota         |           |           |          |        |                      |
| L1             | -.0510866 | .0339824  | -1.50    | 0.133  | -.117691 .0155177    |
| nissan         |           |           |          |        |                      |
| L1             | .0297834  | .0247455  | 1.20     | 0.229  | -.0187169 .0782837   |
| honda          |           |           |          |        |                      |
| L1             | -.0162826 | .0300323  | -0.54    | 0.588  | -.0751449 .0425797   |
| ARCH_toyota    |           |           |          |        |                      |
| arch           |           |           |          |        |                      |
| L1             | .0608223  | .0086686  | 7.02     | 0.000  | .0438321 .0778124    |
| garch          |           |           |          |        |                      |
| L1             | .9222207  | .0111053  | 83.04    | 0.000  | .9004547 .9439868    |
| _cons          | 4.47e-06  | 1.15e-06  | 3.90     | 0.000  | 2.22e-06 6.72e-06    |
The iteration log has three parts: the dots from the search for initial values, the iteration log from optimizing the log likelihood, and the iteration log from the refining step. A detailed discussion of the optimization methods is in *Methods and formulas*.

The header describes the estimation sample and reports a Wald test against the null hypothesis that all the coefficients on the independent variables in the mean equations are zero. Here the null hypothesis is rejected at the 5% level.

The output table first presents results for the mean or variance parameters used to model each dependent variable. Subsequently, the output table presents results for the conditional quasicorrelations.

<p>| | | | | | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>nissan</td>
<td>toyota</td>
<td>L1.</td>
<td>-.005672</td>
<td>.0389348</td>
<td>-0.15</td>
<td>0.884</td>
</tr>
<tr>
<td>nissan</td>
<td>L1.</td>
<td></td>
<td>-.0287095</td>
<td>.0309379</td>
<td>-0.93</td>
<td>0.353</td>
</tr>
<tr>
<td>honda</td>
<td>L1.</td>
<td></td>
<td>.0154979</td>
<td>.0358802</td>
<td>0.43</td>
<td>0.666</td>
</tr>
<tr>
<td>ARCH_nissan</td>
<td>arch</td>
<td>L1.</td>
<td>.084424</td>
<td>.0128192</td>
<td>6.59</td>
<td>0.000</td>
</tr>
<tr>
<td></td>
<td>garch</td>
<td>L1.</td>
<td>.8994206</td>
<td>.0151125</td>
<td>59.52</td>
<td>0.000</td>
</tr>
<tr>
<td></td>
<td>_cons</td>
<td></td>
<td>7.21e-06</td>
<td>1.93e-06</td>
<td>3.74</td>
<td>0.000</td>
</tr>
<tr>
<td>honda</td>
<td>toyota</td>
<td>L1.</td>
<td>-.027242</td>
<td>.0361819</td>
<td>-0.75</td>
<td>0.451</td>
</tr>
<tr>
<td>nissan</td>
<td>L1.</td>
<td></td>
<td>.0617495</td>
<td>.0271378</td>
<td>2.28</td>
<td>0.023</td>
</tr>
<tr>
<td>honda</td>
<td>L1.</td>
<td></td>
<td>-.063507</td>
<td>.0332918</td>
<td>-1.91</td>
<td>0.056</td>
</tr>
<tr>
<td>ARCH_honda</td>
<td>arch</td>
<td>L1.</td>
<td>.0490135</td>
<td>.0073695</td>
<td>6.65</td>
<td>0.000</td>
</tr>
<tr>
<td></td>
<td>garch</td>
<td>L1.</td>
<td>.9331126</td>
<td>.0103685</td>
<td>90.00</td>
<td>0.000</td>
</tr>
<tr>
<td></td>
<td>_cons</td>
<td></td>
<td>5.35e-06</td>
<td>1.35e-06</td>
<td>3.95</td>
<td>0.000</td>
</tr>
<tr>
<td>corr(toyota, nissan)</td>
<td></td>
<td></td>
<td>.6689543</td>
<td>.0168021</td>
<td>39.81</td>
<td>0.000</td>
</tr>
<tr>
<td>corr(toyota, honda)</td>
<td></td>
<td></td>
<td>.7259625</td>
<td>.0140156</td>
<td>51.80</td>
<td>0.000</td>
</tr>
<tr>
<td>corr(nissan, honda)</td>
<td></td>
<td></td>
<td>.6335659</td>
<td>.0180412</td>
<td>35.12</td>
<td>0.000</td>
</tr>
<tr>
<td>Adjustment</td>
<td>lambda1</td>
<td></td>
<td>.0315274</td>
<td>.0088386</td>
<td>3.57</td>
<td>0.000</td>
</tr>
<tr>
<td></td>
<td>lambda2</td>
<td></td>
<td>.8704193</td>
<td>.0613329</td>
<td>14.19</td>
<td>0.000</td>
</tr>
</tbody>
</table>


For example, the conditional quasicorrelation between the standardized residuals for Toyota and Nissan is estimated to be 0.67. Finally, the output table presents results for the adjustment parameters $\lambda_1$ and $\lambda_2$. In the example at hand, the estimates for both $\lambda_1$ and $\lambda_2$ are statistically significant.

The DCC MGARCH model reduces to the CCC MGARCH model when $\lambda_1 = \lambda_2 = 0$. The output below shows that a Wald test rejects the null hypothesis that $\lambda_1 = \lambda_2 = 0$ at all conventional levels.

```
. test _b[Adjustment:lambda1] = _b[Adjustment:lambda2] = 0
   ( 1) [Adjustment]lambda1 - [Adjustment]lambda2 = 0
   ( 2) [Adjustment]lambda1 = 0
   chi2( 2) = 1102.45
   Prob > chi2 =  0.0000
```

These results indicate that the assumption of time-invariant conditional correlations maintained in the CCC MGARCH model is too restrictive for these data.

Example 2: Model with covariates that differ by equation

We improve the previous example by removing the insignificant parameters from the model. To remove these parameters, we specify the honda equation separately from the toyota and nissan equations:

```
. mgarch dcc (toyota nissan = , noconstant) (honda = L.nissan, noconstant),
   > arch(1) garch(1)
```

Calculating starting values....

Optimizing log likelihood

(setting technique to bhhh)
Iteration 0:  log likelihood =  16884.502
Iteration 1:  log likelihood =  16970.755
Iteration 2:  log likelihood =  17140.318
Iteration 3:  log likelihood =  17237.807
Iteration 4:  log likelihood =  17306.120
Iteration 5:  log likelihood =  17342.533
Iteration 6:  log likelihood =  17363.511
Iteration 7:  log likelihood =  17392.501
Iteration 8:  log likelihood =  17407.242
Iteration 9:  log likelihood =  17448.702
(switching technique to nr)
Iteration 10: log likelihood =  17472.199
Iteration 11: log likelihood =  17475.842
Iteration 12: log likelihood =  17476.345
Iteration 13: log likelihood =  17476.350
Iteration 14: log likelihood =  17476.350

Refining estimates
Iteration 0:  log likelihood =  17476.350
Iteration 1:  log likelihood =  17476.350
Dynamic conditional correlation MGARCH model

|                           | Coef.  | Std. Err. |    z  |   P>|z| | [95% Conf. Interval] |
|---------------------------|--------|-----------|------|-------|----------------------|
| **ARCH_toyota**           |        |           |      |       |                      |
| arch L1.                  | 0.0608 | 0.0086    | 7.02 | 0.000 | 0.0438 - 0.0778      |
| garch L1.                 | 0.9219 | 0.0111    | 83.01| 0.000 | 0.9002 - 0.9437      |
| _cons                     | 0.49e-06 | 1.14e-06 | 3.95 | 0.000 | 2.27e-06 - 6.72e-06  |
| **ARCH_nissan**           |        |           |      |       |                      |
| arch L1.                  | 0.0876 | 0.0130    | 6.73 | 0.000 | 0.0621 - 0.1131      |
| garch L1.                 | 0.8951 | 0.0153    | 58.54| 0.000 | 0.8651 - 0.9251      |
| _cons                     | 0.79e-06 | 1.99e-06 | 3.86 | 0.000 | 0.37e-06 - 0.0001    |
| **honda**                 |        |           |      |       |                      |
| nissan L1.                | 0.0199 | 0.0134    | 1.49 | 0.137 | -0.0064 - 0.0463     |
| **ARCH_honda**            |        |           |      |       |                      |
| arch L1.                  | 0.0489 | 0.0074    | 6.63 | 0.000 | 0.0344 - 0.0633      |
| garch L1.                 | 0.9330 | 0.0104    | 89.76| 0.000 | 0.9126 - 0.9534      |
| _cons                     | 0.52e-06 | 1.36e-06 | 3.98 | 0.000 | 2.75e-06 - 8.08e-06  |
| **corr(toyota, nissan)**  |        |           |      |       |                      |
| corr(toyota, nissan)      | 0.6668 | 0.0163    | 40.86| 0.000 | 0.6349 - 0.6988      |
| corr(toyota, honda)       | 0.7258 | 0.0137    | 52.95| 0.000 | 0.6989 - 0.7527      |
| corr(nissan, honda)       | 0.6313 | 0.0175    | 35.98| 0.000 | 0.5969 - 0.6657      |
| **Adjustment**            |        |           |      |       |                      |
| lambda1                   | 0.0324 | 0.0074    | 4.38 | 0.000 | 0.0179 - 0.0469      |
| lambda2                   | 0.8574 | 0.0477    | 18.00| 0.000 | 0.7641 - 0.9508      |

It turns out that the coefficient on L1.nissan in the honda equation is now statistically insignificant. We could further improve the model by removing L1.nissan from the model.

There is no mean equation for Toyota or Nissan. In [TS] mgarch dcc postestimation, we discuss prediction from models without covariates.
Example 3: Model with constraints

Here we fit a bivariate DCC MGARCH model for the Toyota and Nissan shares. We believe that the shares of these car manufacturers follow the same process, so we impose the constraints that the ARCH coefficients are the same for the two companies and that the GARCH coefficients are also the same.

. constraint 1 _b[ARCH_toyota:L.arch] = _b[ARCH_nissan:L.arch]
. constraint 2 _b[ARCH_toyota:L.garch] = _b[ARCH_nissan:L.garch]
. mgarch dcc (toyota nissan = , noconstant), arch(1) garch(1) constraints(1 2)

Calculating starting values....
Optimizing log likelihood
(setting technique to bhhh)
Iteration 0: log likelihood = 10307.609
Iteration 1: log likelihood = 10656.153
Iteration 2: log likelihood = 10862.137
Iteration 3: log likelihood = 10987.457
Iteration 4: log likelihood = 11062.347
Iteration 5: log likelihood = 11135.207
Iteration 6: log likelihood = 11245.619
Iteration 7: log likelihood = 11253.56
Iteration 8: log likelihood = 11294
Iteration 9: log likelihood = 11296.364
(switching technique to nr)
Iteration 10: log likelihood = 11296.76
Iteration 11: log likelihood = 11297.087
Iteration 12: log likelihood = 11297.091
Iteration 13: log likelihood = 11297.091

Refining estimates
Iteration 0: log likelihood = 11297.091
Iteration 1: log likelihood = 11297.091
Dynamic conditional correlation MGARCH model

Sample: 1 - 2015  
Number of obs = 2015  
Distribution: Gaussian  
Wald chi2(.) = 
Log likelihood = 11297.09  
Prob > chi2 = 

( 1) \[ARCH_{toyota}\]L.arch - \[ARCH_{nissan}\]L.arch = 0  
( 2) \[ARCH_{toyota}\]L.garch - \[ARCH_{nissan}\]L.garch = 0

|          | Coef.  | Std. Err. | z     | P>|z| | [95% Conf. Interval] |
|----------|--------|-----------|-------|-----|----------------------|
| ARCH_{toyota} |       |           |       |     |                      |
| arch L1.  | .080889| .0103227  | 7.84  | 0.000 | .060657 -.1011211    |
| garch L1. | .9060711| .0119107 | 76.07 | 0.000 | .8827267 -.9294156   |
| _cons    | 4.21e-06| 1.10e-06 | 3.83  | 0.000 | 2.05e-06 .636e-06    |
| ARCH_{nissan} |      |           |       |     |                      |
| arch L1.  | .080889| .0103227  | 7.84  | 0.000 | .060657 -.1011211    |
| garch L1. | .9060711| .0119107 | 76.07 | 0.000 | .8827267 -.9294156   |
| _cons    | 5.92e-06| 1.47e-06 | 4.03  | 0.000 | 3.04e-06 .880e-06    |
| corr(toyota, nissan) | .6646283 | .0187793 | 35.39 | 0.000 | .6278215 .7014351    |

| Adjustment | Coef.  | Std. Err. | z     | P>|z| | [95% Conf. Interval] |
|-----------|--------|-----------|-------|-----|----------------------|
| lambda1   | .0446559| .0123017  | 3.63  | 0.000 | .020545 .0687668     |
| lambda2   | .8686054| .0510885 | 17.00 | 0.000 | .7684739 .968737     |

We could test our constraints by fitting the unconstrained model and performing a likelihood-ratio test. The results indicate that the restricted model is preferable.

Example 4: Model with a GARCH term

In this example, we have data on fictional stock returns for the Acme and Anvil corporations, and we believe that the movement of the two stocks is governed by different processes. We specify one ARCH and one GARCH term for the conditional variance equation for Acme and two ARCH terms for the conditional variance equation for Anvil. In addition, we include the lagged value of the stock return for Apex, the main subsidiary of Anvil corporation, in the variance equation of Anvil. For Acme, we have data on the changes in an index of futures prices of products related to those produced by Acme in a related. For Anvil, we have data on the changes in an index of futures prices of inputs used by Anvil in a inputs.
The results indicate that increases in the futures prices for related products lead to higher returns on the Acme stock, and increased input prices lead to lower returns on the Anvil stock. In the conditional variance equation for Anvil, the coefficient on L1.apex is positive and significant, which indicates
that an increase in the return on the Apex stock leads to more variability in the return on the Anvil stock.

**Stored results**

`mgarch dcc` stores the following in `e()`:

Scalars

- `e(N)`: number of observations
- `e(k)`: number of parameters
- `e(k_aux)`: number of auxiliary parameters
- `e(k_extra)`: number of extra estimates added to `_b`
- `e(k_eq)`: number of equations in `e(b)`
- `e(k_dv)`: number of dependent variables
- `e(df_m)`: model degrees of freedom
- `e(ll)`: log likelihood
- `e(chi2)`: \( \chi^2 \)
- `e(p)`: significance
- `e(estdf)`: 1 if distribution parameter was estimated, 0 otherwise
- `e(userr)`: user-provided distribution parameter
- `e(tmin)`: minimum time in sample
- `e(tmax)`: maximum time in sample
- `e(N_gaps)`: number of gaps
- `e(rank)`: rank of `e(V)`
- `e(ic)`: number of iterations
- `e(rc)`: return code
- `e(converged)`: 1 if converged, 0 otherwise

Macros

- `e(cmd)`: `mgarch`
- `e(model)`: `dcc`
- `e(cmdline)`: command as typed
- `e(depvar)`: names of dependent variables
- `e(covariates)`: list of covariates
- `e(dv_eqs)`: dependent variables with mean equations
- `e(indeps)`: independent variables in each equation
- `e(tvar)`: time variable
- `e(title)`: title in estimation output
- `e(chi2type)`: Wald; type of model \( \chi^2 \) test
- `e(vcetype)`: `vcetype` specified in `vce()`
- `e(vce)`
- `e(tmins)`: formatted minimum time
- `e(tmaxs)`: formatted maximum time
- `e(dist)`: distribution for error term: `gaussian` or `t`
- `e(arch)`: specified ARCH terms
- `e(garch)`: specified GARCH terms
- `e(technique)`: maximization technique
- `e(properties)`: `b V`
- `e(estat_cmd)`: program used to implement `estat`
- `e(predict)`: program used to implement `predict`
- `e(marginsok)`: predictions allowed by `margins`
- `e(marginsnotok)`: predictions disallowed by `margins`

Matrices

- `e(b)`: coefficient vector
- `e(Cns)`: constraints matrix
- `e(ilog)`: iteration log (up to 20 iterations)
- `e(gradient)`: gradient vector
- `e(hessian)`: Hessian matrix
- `e(V)`: variance–covariance matrix of the estimators
- `e(pinfo)`: parameter information, used by `predict`

Functions

- `e(sample)`: marks estimation sample
### Methods and formulas

**mgarch dcc** estimates the parameters of the DCC MGARCH model by maximum likelihood. The log-likelihood function based on the multivariate normal distribution for observation $t$ is

$$
l_t = -0.5m \log(2\pi) - 0.5 \log \{ \det (R_t) \} - \log \left\{ \det \left( D_t^{1/2} \right) \right\} - 0.5 \tilde{\epsilon}_t R_t^{-1} \tilde{\epsilon}_t'
$$

where $\tilde{\epsilon}_t = D_t^{-1/2} \epsilon_t$ is an $m \times 1$ vector of standardized residuals, $\epsilon_t = y_t - Cx_t$. The log-likelihood function is $\sum_{t=1}^{T} l_t$.

If we assume that $\nu_t$ follow a multivariate $t$ distribution with degrees of freedom (df) greater than 2, then the log-likelihood function for observation $t$ is

$$
l_t = \log \Gamma \left( \frac{df + m}{2} \right) - \log \Gamma \left( \frac{df}{2} \right) - \frac{m}{2} \log \left\{ (df - 2)\pi \right\} - 0.5 \log \{ \det (R_t) \} - \log \left\{ \det \left( D_t^{1/2} \right) \right\} - \frac{df + m}{2} \log \left( 1 + \frac{\tilde{\epsilon}_t R_t^{-1} \tilde{\epsilon}_t'}{df - 2} \right)
$$

The starting values for the parameters in the mean equations and the initial residuals $\hat{\epsilon}_t$ are obtained by least-squares regression. The starting values for the parameters in the variance equations are obtained by a procedure proposed by Gourieroux and Monfort (1997, sec. 6.2.2). The starting values for the quasicorrelation parameters are calculated from the standardized residuals $\tilde{\epsilon}_t$. Given the starting values for the mean and variance equations, the starting values for the parameters $\lambda_1$ and $\lambda_2$ are obtained from a grid search performed on the log likelihood.

The initial optimization step is performed in the unconstrained space. Once the maximum is found, we impose the constraints $\lambda_1 \geq 0$, $\lambda_2 \geq 0$, and $0 \leq \lambda_1 + \lambda_2 < 1$, and maximize the log likelihood in the constrained space. This step is reported in the iteration log as the refining step.

GARCH estimators require initial values that can be plugged in for $\epsilon_{t-i} \epsilon_{t-i}'$ and $H_{t-j}$ when $t-i < 1$ and $t-j < 1$. **mgarch dcc** substitutes an estimator of the unconditional covariance of the disturbances

$$
\hat{\Sigma} = T^{-1} \sum_{t=1}^{T} \tilde{\epsilon}_t \tilde{\epsilon}_t'
$$

for $\epsilon_{t-i} \epsilon_{t-i}'$ when $t-i < 1$ and for $H_{t-j}$ when $t-j < 1$, where $\tilde{\epsilon}_t$ is the vector of residuals calculated using the estimated parameters.

**mgarch dcc** uses numerical derivatives in maximizing the log-likelihood function.

### References


**Also see**

[TS] mgarch dcc postestimation — Postestimation tools for mgarch dcc

[TS] mgarch — Multivariate GARCH models

[TS] tsset — Declare data to be time-series data

[TS] arch — Autoregressive conditional heteroskedasticity (ARCH) family of estimators

[TS] var — Vector autoregressive models

[U] 20 Estimation and postestimation commands