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Remarks and exam Also see	ipies Stored results	Methods and formulas	References
ntax			
<pre>rotate [, options]</pre>	]		
<u>rot</u> ate, clear			
options	Description		
-	Description		
-		rotations; the default, exca	ept with promax()
 1ain			ept with promax()
lain orthogonal	restrict to orthogonal		ept with promax()
Aain orthogonal oblique	restrict to orthogonal allow oblique rotation	ns	ept with promax()
Aain orthogonal oblique rotation_methods	restrict to orthogonal allow oblique rotation rotation criterion rotate Kaiser normali	ns	
Main orthogonal oblique rotation_methods normalize	restrict to orthogonal allow oblique rotation rotation criterion rotate Kaiser normali	ns zed matrix mponents; default is to rot	
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Main <u>orthogonal</u> <u>oblique</u> <u>rotation_methods</u> <u>normalize</u> <u>factors(#)</u> <u>components(#)</u>	restrict to orthogonal allow oblique rotation rotation criterion rotate Kaiser normali rotate # factors or co synonym for factor	ns zed matrix mponents; default is to rot	ate all
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#### 2 rotate — Orthogonal and oblique rotations after factor and pca

rotation_methods	Description
* <u>v</u> arimax	varimax (orthogonal only); the default
vgpf	varimax via the GPF algorithm (orthogonal only)
quartimax	quartimax (orthogonal only)
equamax	equamax (orthogonal only)
parsimax	parsimax (orthogonal only)
entropy	minimum entropy (orthogonal only)
tandem1	Comrey's tandem 1 principle (orthogonal only)
tandem2	Comrey's tandem 2 principle (orthogonal only)
$*\underline{p}$ romax[(#)]	<pre>promax power # (implies oblique); default is promax(3)</pre>
<u>oblimi</u> n (#)	oblimin with $\gamma = \#$ ; default is oblimin(0)
cf(#)	Crawford–Ferguson family with $\kappa = \#, 0 \le \# \le 1$
<u>ben</u> tler	Bentler's invariant pattern simplicity
<u>oblima</u> x	oblimax
quartimin	quartimin
$\underline{\texttt{target}(Tg)}$	rotate toward matrix Tg
partial( $Tg W$ )	rotate toward matrix $Tg$ , weighted by matrix $W$

varimax and promax ignore all optimize\_options.

## Menu

Statistics > Multivariate analysis > Factor and principal component analysis > Postestimation > Rotate loadings

## Description

rotate performs a rotation of the loading matrix after factor, factormat, pca, or pcamat; see [MV] factor and [MV] pca. Many rotation criteria (such as varimax and oblimin) are available that can be applied with respect to the orthogonal and/or oblique class of rotations. rotate stores in e() object of the estimation command in fields  $e(r_name)$ . For instance,  $e(r_L)$  will contain the rotated loadings.

rotate, clear removes the rotation results from the estimation results.

If you want to rotate a given matrix, see [MV] rotatemat. Actually, rotate is implemented using rotatemat.

If you want a Procrustes rotation, which rotates variables optimally toward other variables, see [MV] **procrustes**.

# Options

#### Main 🗋

orthogonal specifies that an orthogonal rotation be applied. This is the default.

See Rotation criteria below for details on the rotation\_methods available with orthogonal.

oblique specifies that an oblique rotation be applied. This often yields more interpretable factors with a simpler structure than that obtained with an orthogonal rotation. In many applications (for example, after factor and pca) the factors before rotation are orthogonal (uncorrelated), whereas the oblique rotated factors are correlated.

See Rotation criteria below for details on the rotation\_methods available with oblique.

clear specifies that rotation results be cleared (removed) from the last estimation command. clear may not be combined with any other option.

rotate stores its results within the e() results of pca and factor, overwriting any previous rotation results. Postestimation commands such as predict operate on the last rotated results, if any, instead of the unrotated results, and allow you to specify norotated to use the unrotated results. The clear option of rotate allows you to remove the rotation results from e(), thus freeing you from having to specify norotated for the postestimation commands.

- normalize requests that the rotation be applied to the Kaiser normalization (Horst 1965) of the matrix **A**, so that the rowwise sums of squares equal 1. Kaiser normalization applies to the rotated columns only (see the factors() option below).
- factors(#), and synonym components(#), specifies the number of factors or components (columns of the loading matrix) to be rotated, counted "from the left", that is, with the lowest column index. The other columns are left unrotated. All columns are rotated by default.

Reporting

blanks(#) shows blanks for loadings with absolute values smaller than #.

detail displays the rotatemat output; seldom used.

format(% fmt) specifies the display format for matrices. The default is format(%9.5f).

noloading suppresses the display of the rotated loadings.

norotation suppresses the display of the optimal rotation matrix.

Optimization

optimize\_options are seldom used; see [MV] rotatemat.

### **Rotation criteria**

In the descriptions below, the matrix to be rotated is denoted as  $\mathbf{A}$ , p denotes the number of rows of  $\mathbf{A}$ , and f denotes the number of columns of  $\mathbf{A}$  (factors or components). If  $\mathbf{A}$  is a loading matrix from factor or pca, p is the number of variables, and f is the number of factors or components.

#### Criteria suitable only for orthogonal rotations

- varimax and vgpf apply the orthogonal varimax rotation (Kaiser 1958). varimax maximizes the variance of the squared loadings within factors (columns of A). It is equivalent to cf(1/p) and to oblimin(1). varimax, the most popular rotation, is implemented with a dedicated fast algorithm and ignores all optimize\_options. Specify vgpf to switch to the general GPF algorithm used for the other criteria.
- quartimax uses the quartimax criterion (Harman 1976). quartimax maximizes the variance of the squared loadings within the variables (rows of A). For orthogonal rotations, quartimax is equivalent to cf(0) and to oblimax.

- equamax specifies the orthogonal equamax rotation. equamax maximizes a weighted sum of the varimax and quartimax criteria, reflecting a concern for simple structure within variables (rows of A) as well as within factors (columns of A). equamax is equivalent to oblimin(p/2) and cf(#), where # = f/(2p).
- parsimax specifies the orthogonal parsimax rotation. parsimax is equivalent to cf(#), where # = (f 1)/(p + f 2).

entropy applies the minimum entropy rotation criterion (Jennrich 2004).

- tandem1 specifies that the first principle of Comrey's tandem be applied. According to Comrey (1967), this principle should be used to judge which "small" factors should be dropped.
- tandem2 specifies that the second principle of Comrey's tandem be applied. According to Comrey (1967), tandem2 should be used for "polishing".

#### Criteria suitable only for oblique rotations

promax [(#)] specifies the oblique promax rotation. The optional argument specifies the promax power. Not specifying the argument is equivalent to specifying promax(3). Values smaller than 4 are recommended, but the choice is yours. Larger promax powers simplify the loadings (generate numbers closer to zero and one) but at the cost of additional correlation between factors. Choosing a value is a matter of trial and error, but most sources find values in excess of 4 undesirable in practice. The power must be greater than 1 but is not restricted to integers.

Promax rotation is an oblique rotation method that was developed before the "analytical methods" (based on criterion optimization) became computationally feasible. Promax rotation comprises an oblique Procrustean rotation of the original loadings A toward the elementwise #-power of the orthogonal varimax rotation of A.

#### Criteria suitable for orthogonal and oblique rotations

oblimin  $\lfloor (\#) \rfloor$  specifies that the oblimin criterion with  $\gamma = \#$  be used. When restricted to orthogonal transformations, the oblimin() family is equivalent to the orthomax criterion function. Special cases of oblimin() include

$\gamma$	Special case
0	quartimax / quartimin
1/2	biquartimax / biquartimin
1	varimax / covarimin
p/2	equamax
p = n	umber of rows of <b>A</b> .

 $\gamma$  defaults to zero. Jennrich (1979) recommends  $\gamma \leq 0$  for oblique rotations. For  $\gamma > 0$ , it is possible that optimal oblique rotations do not exist; the iterative procedure used to compute the solution will wander off to a degenerate solution.

cf (#) specifies that a criterion from the Crawford-Ferguson (1970) family be used with  $\kappa = #$ . cf ( $\kappa$ ) can be seen as  $(1 - \kappa)cf_1(\mathbf{A}) + (\kappa)cf_2(\mathbf{A})$ , where cf<sub>1</sub>( $\mathbf{A}$ ) is a measure of row parsimony and cf<sub>2</sub>( $\mathbf{A}$ ) is a measure of column parsimony. cf<sub>1</sub>( $\mathbf{A}$ ) attains its greatest lower bound when no row of  $\mathbf{A}$  has more than one nonzero element, whereas cf<sub>2</sub>( $\mathbf{A}$ ) reaches zero if no column of  $\mathbf{A}$  has more than one nonzero element. For orthogonal rotations, the Crawford-Ferguson family is equivalent to the oblimin() family. For orthogonal rotations, special cases include the following:

$\kappa$	Special case
0	quartimax / quartimin
1/p	varimax / covarimin
f/(2p)	equamax
(f-1)/(p+f-2)	parsimax
1	factor parsimony
p = number of rows of	of A.
f = number of column	ns of $\mathbf{A}$ .

bentler specifies that the "invariant pattern simplicity" criterion (Bentler 1977) be used.

- oblimax specifies the oblimax criterion. oblimax maximizes the number of high and low loadings. oblimax is equivalent to quartimax for orthogonal rotations.
- quartimin specifies that the quartimin criterion be used. For orthogonal rotations, quartimin is equivalent to quartimax.
- target( $T_g$ ) specifies that A be rotated as near as possible to the conformable matrix  $T_g$ . Nearness is expressed by the Frobenius matrix norm.
- partial (Tg W) specifies that A be rotated as near as possible to the conformable matrix Tg. Nearness is expressed by a weighted (by W) Frobenius matrix norm. W should be nonnegative and usually is zero-one valued, with ones identifying the target values to be reproduced as closely as possible by the factor loadings, whereas zeros identify loadings to remain unrestricted.

# **Remarks and examples**

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Remarks are presented under the following headings:

Orthogonal rotations Oblique rotations Other types of rotation

In this entry, we focus primarily on the rotation of factor loading matrices in factor analysis. rotate may also be used after pca, with the same syntax. We advise caution in the interpretation of rotated loadings in principal component analysis because some of the optimality properties of principal components are not preserved under rotation. See [MV] pca postestimation for more discussion of this point.

## **Orthogonal rotations**

The interpretation of a factor analytical solution is not always easy—an understatement, many will agree. This is due partly to the standard way in which the inherent indeterminacy of factor analysis is resolved. Orthogonal transformations of the common factors and the associated factor loadings are possible without affecting the reconstructed (fitted) correlation matrix and preserving the property that common factors are uncorrelated. This gives considerable freedom in selecting an orthogonal rotation to facilitate the interpretation of the factor loadings. Thurstone (1935) offered criteria for a "simple structure" required for a psychologically meaningful factor solution. These informal criteria for interpretation were then formalized into formal rotation criteria, for example, Harman (1976) and Gorsuch (1983).

## Example 1: Orthogonal varimax rotation

We illustrate rotate by using a factor analysis of the correlation matrix of eight physical variables (height, arm span, length of forearm, length of lower leg, weight, bitrochanteric diameter, chest girth, and chest width) of 305 girls.

	matrix	input	R =	(1000	846	805	859	473	398	301	382 \
>		-		846	1000	881	826	376	326	277	415 \
>				805	881	1000	801	380	319	237	345 \
>				859	826	801	1000	436	329	327	365 \
>				473	376	380	436	1000	762	730	629 \
>				398	326	319	329	762	1000	583	577 \
>				301	277	237	327	730	583	1000	539 \
>				382	415	345	365	629	577	539	1000)
	matrix	R = R,	/100	C							
>	matrix	colnar	nes l		ight ight	arm_s bitro	-	fore_ ch_g		lower ch_w:	0
>	matrix	rownam	nes l		ight ight	arm_s bitro	-	fore_ ch_g	-	lower ch_w:	- 0
		<b>D</b> 1			1 / 9/7	26)					

. matlist R, border format(%7.3f)

	height	arm_s~n	fore_~m	lower~g	weight	bitrod	ch_gi~h	ch_wi~h
height arm_span fore_arm lower_leg weight bitrod	1.000 0.846 0.805 0.859 0.473 0.398 0.301	1.000 0.881 0.826 0.376 0.326 0.277	1.000 0.801 0.380 0.319 0.237	1.000 0.436 0.329 0.327	1.000 0.762 0.730	1.000	1 000	
ch_girth ch_width	0.301	0.277	0.237	0.327	0.730	0.583 0.577	1.000 0.539	1.000

We extract two common factors with the iterated principal-factor method. See the description of factormat in [MV] factor for details on running a factor analysis on a Stata matrix rather than on a dataset.

	ctormat R, n(3 =305)	305) fac(2) ipf			
Fact	or analysis/co	orrelation		Number of obs	s = 305
]	Method: iterat	ted principal fa	actors	Retained fact	cors = 2
]	Rotation: (un	rotated)		Number of par	rams = 15
-	Factor	Eigenvalue	Difference	Proportion	Cumulative
-	Factor1	4.44901	2.93878	0.7466	0.7466
	Factor2	1.51023	1.40850	0.2534	1.0000
	Factor3	0.10173	0.04705	0.0171	1.0171
	Factor4	0.05468	0.03944	0.0092	1.0263
	Factor5	0.01524	0.05228	0.0026	1.0288
	Factor6	-0.03703	0.02321	-0.0062	1.0226
	Factor7	-0.06025	0.01415	-0.0101	1.0125
	Factor8	-0.07440	•	-0.0125	1.0000

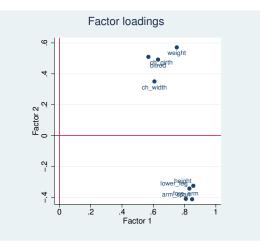
LR test: independent vs. saturated: chi2(28) = 2092.68 Prob>chi2 = 0.0000

Variable	Factor1	Factor2	Uniqueness
height	0.8560	-0.3244	0.1620
arm_span	0.8482	-0.4115	0.1112
fore_arm	0.8082	-0.4090	0.1795
lower_leg	0.8309	-0.3424	0.1923
weight	0.7503	0.5712	0.1108
bitrod	0.6307	0.4922	0.3600
ch_girth	0.5687	0.5096	0.4169
ch_width	0.6074	0.3507	0.5081

Factor loadings (pattern matrix) and unique variances

The default factor solution is rather poor from the perspective of a "simple structure", namely, that variables should have high loadings on few (one) factors and factors should ideally have only low and high values. A plot of the loadings is illuminating.

. loadingplot, xlab(0(.2)1) ylab(-.4(.2).6) aspect(1) yline(0) xline(0)



There are two groups of variables. We would like to see one group of variables close to one axis and the other group of variables close to the other axis. Turning the plot by about 45 degrees counterclockwise should make this possible and offer a much "simpler" structure. This is what the rotate command accomplishes.

. ro	tate				
	or analysis/co			Number of obs	= 305
	Method: iterat	ted principal fa	actors	Retained facto	rs = 2
	Rotation: orth	nogonal varimax	(Kaiser off)	Number of para	ms = 15
	Factor	Variance	Difference	Proportion	Cumulative
	Factor1 Factor2	3.39957 2.55968	0.83989	0.5705 0.4295	0.5705 1.0000

LR test: independent vs. saturated: chi2(28) = 2092.68 Prob>chi2 = 0.0000

Variable	Factor1	Factor2	Uniqueness
height	0.8802	0.2514	0.1620
arm_span	0.9260	0.1770	0.1112
fore_arm	0.8924	0.1550	0.1795
lower_leg	0.8708	0.2220	0.1923
weight	0.2603	0.9064	0.1108
bitrod	0.2116	0.7715	0.3600
ch_girth	0.1515	0.7484	0.4169
ch_width	0.2774	0.6442	0.5081

Rotated factor loadings (pattern matrix) and unique variances

Factor rotation matrix

	Factor1	Factor2
Factor1	0.8018	0.5976
Factor2	-0.5976	0.8018

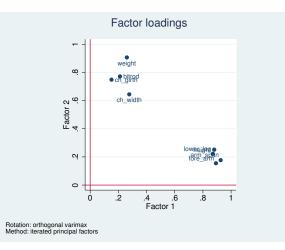
See [MV] **factor** for the interpretation of the first panel. Here we will focus on the second and third panel. The rotated factor loadings satisfy

 $Factor1_{rotated} = 0.8018 \times Factor1_{unrotated} - 0.5976 \times Factor2_{unrotated}$ 

 $\texttt{Factor2}_{rotated} = 0.5976 \times \texttt{Factor1}_{unrotated} + 0.8018 \times \texttt{Factor2}_{unrotated}$ 

The uniqueness—the variance of the specific factors—is not affected, because we are changing only the coordinates in common factor space. The purpose of rotation is to make factor loadings easier to interpret. The first factor loads high on the first four variables and low on the last four variables; for the second factor, the roles are reversed. This is really a simple structure according to Thurstone's criteria. This is clear in the plot of the factor loadings.

. loadingplot, xlab(0(.2)1) ylab(0(.2)1) aspect(1) yline(0) xline(0)



rotate provides several different rotations. You may make your intention clearer by typing the command as

<sup>.</sup> rotate, orthogonal varimax
 (output omitted)

rotate defaults to orthogonal (angle and length preserving) rotations of the axes; thus, orthogonal may be omitted. The default rotation method is varimax, probably the most popular method. We warn that the varimax rotation is not appropriate if you expect a general factor contributing to all variables (see also Gorsuch 1983, chap. 9). In such a case you could, for instance, consider a quartimax rotation.

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## Example 2: Orthogonal varimax rotation with normalization

rotate has performed what is known as "raw varimax", rotating the axes to maximize the sum of the variance of the squared loadings in the columns—the variance in a column is large if it comprises small and large (in the absolute sense) values. In rotating the axes, rows with large initial loadings—that is, with high communalities—have more influence than rows with only small values. Kaiser suggested that in the computation of the optimal rotation, all rows should have the same weight. This is usually known as the Kaiser normalization and sometimes known as the Horst normalization (Horst 1965). The option normalize applies this normalization method for rotation.

. 100	cate, normaliz	e				
Facto	or analysis/co	rrelation		Number of obs	s = 3	305
Ν	Method: iterat	ed principal fa	actors	Retained fact	ors =	2
F	Rotation: orth	logonal varimax	(Kaiser on)	Number of par	ams =	15
-	T					
-	Factor	Variance	Difference	Proportion	Cumulative	
-	Factor Factor1	Variance 3.31500	Difference 0.67075	Proportion 0.5563	Cumulative	

LR test:	independent	vs. satu	irated:	chi2(28	3) =	2092.68 Pi	rob>chi2 =	0.0000
Rotated fact	or loadings	(pattern	matrix)	and uni	ique	variances		

Variable	Factor1	Factor2	Uniqueness
height	0.8724	0.2775	0.1620
arm_span	0.9203	0.2045	0.1112
fore_arm	0.8874	0.1815	0.1795
lower_leg	0.8638	0.2478	0.1923
weight	0.2332	0.9137	0.1108
bitrod	0.1885	0.7775	0.3600
ch_girth	0.1292	0.7526	0.4169
ch_width	0.2581	0.6522	0.5081

Factor rotation matrix

	Factor1	Factor2
Factor1	0.7837	0.6212
Factor2	-0.6212	0.7837

Here the raw and normalized varimax rotated loadings are not much different.

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In the first example, loadingplot after rotate showed the rotated loadings, not the unrotated loadings. How can this be? Remember that Stata estimation commands store their results in e(), which we can list using ereturn list.

```
. ereturn list
scalars:
                  e(f) = 2
                  e(N) = 305
               e(df_m) = 15
               e(df_r) = 13
             e(chi2_i) = 2092.68137837692
               e(df_i) = 28
                e(p_i) = 0
              e(evsum) = 5.959224129627412
                e(r_f) = 2
macros:
    e(r_normalization) : "kaiser"
            e(r_class) : "orthogonal"
        e(r_criterion) : "varimax"
           e(r_ctitle) : "varimax"
            e(cmdline) : "factormat R, n(305) fac(2) ipf"
                e(cmd) : "factor"
       e(marginsnotok) : "_ALL"
         e(properties) : "nob noV eigen"
              e(title) : "Factor analysis"
            e(predict) : "factor_p"
          e(estat_cmd) : "factor_estat"
         e(rotate_cmd) : "factor_rotate"
            e(factors) : "factors(2)"
             e(mtitle) : "iterated principal factors"
             e(method) : "ipf"
         e(matrixname) : "R"
matrices:
               e(r Ev) : 1 x 2
              e(r Phi) : 2 \times 2
                e(r_T) : 2 x 2
                e(r_L) : 8 x 2
                  e(C) : 8 x 8
                e(Phi) : 2 x 2
                  e(L) : 8 x 2
                e(Psi) : 1 x 8
                 e(Ev) : 1 x 8
functions:
             e(sample)
```

When you replay an estimation command, it simply knows where to look, so that it can redisplay the output. rotate does something that few other postestimation commands are allowed to do: it adds information to the estimation results computed by factor or pca. But to avoid confusion, it writes in e() fields with the prefix  $r_{-}$ . For instance, the matrix  $e(r_{-}L)$  contains the rotated loadings.

If you replay factor after rotate, factor will display the rotated results. And this is what all factor and pca postestimation commands do. For instance, if you predict after rotate, predict will use the rotated results. Of course, it is still possible to operate on the unrotated results. factor, norotated replays the unrotated results. predict with the norotated option computes the factor scores for the unrotated results.

rotate stores information only about the most recent rotation, overwriting any information from the previous rotation. If you need the previous results again, run rotate with the respective options again; you do not need to run factor again. It is also possible to use estimates store to store estimation results for different rotations, which you may later restore and replay at will. See [R] estimates store for details. If you no longer need the rotation results, you may type

. rotate, clear

to clean up the rotation result and return the factor results back to their pristine state (as if rotate had never been called).

### Example 3: Orthogonal quartimax and orthogonal oblimin rotations

rotate provides many more orthogonal rotations. Previously we stated that the varimax rotation can be thought of as the rotation that maximizes the varimax criterion, namely, the variance of the squared loadings summed over the columns. A column of loadings with a high variance tends to contain a series of large values and a series of low values, achieving the simplicity aim of factor analytic interpretation. The other types of rotation simply maximize other concepts of simplicity. For instance, the quartimax rotation aims at rowwise simplicity—preferably, the loadings within variables fall into a grouping of a few large ones and a few small ones, using again the variance in squared loadings as the criterion to be maximized.

. 10	rotate, quartimax normalize						
Fact	or analysis/com	relation	Number of obs	s = 3	305		
	Method: iterate	ed principal fa	Retained fact	cors =	2		
	Rotation: orthogonal quartimax (Kaiser on) Number				rams =	15	
	Factor	Variance	Difference	Proportion	Cumulative		
	Factor Factor1	Variance 3.32371	Difference 0.68818	Proportion 0.5577	Cumulative		

LR test: independent vs. saturated: chi2(28) = 2092.68 Prob>chi2 = 0.0000 Rotated factor loadings (pattern matrix) and unique variances

Variable	Factor1	Factor2	Uniqueness
height	0.8732	0.2749	0.1620
arm_span	0.9210	0.2017	0.1112
fore_arm	0.8880	0.1788	0.1795
lower_leg	0.8646	0.2452	0.1923
weight	0.2360	0.9130	0.1108
bitrod	0.1909	0.7769	0.3600
ch_girth	0.1315	0.7522	0.4169
ch_width	0.2601	0.6514	0.5081

Factor rotation matrix

	Factor1	Factor2
Factor1	0.7855	0.6188
Factor2	-0.6188	0.7855

Here the quartimax and the varimax rotated results are rather similar. This need not be the case varimax focuses on simplicity within columns (factors) and quartimax within rows (variables). It is possible to compromise, rotating to strive for a weighted sum of row simplicity and column simplicity. This is known as the orthogonal oblimin criterion; in the orthogonal case, oblimin() is equivalent to the Crawford–Ferguson (option cf()) family and to the orthomax family. These are parameterized families of criteria with, for instance, the following special cases:

oblimin(0)	quartimax rotation
oblimin(0.5)	biquartimax rotation
oblimin(1)	varimax rotation

. rotate, oblimin(0.5) normalize		
Factor analysis/correlation	Number of obs =	305
Method: iterated principal factors	Retained factors =	2
Rotation: orthogonal oblimin (Kaiser on)	Number of params =	15

Factor	Variance	Difference	Proportion	Cumulative
Factor1	3.31854	0.67783	0.5569	0.5569
Factor2	2.64071		0.4431	1.0000

LR test: independent vs. saturated: chi2(28) = 2092.68 Prob>chi2 = 0.0000 Rotated factor loadings (pattern matrix) and unique variances

Variable	Factor1	Factor2	Uniqueness
height	0.8727	0.2764	0.1620
arm_span	0.9206	0.2033	0.1112
fore_arm	0.8877	0.1804	0.1795
lower_leg	0.8642	0.2468	0.1923
weight	0.2343	0.9134	0.1108
bitrod	0.1895	0.7772	0.3600
ch_girth	0.1301	0.7525	0.4169
ch_width	0.2589	0.6518	0.5081

Factor rotation matrix

	Factor1	Factor2
Factor1	0.7844	0.6202
Factor2	-0.6202	0.7844

Because the varimax and orthomax rotation are relatively close, the factor loadings resulting from an optimal rotation of a compromise criterion are close as well.

The orthogonal quartimax rotation may be obtained in different ways, namely, directly or by the appropriate member of the oblimin() or cf() families:

```
. rotate, quartimax
(output omitted)
. rotate, oblimin(0)
```

- (output omitted)
  . rotate, cf(0)
- (output omitted)

### Technical note

The orthogonal varimax rotation also belongs to the oblimin and Crawford-Ferguson families.

- . rotate, varimax (output omitted)
- . rotate, oblimin(1)
   (output omitted)
- . rotate, cf(0.125)
   (output omitted)

4

(The 0.125 = 1/8 above is 1 divided by the number of variables.) All three produce the orthogonal varimax rotation. (There is actually a fourth way, namely rotate, vgpf.) There is, however, a subtle difference in algorithms used. The varimax rotation as specified by the varimax option (which is also the default) is computed by the classic algorithm of cycling through rotations of two factors at a time. The other ways use the general "gradient projection" algorithm proposed by Jennrich; see [MV] rotatemat for more information.

## **Oblique rotations**

In addition to orthogonal rotations, oblique rotations are also available.

#### Example 4: Oblique oblimin rotation

The rotation methods that we have discussed so far are all orthogonal: the angles between the axes are unchanged, so the rotated factors are uncorrelated.

Returning to our original factor analysis,

. factormat R, n(305) fac(2) ipf (output omitted)

we examine the correlation matrix of the common factors,

. estat common Correlation matrix of the common factors

Factors	Factor1	Factor2
Factor1 Factor2	1 0	1

and see that they are uncorrelated.

The indeterminacy in the factor analytic model, however, allows us to consider other transformations of the common factors, namely, oblique rotations. These are rotations of the axes that preserve the norms of the rows of the loadings but not the angles between the axes or the angles between the rows. There are advantages and disadvantages of oblique rotations. See, for instance, Gorsuch (1983, chap. 9). In many substantive theories, there seems little reason to impose the restriction that the common factors be uncorrelated. The additional freedom in choosing the axes generally leads to more easily interpretable factors, sometimes to a great extent. However, although most researchers are willing to accept mildly correlated factors, they would prefer to use fewer of such factors.

rotate provides an extensive menu of oblique rotations; with a few exceptions, criteria suitable for orthogonal rotations are also suitable for oblique rotation. Again oblique rotation can be conceived of as maximizing some "simplicity" criterion. We illustrate with the oblimin oblique rotation. . rotate, oblimin oblique normalize

Fac	tor analysis/co	orrelation	Number of obs	=	305	
	Method: iterat	Retained factors		Retained factors =	= 2	2
	Rotation: obl	Number of params	=	15		
	Factor	Variance	Proportion	Rotated factors are	cor	related
	 Factor1	3.95010	0.6629			
	Factor2	3.35832	0.5635			

LR test: independent vs. saturated: chi2(28) = 2092.68 Prob>chi2 = 0.0000 Rotated factor loadings (pattern matrix) and unique variances

Variable	Factor1	Factor2	Uniqueness
height	0.8831	0.0648	0.1620
arm_span fore_arm	0.9560	-0.0288 -0.0450	0.1112 0.1795
lower_leg	0.8819	0.0344	0.1923
weight	0.0047	0.9408	0.1108
bitrod	-0.0069	0.8032	0.3600
ch_girth	-0.0653	0.7923	0.4169
ch_width	0.1042	0.6462	0.5081

Factor rotation matrix

	Factor1	Factor2
Factor1	0.9112	0.7930
Factor2	-0.4120	0.6092

The oblique rotation yields a much "simpler" structure in the Thurstone (1935) sense than that of the orthogonal rotations. This time, the common factors are moderately correlated.

. estat common

Correlation matrix of the oblimin(0) rotated common factors

Factors	Factor1	Factor2
Factor1 Factor2	1 .4716	1

4

## Technical note

The numerical maximization of a simplicity criterion with respect to the class of orthogonal or oblique rotations proceeds in a stepwise method, making small improvements from an initial guess, until no more small improvements are possible. Such a procedure is not guaranteed to converge to the global optimum but to a local optimum instead. In practice, we experience few such problems. To some extent, this is because we have a reasonable starting value using the unrotated factors or loadings. As a safeguard, Stata starts the improvement from multiple initial positions chosen at random from the classes of orthonormal and normal rotation matrices. If the maximization procedure converges to the same criterion value at each trial, we may be reasonably certain that we have found the global optimum. Let us illustrate.

. set seed 123				
. rotate, oblimin d	oblique normali	ize protect(10)		
Trial 1 : min cri	iterion .0181	1657		
Trial 2 : min cr	iterion 46234	1.38		
Trial 3 : min cr	iterion .0181	L657		
Trial 4 : min cr	iterion .0181	L657		
Trial 5 : min cr	iterion .0181	L657		
Trial 6 : min cr	iterion .0181	L657		
Trial 7 : min cr	iterion .0181	L657		
Trial 8 : min cr	iterion 1769.	. 989		
Trial 9 : min cr	iterion 25020	05.6		
Trial 10 : min cr	iterion .0181	L657		
Factor analysis/con	rrelation		Number of obs	= 305
Method: iterate	ed principal fa	actors	Retained factors	= 2
Rotation: oblic	que oblimin (Ka	Number of params	= 15	
Factor	Variance	Proportion	Rotated factors are	correlated
Factor1	3.95010	0.6629		
Factor2	3.35832	0.5635		

LR test: i	ndependent vs	. saturated:	chi2(28) = 2092.68 Prob>chi2 = 0.0000
Rotated factor	loadings (pa	ttern matrix)	) and unique variances

Variable	Factor1	Factor2	Uniqueness
height	0.8831	0.0648	0.1620
arm_span	0.9560	-0.0288	0.1112
fore_arm	0.9262	-0.0450	0.1795
lower_leg	0.8819	0.0344	0.1923
weight	0.0047	0.9408	0.1108
bitrod	-0.0069	0.8032	0.3600
ch_girth	-0.0653	0.7923	0.4169
ch_width	0.1042	0.6462	0.5081

Factor rotation matrix

	Factor1	Factor2
Factor1	0.9112	0.7930
Factor2	-0.4120	0.6092

Here three of the random trials converged to distinct rotations from the rest. Specifying options log and trace would demonstrate that in these cases, the initial configurations were so far off that no improvements could be found. In a real application, we would probably rerun rotate with more trials, say, protect(50), for more reassurance.

### Technical note

There is another but almost trivial source of nonuniqueness. All simplicity criteria supported by rotate and rotatemat are invariant with respect to permutations of the rows and of the columns. Also, the signs of rotated loadings are undefined. rotatemat, the computational engine of rotate, makes sure that all columns have a positive orientation, that is, have a positive sum. rotate, after factor and pca, also sorts the columns into decreasing order of explained variance.

## Other types of rotation

rotate supports a few rotation methods that do not fit into the scheme of "simplicity maximization". The first is known as the target rotation, which seeks to rotate the factor loading matrix to approximate as much as possible a target matrix of the same size as the factor loading matrix.

### Example 5: Rotation toward a target matrix

We continue with our same example. If we had expected a factor loading structure in which the first group of four variables would load especially high on the first factor and the second group of four variables on the second factor, we could have set up the following target matrix.

```
. matrix W = ( 1,0 \ 1,0 \ 1,0 \ 1,0 \ 0,1 \ 0,1 \ 0,1 \ 0,1 )
. matrix list W
W[8,2]
    c1
        c2
         0
     1
r1
r^2
     1
         Ο
r3
     1
         0
         0
r4
     1
r5
     0
         1
r6
     0
         1
r7
     0
         1
r8
     0
         1
```

It is also possible to request an orthogonal or oblique rotation toward the target  $\mathbf{W}$ .

. rota	rotate, target(W) normalize								
Me		orrelation ced principal fa nogonal target	Number of obs Retained fact Number of par	ors = 2					
	Factor	Variance	Proportion	Cumulative					
	Factor1         3.30616         0.           Factor2         2.65309         0.		0.65307	0.5548 0.4452	0.5548 1.0000				

```
LR test: independent vs. saturated: chi2(28) = 2092.68 Prob>chi2 = 0.0000
Rotated factor loadings (pattern matrix) and unique variances
```

Variable	Factor1	Factor2	Uniqueness
height	0.8715	0.2802	0.1620
arm_span	0.9197	0.2073	0.1112
fore_arm	0.8869	0.1843	0.1795
lower_leg	0.8631	0.2505	0.1923
weight	0.2304	0.9144	0.1108
bitrod	0.1861	0.7780	0.3600
ch_girth	0.1268	0.7530	0.4169
ch width	0.2561	0.6530	0.5081

Factor rotation matrix

	Factor1	Factor2
Factor1	0.7817	0.6236
Factor2	-0.6236	0.7817

With this target matrix, the result is not far different from the varimax and other orthogonal rotations.

### Example 6: Oblique promax rotation

For our last example, we return to the early days of factor analysis, the time before fast computing. Analytical methods for orthogonal rotation, such as varimax, were developed relatively early. Analogous methods for oblique rotations proved more complicated. Hendrickson and White (1964) proposed a computationally simple method to obtain an oblique rotation that comprises an oblique Procrustes rotation of the factor loadings toward a signed power of the varimax rotation of the factor loadings. The promax method has one parameter, the power to which the varimax loadings are raised. Larger promax powers simplify the factor loadings (that is, generate more zeros and ones) at the cost of more correlation between the common factors. Generally, we recommend that you keep the power in the range (1,4] and not restricted to integers. Specifying promax is equivalent to promax(3).

. rotate, promax	normalize			
Factor analysis/c	orrelation	Number of obs	= 305	
Method: itera	ted principal f	actors	Retained factors	= 2
Rotation: obl	ique promax (Ka	iser on)	Number of params	= 15
Factor	Variance	Rotated factors are	correlated	
	3.92727	0,6590		

LR test: independent vs	. saturated: c	hi2(28) = 2092.68	Prob>chi2 = 0.0000
Rotated factor loadings (pa	ttern matrix) a	and unique variance	es

0.5559

Variable	Factor1	Factor2	Uniqueness
height arm_span	0.8797	0.0744 -0.0176	0.1620
fore_arm	0.9205	-0.0340	0.1795
lower_leg	0.8780	0.0443	0.1923
weight	0.0214	0.9332	0.1108
bitrod	0.0074	0.7966	0.3600
ch_girth	-0.0509	0.7851	0.4169
ch_width	0.1152	0.6422	0.5081

3.31295

Factor rotation matrix

Factor2

	Factor1	Factor2
Factor1	0.9069	0.7832
Factor2	-0.4214	0.6218

In this simple two-factor example, the promax solution is similar to the oblique oblimin solution.

4

4

## Stored results

rotate adds stored results named e(r\_name) to the stored results that were already defined by factor or pca.

rotate adds to the following results:

Scalars e(r_f) e(r_fmin)	number of factors/components in rotated solution rotation criterion value
Macros	
e(r_class)	orthogonal or oblique
e(r_criterion)	rotation criterion
e(r_ctitle)	title for rotation
e(r_normalization)	kaiser or none
Matrices	
e(r_L)	rotated loadings
e(r_T)	rotation
e(r_Phi)	correlations between common factors (after factor only)
e(r_Ev)	explained variance by common factors (factor) or rotated components (pca)

The factors/components in the rotated solution are in decreasing order of e(r\_Ev).

## Technical note

The rest of this section contains information of interest to programmers who want to provide rotate support to other estimation commands. Similar to other postestimation commands, such as estat and predict, rotate invokes a handler command. The name of this command is extracted from the field e(rotate\_cmd). The estimation command *cmd* should set this field appropriately. For instance, pca sets the macro e(rotate\_cmd) to pca\_rotate. The command pca\_rotate implements rotation after pca and pcamat, using rotatemat as the computational engine. pca\_rotate does not display output itself; it relies on pca to do so.

For consistent behavior for end users and programmers alike, we recommend that the estimation command *cmd*, the driver commands, and other postestimation commands adhere to the following guidelines:

#### Driver command

- The rotate driver command for *cmd* should be named *cmd*\_rotate.
- *cmd*\_rotate should be an e-class command, that is, returning in e().
- Make sure that *cmd\_*rotate is invoked after the correct estimation command (for example, if "'e(cmd)'" != "pca" ...).
- Allow at least the option <u>detail</u> and any option available to rotatemat.
- Extract from e() the matrix you want to rotate; invoke rotatemat on the matrix; and run this command quietly (that is, suppress all output) unless the option detail was specified.
- Extract the r() objects returned by rotatemat; see *Methods and formulas* of [MV] rotatemat for details.
- Compute derived results needed for your estimator.
- Store in e() fields (macros, scalars, matrices) named r\_name, adding to the existing e() fields.

Store the macros returned by rotatemat under the same named prefixed with  $r_{-}$ . In particular, the macro  $e(r_criterion)$  should be set to the name of the rotation criterion returned by rotatemat as r(criterion). Other commands can check this field to find out whether rotation results are available.

We suggest that only the most recent rotation results be stored, overwriting any existing  $e(r_*)$  results. The programmer command \_rotate\_clear clears any existing  $r_*$  fields from e().

• Display the rotation results by replaying *cmd*.

#### Estimation command cmd

- In *cmd*, define e(rotate\_cmd) to *cmd*\_rotate.
- *cmd* should be able to display the rotated results and should default to do so if rotated results are available. Include an option noROTated to display the unrotated results.
- You may use the programmer command <u>\_rotate\_text</u> to obtain a standard descriptive text for the rotation method.

#### Other postestimation commands

- Other postestimation commands after *cmd* should operate on the rotated results whenever they are appropriate and available, unless the option noROTated specifies otherwise.
- Mention that you operate on the unrotated results only if rotated results are available, but the user or you as the programmer decided not to use them.

## Methods and formulas

See Methods and formulas of [MV] rotatemat.

Henry Felix Kaiser (1927–1992) was born in Morristown, New Jersey, and educated in California, where he earned degrees at Berkeley in between periods of naval service during and after World War II. A specialist in psychological and educational statistics and measurement, Kaiser worked at the Universities of Illinois and Wisconsin before returning to Berkeley in 1968. He made several contributions to factor analysis, including varimax rotation (the subject of his PhD) and a measure for assessing sampling adequacy. Kaiser is remembered as an eccentric who spray-painted his shoes in unusual colors and listed ES (Eagle Scout) as his highest degree.

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Also see References in [MV] rotatemat.

## Also see

- [MV] factor Factor analysis
- [MV] factor postestimation Postestimation tools for factor and factormat
- [MV] **pca** Principal component analysis
- [MV] pca postestimation Postestimation tools for pca and pcamat
- [MV] procrustes Procrustes transformation
- [MV] rotatemat Orthogonal and oblique rotations of a Stata matrix